# From Exponential Growth to Saturation: An Instability Dissected in Phase-Space

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# Plan (roughly)

- Preamble
- Instability
- Dissection
- Summary
- Plan (actually)

#### The "Double" Nucleus of M31: Observations, Hypotheses,

# Models and Implications



FIG. 7.—HST WFPC2 color image of M31 constructed from *I*-band, *V*-band and 3000 Å band PSF-deconvolved images obtained by Lauer et al. (1998). The left brightness peak (with embedded blue star cluster) is P2; the right peak is P1. The *I*- and *V*-band images were substepped by half of a PC pixel, so the scale is 0.0228 pixel<sup>-1</sup>. The 3000 Å image was not substepped; we matched it to the *I*- and *V*-band images by interpolation.

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FIG. 2. (a) Contour map of the surface brightness of the best-fit model. The contour interval is  $0^{m}$ 1, and the vertical axis points  $70^{\circ}$  counterclockwise from north. The origin, which coincides with the black hole at P2, is marked by a cross, and the projected locations of the three ringlets in Eq. (2) are shown as dotted lines. (b) Deconvolved V-band surface-brightness contours of the nucleus of M31 (Fig. 2 of L93). The orientation and origin are the same as in (a) but the contour interval of  $0^{m}$ 25 is larger and a larger area is shown.

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Figure 1: Before and After

#### Two Counter-Rotating Rings

Start with two softened counter-rotating Keplerian rings, with angular momenta,

 $L_p = m_p \sqrt{GM_{\bullet}a_p}(1-e_p^2) \text{ and } L_r = -m_r \sqrt{GM_{\bullet}a_r(1-e_r^2)};$ 

- Of course both secular energy, and total angular momentum,  $L_T = L_p + L_r$  are conserved;
- A positive torque exerted by p on r would increase r's angular momentum, making  $L_r$  tend to zero, hence increasing r's eccentricity;
- An equal and opposite (hence negative) torque exerted by r on p would decrease p's angular momentum, making  $L_p$  tend to zero, hence increasing r's eccentricity;
- The CR instability requires that such a configuration is maintained for sufficiently long to bring about significant growth in eccentricities; maintaining such a configuration would require that rings precess with neighboring frequency, in the same direction, with increasing eccentricity: Such a tuning is provided by softening(heat)!

#### Numerical Clusters

- Black Hole,  $10^8 M_{\odot}$ , dominating cluster,  $10^7 M_{\odot}$ , perturbed by various counter-rotating perturbers,  $10^5 -510^6 M_{\odot}$ ;
- Cluster: thin Kuzmin disk (ring) radial scale of 1pc, with vertical  $sech^2$  profile with 0.1pc, typical  $\sigma_v \simeq 200$  km/s;
- Perturbers: Counter-rotating: ring (both overlapping and not, coplanar, inclined), IMBH (various configurations).
- $10^4 -10^6$  particles, softening length of  $10^{-3}$  pc for particle-particle interactions, and  $10^{-5}$  pc for particle-SMBH interactions;
- Parallel runs on cluster of 8-36 procs, with tree code (Gadget's parallel version), pushed to its limits, errors of  $10^{-4}$  and  $10^{-5}$  in energy and angular momentum respectively, over 1 Myr calculations ( $10T_{prec}$ ).

# Axisymmetric to Eccentric



# Puffing up a Thin Disk





Figure 1: Eccentricity-Inclination Evolution

# Mode Relaxation as Function of SMBH Softening



#### Averaged (secular), self-consistent, collisionless dynamics

Evolution governed by CBE-Poisson system of equations:

$$\frac{\partial f}{\partial t} + \mathbf{v} \cdot \frac{\partial \mathbf{f}}{\partial \mathbf{r}} - \nabla \phi \cdot \frac{\partial \mathbf{f}}{\partial \mathbf{v}} = \mathbf{0}$$

where:  $\phi(\mathbf{r}, \mathbf{t}) = \phi_{self}(\mathbf{r}, \mathbf{t}) + \phi_{ext}(\mathbf{r}, \mathbf{t})$ ,

$$\phi_{self}(\mathbf{r}, \mathbf{t}) = -\mathbf{G} \int \mathbf{d}^{3}\mathbf{r}' \mathbf{d}^{3}\mathbf{v}' \frac{\mathbf{f}(\mathbf{r}', \mathbf{v}'\mathbf{t})}{|\mathbf{r} - \mathbf{r}'|}$$

and  $\phi_{ext}(\mathbf{r}, \mathbf{t}) = \frac{-\mathbf{GM}_{\bullet}}{\mathbf{r}} + \phi_{\mathbf{c}}(\mathbf{r}, \mathbf{t})$ 

- Black-Hole dominated dynamics, hence essentially Keplerian motion perturbed by cluster potential. Replace orbits by rings, with mass distributed inversely proportional to time spent on orbit (Averaging, Gauss)
- Consequence of Averaging:  $L \sim \sqrt{GM_{\bullet}a}$  conserved, leaving precession (periapsis, node) and eccentricity/inclination dynamics of Gaussian ring, in averaged cluster potential:  $f_{ave}(L, G, H, g, h, t)$

# Secular (Orbit Averaged), CBE-Poisson Dynamics

The three actions are:

- $I_a = \sqrt{GMa};$
- $L_a = |\mathbf{r} \times \mathbf{v}|$ , the magnitude of the orbital angular momentum;
- $L_{az} = (\hat{z} \cdot \boldsymbol{r} \times \boldsymbol{v})$ , the *z*-component of the orbital angular momentum.

The angles conjugate to them:

- $w_a$ , the orbital phase;
- $\mathbf{g}_a$ , the angle to periapse from the ascending node;
- $h_a$ , the longitude of the ascending node.

In these Variabes:

 $H_{kepler}(I_a) = -1/2(GM/I_a)^2$ 

Trivial Dynamics:

- All variables constant except,  $w_a$ ;
- $w_a$  advancing at constant keplerian rate:  $\Omega_k = (\partial H_k / \partial I_a) = (GM)^2 / I_a^3$

#### Secular Collisionless Boltzmann

#### Consequences on Forces:

- Potential:  $\Phi(I, L, L_z, g, h, t) = -G \oint \frac{dw}{2\pi} \int d^3r' d^3v' \frac{F(I', L', L'_z, g', h', t)}{|\mathbf{r} \mathbf{r}'|}$
- Non Inertial Forces:

$$\boldsymbol{a}(t) = G \int d^3r \, d^3v \, F \frac{\hat{\boldsymbol{r}}}{r^2} = G \int dI \, dL \, dL_z \, dg \, dh F(I, \, L, \, L_z, \, g, \, h, \, t) \oint dw \, \frac{\hat{\boldsymbol{r}}}{r^2}$$

which averages to zero over a Keplerian orbit! Slow Dynamics, Equations:

$$\frac{dL}{dt} = -\frac{\partial\Phi}{\partial g}, \qquad \frac{dg}{dt} = \frac{\partial\Phi}{\partial L}; \qquad \frac{dL_z}{dt} = -\frac{\partial\Phi}{\partial h}, \qquad \frac{dh}{dt} = \frac{\partial\Phi}{\partial L_z}$$

Slow Dynamics, CBE:

$$\frac{dF}{dt} \equiv \frac{\partial F}{\partial t} - \frac{\partial \Phi}{\partial g} \frac{\partial F}{\partial L} + \frac{\partial \Phi}{\partial L} \frac{\partial F}{\partial g} - \frac{\partial \Phi}{\partial h} \frac{\partial F}{\partial L_z} + \frac{\partial \Phi}{\partial L_z} \frac{\partial F}{\partial h} = \frac{\partial F}{\partial t} + [F, \Phi] = 0$$



Figure 1: Instability in 2D: Density in Time

#### Single Particle Phase-Space

Restricting to Planar configurations:

- Cluster Mean Field:  $\Phi(r, \theta, t) = \Phi_0(r, t) + \Phi_1(r, t) \cos[\theta + \phi(r, t)]$
- Single Particle Hamiltonian::  $H = \frac{v^2}{2} \frac{GM}{r} + \Phi(r, \theta, t)$
- Softened Black Hole ::  $H = \frac{v^2}{2} \frac{GM}{r} + [\frac{GM}{r} \frac{GM}{\sqrt{r^2 + b^2}}] + \Phi(r, \theta, t)$
- Averaging over Keplerian ring:  $x = a[\cos(g)(\cos(E) \sqrt{1 e^2}) l\sin(g)\sin(E)],$  $y = a[\sin(g)(\cos(E) - \sqrt{1 - e^2}) + l\cos(g)\sin(E)];$
- Averaged Hamiltonian:  $H_{ave} = \Phi_0(a, l, t) + \Phi_1(a, l, t) \cos(g) \Omega(t)l$
- $\overline{\Phi}_0 \propto e^2$  undergoes slight variations;  $\overline{\Phi}_1(a, l, t) \propto e$  increases significantly;  $\Omega(t)$  increases to a maximum of  $60kms^{-1}pc^{-1}$ , before saturating at half that value;



Figure 3: Instability in 2D: Prograde in xy-plane, a = 0.9 pc



Figure 2: Instability in 2D: Retrograde in xy-plane, a = 0.9pc



Figure 6: Instability in 2D: Retrograde in lg-plane,  $a=0.9 {\rm pc}$ 



Figure 4: Instability in 2D: Retrograde in xy-plane, a = 0.9pc



Figure 5: Instability in 2D: Retrograde in xy-plane, a = 0.9pc



Figure 7: Instability in 2D: Sphere and Phase Plane a = 0.9pc



Figure 1: Particle Centroid vs Model Equilibrium: Prograde Population at various semi-major axis



Figure 2: Particle Centroid vs Model Equilibrium: Retrograde Populations at  $a=0.9~{\rm pc}$ 



Figure 4: Instability in 2D: Equilibria and Separatrix



Figure 3:  $\Phi_0$  and  $\Phi_1$  before and after Averaging

#### Model Hamiltonian

- Averaged Hamiltonian:  $H_{ave} = \Phi_0(a, l, t) + \Phi_1(a, l, t) \cos(g) \Omega(t) l$
- For moderate eccentricity:  $\bar{\Phi}_0 \propto e^2$ , and  $\bar{\Phi}_1(a,l,t) \propto e(\sqrt{1-l^2})$
- Model Hamiltonian:  $H = -\frac{1}{2}f_0(t)l^2 + f_1(t)\sqrt{1-l^2}\cos(g) \Omega(t)l$
- Adiabatic Limit:  $t_{prec} \gg t_{growth}$ , hence work with time-frozen Hamiltonian:  $H_{freeze} = -\frac{1}{2}f_0l^2 + f_1\sqrt{1-l^2}\cos g - \Omega l$
- Rescale by  $f_0$ :  $\frac{H}{f_0} = -\frac{1}{2}l^2 + \alpha\sqrt{1-l^2}\cos g \beta l$  with  $\alpha = f_1/f_0$  and  $\beta = \Omega/f_0$ ;
- One degree of freedom, with slowly varying parameters:  $H_s = -\frac{1}{2}[l+\beta]^2 + \alpha\sqrt{1-l^2} \cos g$

# **Equations of Motion**

Precession:

$$\frac{dg}{dt} = \frac{\partial H_s}{\partial l} = -l - \beta - \alpha \frac{l}{\sqrt{1 - l^2}} \cos(g)$$

Torque (change in e):

$$\frac{dl}{dt} = -\frac{\partial H_s}{\partial g} = \alpha \sqrt{1 - l^2} \sin g$$

or

$$\frac{dg}{dt} = -l - \beta - \alpha \frac{l}{e} \cos(g)$$
$$\frac{dl}{dt} = \alpha e \sin g$$

with  $\alpha, \beta > 0$ 

#### **Qualitative Features**

- Increasing  $\alpha$ : pattern is more lopsided, with stronger torques;
- Increasing β: faster pattern speed; prograde needs to decrease eccentricity (increase I) to keep up, if at all; and the reverse is true;
- Prograde (*l* ≥ 0), aligned equilibrium: For increasing α (mode strength), *e* needs to increase to maintain equilibrium at fixed β; similarly if β were to decrease higher eccentricity would be required to maintain the equilibrium; indication of likelihood of capture;
- Increasing  $\alpha$ : stronger mode, larger torques; positive torque increases eccentricity of retrograde ( $l < 0, \Delta l > 0$ ), and decreases eccentricity of prograde orbit; negative torque works in reverse;

#### **Qualitative Features**

- Prograde (*l* ≥ 0): retro-precession from axisymmetric mean field, modulated by contributions from lopsided field; for *g* around π (aligned orbits), pro-precession from *m* = 1 lump, and the possibility of reversing effect of axisymmetric Φ<sub>0</sub> to get a star to precess with prograde pattern;
- Retrograde ( $l \le 0$ ): pro-precession from axisymmetric mean field, modulated by contributions from lopsided field; for g around  $\pi$  (aligned orbits), retro-precession from m = 1 lump, and the possibility of reversing the effect  $\Phi_0$ , to pull a star into retrograde precession;

#### Capture into and Escape From Resonance

Time variation of model parameters,  $\alpha(t)$  and  $\beta(t)$ :

- Adiabatic Regime: variations slow when compared to orbital periods (precession due to  $\Phi_0(t)$ ;
- A Sequence of time frozen Hamiltonians: Critical behavior around separatrices;
- Capture and Escape: Likelihood of excitation of l > 0 populations, likelihood of capture and excitation of l < 0;
- The Picture is modified by the self-consistent requirement in which  $\alpha(t)$  and  $\beta(t)$  are functions of the evolving distributions;





Figure 1: Model Hamiltonian:  $\beta = 0.6$ , and  $\alpha$  varying between 0.01 and 0.4.



Figure 2: Model Hamiltonian: Prograde Dynamics for  $\beta=0.6,$  and  $\alpha$  varying between 0.01 and 0.4.



Figure 3: Model Hamiltonian: Prograde Dynamics for  $\beta=0.6,$  and  $\alpha$  varying between 0.01 and 0.4.

# Summary

- Violent instabilities in Hot, Counter-Rotating, Stellar systems, which promote growth of eccentricities and inclinations on rather short timescales
- Unstable configurations saturate into puffy m = 1 equilibria: At least the m=1 part comes out naturally as a negative temperature thermodynamic equilibrium of counter-rotating clusters.
- Saturation is associated with the dispersal the (lighter), counter-rotating perturber: in 3D, via eccentricity/inclination instability; in 2D via filling of the full (prograde and retrograde) phase space.

#### Plan of Action

- In 2D: Construct a self-consistent model for the time-varying parameters that enter into our averaged, adiabatic dynamics;
- In 3D: Identify the source of eccentricity-inclination instability, and generalize current, 2D treatment, to the full 4D phase-space;
- For both limits: Study the workings of relaxation (mainly resonant) on the saturated mode;
- Secure the link between micro-canonical equilibria, and our global modes.