# Relativistic Intrinsic Lagrangian Perturbation Theory



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# **Motivations**

• Newtonian Lagrangian perturbation theory.

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- ightarrow Formulate the equations in terms of a single dynamical field  $\eta^a.$
- $\rightarrow\,$  Perturb it and try to find the separable non propagating and propagating parts.
- $\rightarrow\,$  Inject the solution without truncation into the functionals of the metric to keep non-linear terms.

Motivations

Why a Lagrangian perturbation theory? Standard perturbation theory 3+1 foliation and intrinsic description Einstein equations for irrotational dust The Minkowski Restriction

First-order intrinsic Lagrangian perturbation theory Perturbation scheme First-order Einstein equations for irrotational dust Solutions to the first-order equations Separable non-propagating solutions The non-integrable dynamics MR and comparision to the comoving synchronous solutions

Conclusion and Outlook

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$$\frac{d}{dt}\mathbf{v} = \mathbf{g} \quad ; \quad \frac{d}{dt}\varrho + \mathbf{v} \cdot \nabla \varrho = 0 \quad , \tag{1}$$

$$\nabla \times \mathbf{g} = \mathbf{0}$$
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$$\frac{d}{dt}\mathbf{v} = \mathbf{g} \quad ; \quad \frac{d}{dt}\varrho + \mathbf{v} \cdot \nabla \varrho = 0 \quad , \tag{3}$$

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$$\ddot{\mathbf{f}} = \mathbf{g} \quad ; \quad \frac{d}{dt} \varrho + \mathbf{v} \cdot \nabla \varrho = 0 \; ,$$
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$$\ddot{\mathbf{f}} = \mathbf{g} \quad ; \varrho = \frac{\varrho_{\mathbf{i}}}{J} / J = \frac{1}{6} \epsilon_{ijk} \epsilon^{lmn} f^{i}_{|I} f^{j}_{|m} f^{k}_{|n} , \qquad (7)$$

$$\nabla \times \mathbf{g} = \mathbf{0}$$
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$$\delta_{ab}\ddot{F}^{a}_{|[i}f^{b}_{|j]} = 0 \quad ; \quad \nabla \cdot \mathbf{g} = \Lambda - 4\pi G\varrho \quad . \tag{10}$$

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$$\delta_{ab}\ddot{F}^{a}_{|[i}f^{b}_{|j]} = 0 \quad ; \quad \frac{1}{2}\epsilon_{abc}\epsilon^{ikl}\ddot{F}^{a}_{|i}f^{b}_{|k}f^{c}_{|l} = \Lambda J - 4\pi G\varrho_{i}$$
(12)

Conclusions :

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$$\delta_{ab}\ddot{F}^{a}_{|[i}f^{b}_{|j]} = 0 \quad ; \quad \frac{1}{2}\epsilon_{abc}\epsilon^{ikl}\ddot{F}^{a}_{|i}f^{b}_{|k}f^{c}_{|l} = \Lambda J - 4\pi G\varrho_{i}$$
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Conclusions :

• Newton's equations expressed in a single dynamical field f.

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Conclusions :

- Newton's equations expressed in a single dynamical field f.
- This description breaks down when two trajectories cross each other...

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#### Lagrangian perturbation theory

- Only the trajectory field is perturbed :  $\mathbf{f} = \mathbf{f}^H + \mathbf{P}$
- Large density contrasts are allowed.



Figure : Density from Eulerian numerical simulation (*left*) and Lagrangian analytical solution to order 2 (*right*). A. Melott. Size of the box :  $200h^{-1}Mpc$ .

## Extend to Relativity the Lagrangian perturbation theory !

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SPT perturbs the metric :

$$\mathsf{g}_{\mu
u} = \underbrace{\eta_{\mu
u}}_{\mathsf{Minkowski}} + \underbrace{h_{\mu
u}}_{\ll 1}$$

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Why a Lagrangian perturbation theory ? Standard perturbation theory

### 3+1 foliation and intrinsic description

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- ⇒ Spacetime can be foliated into spatial hypersurfaces of constant time :  $\Sigma_t$ .
  - The normal vector to  $\Sigma_t$  is the 4-velocity **u**.



Local coordinate basis : Lagrangian coordinates : X; { $dX^i$ } local coordinate basis.

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- $\Rightarrow$  The Newtonian deformation form is  $\mathbf{d}f^a = f^a_{|i|} \mathbf{d}X^i$ .

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Relativistic analog of  $df^a$ ?

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Relativistic analog of df^a?
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**Non–integrable** Cartan's coframe fields :  $\eta^a = \eta^a_i dX^i$ 

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- {*a* = 1, 2, 3} is a counter : a non-coordinate index.
- Thus i is a coordinate index.

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The Minkowski Restriction

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 $\ensuremath{\boldsymbol{\mathsf{S}}}\xspace$  ymmetry of the metric

$$G_{ab}\,\ddot{\eta}^a_{[i}\eta^b_{\ j]}=0$$

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Evolution equation for the extrinsic curvature

$$\begin{aligned} G_{ab} \ddot{\eta}^{a}_{[i} \eta^{b}_{j]} &= 0 \\ \frac{1}{2J} \epsilon_{abc} \epsilon^{ikl} \left( \dot{\eta}^{a}_{j} \eta^{b}_{\ k} \eta^{c}_{\ l} \right)^{\cdot} &= -\mathcal{R}^{i}_{\ j} + (4\pi G \varrho + \Lambda) \, \delta^{i}_{\ j} \end{aligned}$$

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Hamilton constraint

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Einstein's equations fully expressed in terms of  $\eta^a$ .

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Conclusion and Outlook

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The Minkowski restriction

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• 
$$X^i \longrightarrow x^m = f^m(X^i, t)$$
  
•  $ds^2 = g_{ij} dX^i dX^j = \delta_{mn} f^m_{|i|} dX^i f^n_{|j|} dX^j = \delta_{mn} dx^m dx^n.$ 

Electric part of the Lagrange-Einstein system :

$$\delta_{ab}\ddot{\eta}^{a}_{\ [i}\eta^{b}_{\ ]j} = 0 \tag{17}$$

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MR of this system of equations

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$$\delta_{ab}\ddot{F}^{a}_{|[i}f^{b}_{|j]} = 0 \tag{19}$$

$$\frac{1}{2}\epsilon_{abc}\epsilon^{ikl}\ddot{F}^{a}_{|l}f^{b}_{|k}f^{c}_{|l} = \Lambda J - 4\pi G\varrho_{\mathbf{i}}.$$
 (20)

### We recover the Lagrange-Newton system for $\hat{\mathbf{f}} = \mathbf{g}$ .

### First–order intrinsic Lagrangian perturbation theory

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#### Split the solutions into :

• a separable part that does not describe deviations to flatness

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- $\rightarrow$  The solution will be injected into the functionals of the metric without truncating.

#### Split the solutions into :

- a separable part that does not describe deviations to flatness
- a part that deviates to flatness and contains GW !

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$$\eta_{i}^{a} = a(t) \, \tilde{\eta}_{i}^{a} = a(t) \left( \delta_{i}^{a} + P_{i}^{a}(\mathbf{X}, \mathbf{t}) \right)$$

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$$\eta_j^b(t_i) = a(t) \, \delta_j^b \Rightarrow g_{ij}(t_i) = G_{ij} = \delta_{ij} + G_{ij}^{(1)}$$

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....

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$$\eta_j^b(t_i) = a(t) \, \delta_j^b \Rightarrow g_{ij}(t_i) = G_{ij} = \delta_{ij} + G_{ij}^{(1)}$$

- $\dot{P}_{ij}(t_i) = U_{ij}$   $\ddot{P}_{ij}(t_i) = W_{ij} 2H_iU_{ij}$

• Metric 
$$g_{ij} = a^2(t) \left( \delta_{ij} + G_{ij}^{(1)} + 2P_{(ij)} + P_{i}^a P_{aj} \right)$$

$$\eta_{i}^{a} = a(t) \, \tilde{\eta}_{i}^{a} = a(t) \left( \delta_{i}^{a} + P_{i}^{a}(\mathbf{X}, \mathbf{t}) \right)$$

· - >

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$$\eta_j^b(t_i) = a(t) \, \delta_j^b \Rightarrow g_{ij}(t_i) = G_{ij} = \delta_{ij} + G_{ij}^{(1)}$$

- $\dot{P}_{ij}(t_i) = U_{ij}$
- $\ddot{P}_{ij}(t_i) = W_{ij} 2H_iU_{ij}$
- Metric  $g_{ij} = a^2(t) \left( \delta_{ij} + G^{(1)}_{ij} + 2P_{(ij)} + P^a_{\ i} P_{a\,j} \right)$
- Perturbation decomposition  $P_{ij} = \frac{1}{3}P\delta_{ij} + \Pi_{ij} + \mathfrak{P}_{ij}$

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 $G_{ab}\,\ddot{\eta}^a_{[i}\eta^b_{\ j]}=0$ 

 $\mathfrak{P}_{ij}=0$ 

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Evolution equation for the extrinsic curvature

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 $\mathfrak{P}_{ij}=0$ 

$$\frac{1}{2J}\epsilon_{abc}\epsilon^{ikl}\left(\dot{\eta}^{a}_{\ j}\eta^{b}_{\ k}\eta^{c}_{\ l}\right)^{\cdot} = -\mathcal{R}^{i}_{\ j} + \left(4\pi G\varrho + \Lambda\right)\delta^{i}_{\ j}$$

 $\mathfrak{P}_{ij} = 0$  $\ddot{P} + 3H\dot{P} = -\frac{{}^{(1)}\mathcal{R}}{4}$ ;  $\ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \, {}^{(1)}\tau_{ij}$ 

$$\mathfrak{P}_{ij} = 0$$
  
 $\ddot{P} + 3H\dot{P} = -\frac{{}^{(1)}\mathcal{R}}{4}$ ;  $\ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \, {}^{(1)}\tau_{ij}$ 

Hamilton constraint

 $\mathfrak{P}_{ij}=0$ 

$$\begin{split} \ddot{P} + 3H\dot{P} &= -\frac{(1)\mathcal{R}}{4} \qquad ; \qquad \ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \, {}^{(1)}\tau_{ij} \\ \frac{1}{2J}\epsilon_{abc}\epsilon^{mjk}\dot{\eta}^{a}_{\ m}\dot{\eta}^{b}_{\ j}\eta^{c}_{\ k} &= -\frac{\mathcal{R}}{2} + (8\pi G\varrho + \Lambda) \end{split}$$

 $\mathfrak{P}_{ij}=0$ 

 $\ddot{P} + 3H\dot{P} = -\frac{{}^{(1)}\mathcal{R}}{4} ; \qquad \ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \, {}^{(1)}\tau_{ij}$   $H\dot{P} + 4\pi G \varrho_{Hi} a^{-3} P = -\frac{{}^{(1)}\mathcal{R}}{4} - a^{-3} W$ 

 $\mathfrak{P}_{ij} = 0$ 

 $\ddot{P} + 3H\dot{P} = -\frac{{}^{(1)}\mathcal{R}}{4} ; \qquad \ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \,{}^{(1)}\tau_{ij}$  $H\dot{P} + 4\pi G \varrho_{Hi} a^{-3}P = -\frac{{}^{(1)}\mathcal{R}}{4} - a^{-3}W$ 

Momentum constraints

 $\begin{aligned} \mathfrak{P}_{ij} &= 0 \\ \ddot{P} + 3H\dot{P} &= -\frac{{}^{(1)}\mathcal{R}}{4} \qquad ; \qquad \ddot{\Pi}_{ij} + 3H\dot{\Pi}_{ij} = -a^{-2} \, {}^{(1)}\tau_{ij} \\ H\dot{P} + 4\pi G \varrho_{Hi} a^{-3}P &= -\frac{{}^{(1)}\mathcal{R}}{4} - a^{-3}W \\ \left(\epsilon_{abc} \epsilon^{ikl} \dot{\eta}^{a}_{j} \eta^{b}_{k} \eta^{c}_{l}\right)_{||i} &= \left(\epsilon_{abc} \epsilon^{ikl} \dot{\eta}^{a}_{i} \eta^{b}_{k} \eta^{c}_{l}\right)_{|j} \end{aligned}$ 

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Further decomposition for  $\Pi_{\it ij}$  :

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$$P_{ij} = \frac{1}{3}P\delta_{ij} + {}^{E}\Pi_{ij} + {}^{H}\Pi_{ij}$$

We combine the Hamilton constraint

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$$H\dot{P} + 4\pi G \varrho_{Hi} a^{-3} P = -\frac{{}^{(1)}\mathcal{R}}{4} - a^{-3} W$$

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We combine the Hamilton constraint and the trace part of the evolution equation

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$${}^{E}W_{ij}^{tl} + H_{\mathbf{i}}{}^{E}U_{ij}^{tl} = \mathcal{D}_{ij}(H_{\mathbf{i}}S - \phi) \quad ; \quad {}^{H}W_{ij}^{tl} + H_{\mathbf{i}}{}^{H}U_{ij}^{tl} = \tilde{W}_{ij}^{tl} + H_{\mathbf{i}}{}^{H}\tilde{U}_{ij}^{tl}$$

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$$\mathcal{D}_{ij} = \partial_i \partial j - \frac{1}{3} \delta_{ij} \Delta_0.$$
  
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Motivations

Why a Lagrangian perturbation theory? Standard perturbation theory 3+1 foliation and intrinsic description Einstein equations for irrotational dust The Minkowski Restriction

#### First-order intrinsic Lagrangian perturbation theory

Perturbation scheme First–order Einstein equations for irrotational dust

#### Solutions to the first-order equations

Separable non-propagating solutions

The non-integrable dynamics

MR and comparision to the comoving synchronous solutions

Conclusion and Outlook

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For an Einstein-de Sitter background ( $\Lambda = 0, k = 0$ )  $\Psi(\mathbf{X}, t) = {}^{\Psi}C^{-1}(\mathbf{X}) \left(\frac{t}{t_i}\right)^{-1} + {}^{\Psi}C^{2/3}(\mathbf{X}) \left(\frac{t}{t_i}\right)^{2/3} + {}^{\Psi}C^0(\mathbf{X})$ 

$${}^{\Psi}C^{-1} = -\frac{3}{5}(St_{i} + \phi t_{i}^{2}) ; {}^{\Psi}C^{2/3} = \frac{3}{5}St_{i} - \frac{9}{10}\phi t_{i}^{2} ; {}^{\Psi}C^{0} = \frac{\phi}{4\pi G\rho_{H_{i}}}$$

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The non-integrable dynamics

We solve :

$${}^{H}\ddot{\Pi}_{ij} + 3H^{H}\dot{\Pi}_{ij} - a^{-2} {}^{H}\Pi_{ij}{}^{|k}_{|k} = a^{-2} \left({}^{H}W^{tl}_{ij} + H^{H}_{i}U^{tl}_{ij}\right) .$$
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- Peculiar solution :  ${}^{H}\Pi_{ij}^{pec}(\mathbf{X})$
- Homogeneous solution  ${}^{H}\Pi_{ii}^{hom}(\mathbf{X}, t)$  contains propagation : **GW**.

Monochromatic solution of pulsation  $\omega$  :

$$\begin{split} {}^{H}\Pi^{\omega}_{\ ij}(\mathbf{X},t) &= \left( C^{\omega}_{1} \ \mathcal{J}_{0}(3\omega t_{i}^{2/3}t^{1/3}) + C^{\omega}_{2} \ \mathcal{Y}_{0}(3\omega t_{i}^{2/3}t^{1/3}) \right) \\ & \{ C^{K+}_{\ ij} \ e^{i\mathbf{K}\cdot\mathbf{X}} + C^{K-}_{\ ij} \ e^{-i\mathbf{K}\cdot\mathbf{X}} \} \end{split}$$

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 $P(\mathbf{X}, t), {}^{E}\Pi_{ij}(\mathbf{X}, t), {}^{H}\Pi_{ij}(\mathbf{X}, t) : \mathbf{X} = \text{local coordinate on curved space}$ 

# **Conclusion and Outlook**

In analogy with the Newtonian case, we have formulated Einstein equation in the Cartan formalism :

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- $\Rightarrow\,$  The non-integrable part encodes the deviations to the flat space : the GW.

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The difference is that our coordinates are defined on locally curved space sections.

## Outlook :

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• How can we link our quantities to the gauge-invariants of standard perturbation theory ?

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- How can we link our quantities to the gauge-invariants of standard perturbation theory ?
- What does this theory gives at further orders?

#### References

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