

Imperial Centre for Inference & Cosmology **Imperial College** 

- Warning: frequentist hypothesis testing (e.g., likelihood ratio test) cannot be interpreted as a statement about the probability of the hypothesis!
- Example: to test the null hypothesis H<sub>0</sub>: θ = 0, draw *n* normally distributed points (with known variance σ<sup>2</sup>). The χ<sup>2</sup> is distributed as a chi-square distribution with (*n*-1) degrees of freedom (dof). Pick a significance level α (or p-value, e.g. α = 0.05). If P(χ<sup>2</sup> > χ<sup>2</sup><sub>obs</sub>) < α reject the null hypothesis.</li>
- This is a statement about the likelihood of observing data as extreme or more extreme than have been measured assuming the null hypothesis is correct.
- It is not a statement about the probability of the null hypothesis itself and cannot be interpreted as such! (or you'll make gross mistakes)
- The use of p-values implies that a hypothesis that may be true can be rejected because it has not predicted observable results that have not actually occurred. (Jeffreys, 1961)

### The significance of significance

- Important: A 2-sigma result does not wrongly reject the null hypothesis 5% of the time: at least 29% of 2-sigma results are wrong!
  - Take an equal mixture of H<sub>0</sub>, H<sub>1</sub>
  - Simulate data, perform hypothesis testing for H<sub>0</sub>
  - Select results rejecting  $H_0$  at (or within a small range from) 1-a CL (this is the prescription by Fisher)
  - What fraction of those results did actually come from H<sub>0</sub> ("true nulls", should not have been rejected)?

p-value	sigma	fraction of true nulls	lower bound
$0.05 \\ 0.01$	$1.96 \\ 2.58$	$0.51 \\ 0.20$	$0.29 \\ 0.11$
0.001	3.29	0.024	0.018

Recommended reading: Sellke, Bayarri & Berger, *The American Statistician*, 55, 1 (2001) Bayesian model comparison

#### Bayesian inference chain

- Select a model (parameters + priors)
- Compute observable quantities as a function of parameters
- Compare with available data
  - derive parameters constraints: PARAMETER INFERENCE
  - compute relative model probability: MODEL COMPARISON
- · Go back and start again

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#### The 3 levels of inference

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LEVEL 1 I have selected a model M and prior P(θ|M)

#### LEVEL 2

Actually, there are several possible models: M<sub>0</sub>, M<sub>1</sub>,...

LEVEL 3 None of the models is clearly the best



 $P(\theta|d, M) = \frac{P(d|\theta, M)P(\theta|M)}{P(d|M)}$ 

#### **Parameter inference**

(assumes M is the true model)



#### **Model comparison**

What is the relative plausibility of M<sub>0</sub>, M<sub>1</sub>,... in light of the data?



 $P(\theta|d) = \sum_{i} P(M_i|d) P(\theta|d, M_i)$ 

#### Model averaging

What is the inference on the parameters accounting for model uncertainty?

$$P(\theta|d, M) = \frac{P(d|\theta, M)P(\theta|M)}{P(d|M)}$$

Bayesian evidence or model likelihood

The evidence is the integral of the likelihood over the prior:

$$P(d|M) = \int_{\Omega} d\theta P(d|\theta, M) P(\theta|M)$$

Bayes' Theorem delivers the model's posterior:

$$P(M|d) = \frac{P(d|M)P(M)}{P(d)}$$

When we are comparing two models:

The Bayes factor:

$$\frac{P(M_0|d)}{P(M_1|d)} = \frac{P(d|M_0)}{P(d|M_1)} \frac{P(M_0)}{P(M_1)} \qquad B_{01} \equiv \frac{P(d|M_0)}{P(d|M_1)}$$

**Posterior odds = Bayes factor × prior odds** 

## Scale for the strength of evidence

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 A (slightly modified) Jeffreys' scale to assess the strength of evidence (Notice: this is empirically calibrated!)

InB	relative odds	favoured model's probability	Interpretation
< 1.0	< 3:1	< 0.750	not worth mentioning
< 2.5	< 12:1	0.923	weak
< 5.0	< 150:1	0.993	moderate
> 5.0	> 150:1	> 0.993	strong



- Bayes factor balances quality of fit vs extra model complexity.
- It rewards highly predictive models, penalizing "wasted" parameter space



#### The evidence as predictive probability

• The evidence can be understood as a function of d to give the predictive probability under the model M:



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#### Simple example: nested models

 This happens often in practice: we have a more complex model, M<sub>1</sub> with prior P(θ|M<sub>1</sub>), which reduces to a simpler model (M<sub>0</sub>) for a certain value of the parameter,

e.g.  $\theta = \theta^* = 0$  (nested models)

 Is the extra complexity of M<sub>1</sub> warranted by the data?



#### Simple example: nested models

Define: 
$$\lambda \equiv \frac{\hat{\theta} - \theta^{\star}}{\delta \theta}$$
  
For "informative" data:  
 $\ln B_{01} \approx \ln \frac{\Delta \theta}{\delta \theta} - \frac{\lambda^2}{2}$   
wasted parameter  
space  
(favours simpler model)  
 $\overset{(\text{favours more complex model})}{\text{wasted parameter space}}$ 

#### The rough guide to model comparison



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## Information criteria

- Several information criteria exist for approximate model comparison k = number of fitted parameters N = number of data points, -2 ln(L<sub>max</sub>) = best-fit chi-squared
- Akaike Information Criterium (AIC):
- **Bayesian Information Criterium (BIC):** •
- **Deviance Information Criterium (DIC):** ٠

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$$AIC \equiv -2\ln \mathcal{L}_{max} + 2k$$

$$BIC \equiv -2\ln \mathcal{L}_{max} + k\ln N$$

$$\mathrm{DIC} \equiv -2\widehat{D_{\mathrm{KL}}} + 2\mathcal{C}_{b}.$$



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#### Notes on information criteria

- The best model is the one which minimizes the AIC/BIC/DIC
- Warning: AIC and BIC penalize models differently as a function of the number of data points N.
   For N>7 BIC has a more strong penalty for models with a larger number of free parameters k.
- BIC is an approximation to the full Bayesian evidence with a default Gaussian prior equivalent to 1/N-th of the data in the large N limit.
- DIC takes into account whether parameters are measured or not (via the Bayesian complexity, see later).
- When possible, computation of the Bayesian evidence is preferable (with explicit prior specification).





evidence: 
$$P(d|M) = \int_{\Omega} d\theta P(d|\theta, M) P(\theta|M)$$
  
Bayes factor:  $B_{01} \equiv \frac{P(d|M_0)}{P(d|M_1)}$ 

- Usually computational demanding: multi-dimensional integral!
- Several techniques available:
  - Brute force: thermodynamic integration
  - Laplace approximation: approximate the likelihood to second order around maximum gives Gaussian integrals (for normal prior). Can be inaccurate.
  - Savage-Dickey density ratio: good for nested models, gives the Bayes factor
  - Nested sampling: clever & efficient, can be used generally



- This methods works for nested models and gives the Bayes factor analytically.
- **Assumptions:** nested models (M<sub>1</sub> with parameters  $\theta$ ,  $\Psi$  reduces to M<sub>0</sub> for e.g.  $\Psi = 0$ ) and separable priors (i.e. the prior P( $\theta$ ,  $\Psi$ |M<sub>1</sub>) is uncorrelated with P( $\theta$ |M<sub>0</sub>))

• Result:



• What if we do not know how to set the prior? For nested models, we can still choose a prior that will maximise the support for the more complex model:



• The absolute upper bound: put all prior mass for the alternative onto the observed maximum likelihood value. Then

$$B < \exp(-\chi^2/2)$$

• More reasonable class of priors: symmetric and unimodal around  $\Psi$ =0, then ( $\alpha$  = significance level)

$$B < \frac{-1}{\exp(1)\alpha \ln \alpha}$$

#### If the upper bound is small, no other choice of prior will make the extra parameter significant.

Sellke, Bayarri & Berger, *The American Statistician*, 55, 1 (2001)

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α	sigma	Absolute bound on InB (B)	"Reasonable" bound on InB (B)
0.05	2	2.0 (7:1) <mark>weak</mark>	0.9 (3:1) <mark>undecided</mark>
0.003	3	4.5 (90:1) moderate	3.0 (21:1) <mark>moderate</mark>
0.0003	3.6	6.48 (650:1) <mark>strong</mark>	5.0 (150:1) <mark>strong</mark>



## Rule of thumb: interpret a n-sigma result as a (n-1)-sigma result



Figure 4. Comparison of  $\underline{B}(x, G_{us})$  and P Values.

Sellke, Bayarri & Berger, The American Statistician, 55, 1 (2001)

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#### Nested sampling

- Perhaps the method to compute the evidence
- At the same time, it delivers samples from the posterior: it is a highly efficient sampler! (much better than MCMC in tricky situations)
- Invented by John Skilling in 2005: the gist is to convert a *n*-dimensional integral in a 1D integral that can be done easily.

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Liddle et al (2006)



#### Nested sampling





(animation courtesy of David Parkinson)

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An algorithm originally aimed primarily at the Bayesian evidence computation (Skilling, 2006):

$$X(\lambda) = \int_{\mathcal{L}(\theta) > \lambda} P(\theta) d\theta$$
$$P(d) = \int d\theta L(\theta) P(\theta) = \int_0^1 L(X) dX$$

## The MultiNest algorithm

• Feroz & Hobson (2007)





0.4



#### The egg-box example



• MultiNest reconstruction of the egg-box posterior:



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Ellipsoidal decomposition



## Unimodal distribution Multimodal distribution



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## Multinest: Efficiency

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Gaussian mixture model:

True evidence: log(E) = -5.27 **Multinest:** Reconstruction:  $log(E) = -5.33 \pm 0.11$ Likelihood evaluations ~  $10^4$  **Thermodynamic integration:** Reconstruction:  $log(E) = -5.24 \pm 0.12$ 

Likelihood evaluations ~  $10^6$ 



D	Ν	efficiency	likes per dimension
2	7000	70%	83
5	18000	51%	7
10	53000	34%	3
20	255000	15%	1.8
30	753000	8%	1.6

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### Application: the spatial curvature

- Is the Universe spatially flat? (Vardanyan, Trotta and Silk, 2009)
- A three-way model comparison:
   Ω<sub>k</sub> = 0 vs Ω<sub>k</sub> < 0 vs Ω<sub>k</sub> > 0
   (with either the Astronomer's prior or Curvature scale prior)
- Result: odds range from moderate evidence (InB = 4) for flatness to undecided (InB = 0.4) depending on the choice of prior
- Probability(infinite Universe) = 98% (Astronomer's prior) Probability(infinite Universe) = 45% (Curvature scale prior)
- Upper bound: odds of 49:1 at best for n ≠ 1 (Gordon and Trotta 2007)





#### A "simple" example: how many sources?

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## A "simple" example: how many sources?

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Feroz and Hobson (2007)



#### Bayesian reconstruction

7 out of 8 objects correctly identified. Mistake happens because 2 objects very close.



Cluster detection from Sunyaev-Zeldovich effect in cosmic microwave background maps



Feroz et al 2009

Background + 3 point radio sources Background + 3 point radio sources + cluster



#### Bayesian model comparison: **R = P(cluster | data)/P(no cluster | data)**

 $R = 0.35 \pm 0.05$   $R \sim 10^{33}$ 

Cluster parameters also recovered (position, temperature, profile, etc)

#### The cosmological concordance model



from Trotta (2008)

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No reionization and no tilt

 $^{-2}$ 

-10.3

#### InB < 0: favours $\Lambda CDM$

WMAP3+, HST

Strongly disfavoured

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#### Bayesian model comparison of 193 models Higgs inflation as reference model

![](_page_34_Picture_1.jpeg)

![](_page_34_Figure_2.jpeg)

![](_page_34_Figure_3.jpeg)

![](_page_34_Figure_4.jpeg)

![](_page_34_Figure_5.jpeg)

Schwarz-Terrero-Escalante Classification:

J.Martin, C.Ringeval, R.Trotta, V.Vennin ASPIC project

Displayed Evidences: 193

## Model complexity

- "Number of free parameters" is a relative concept. The relevant scale is set by the prior range
- How many parameters can the data support, regardless of whether their detection is significant?
- **Bayesian complexity** or effective number of parameters:

$$C_b = \overline{\chi^2(\theta)} - \chi^2(\widehat{\theta})$$
$$= \sum_i \frac{1}{1 + (\sigma_i / \Sigma_i)^2}$$

Kunz, RT & Parkinson, astro-ph/0602378, Phys. Rev. D 74, 023503 (2006) Following Spiegelhalter et al (2002)

## Polynomial fitting

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• Data generated from a model with n = 6:

15 15 0 0 -log(-log(model likelihood)) -log(-log(model likelihood)) mode -1 -1 ο complexity 0 complexity 0 rue -2 -2 -3 ·3 5 5 mode υ 0 0 15 5 10 0 5 10 15 0 number of parameters number of parameters

GOOD DATA Max supported complexity ~ 9

#### INSUFFICIENT DATA Max supported complexity ~ 4

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# How many parameters does the CMB need?

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![](_page_37_Figure_1.jpeg)

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![](_page_38_Picture_1.jpeg)

![](_page_38_Figure_2.jpeg)

![](_page_38_Figure_3.jpeg)

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## Key points

- Bayesian model comparison extends parameter inference to the space of models
- The Bayesian evidence (model likelihood) represents the change in the degree of belief in the model after we have seen the data
- Models are rewarded for their predictivity (automatic Occam's razor)
- Prior specification is for model comparison a key ingredient of the model building step. If the prior cannot be meaningfully set, then the physics in the model is probably not good enough.
- Bayesian model complexity can help (together with the Bayesian evidence) in assessing model performance.