Lower Bounds for the Decay of Correlations in Non-uniformly Expanding Maps

Huyi Hu * Sandro Vaienti [†]

August 24, 2017

Abstract

We give conditions under which nonuniformly expanding maps exhibit lower bounds of polynomial type for the decay of correlations and for a large class of observables. We show that if the Lasota-Yorke type inequality for the transfer operator of a first return map are satisfied in a Banach space \mathcal{B} , and the absolutely continuous invariant measure obtained is weak mixing, in terms of aperiodicity, then under some renewal condition, the maps have polynomial decay of correlations for observables in \mathcal{B} . We also provide some general conditions that give aperiodicity for expanding maps in higher dimensional spaces. As applications, we obtain lower bounds for piecewise expanding maps with an indifferent fixed point and for which we also allow non-Markov structure and unbounded distortion. The observables are functions that have bounded variation or satisfy quasi-Hölder conditions and have their support bounded away from the neutral fixed points.

0 Introduction

The purpose of this paper is to study polynomial decay of correlations for invariant measures which are absolutely continuous with respect to the Lebesgue measure on compact subsets of \mathbb{R}^n . Typically the maps T which we consider are non uniformly expanding and may neither have a Markov partition nor exhibit

^{*}Mathematics Department, Michigan State University, East Lansing, MI 48824, USA. e-mail: <hu@math.msu.edu>.

[†]Aix Marseille Université, CNRS, CPT, UMR 7332, Marseille, France and and Université de Toulon, CNRS, CPT, UMR 7332, 83957 La Garde. e-mail: <vaienti@cpt.univ-mrs.fr>. HH was supported by Aix-Marseille University and the University of Toulon during his visits at the Center of Theoretical Physics in Luminy. SV was supported by the ANR-Project *Perturbations*, by the CNRS-PEPS *Mathematical Methods of Climate Theory* and by the PICS (Projet International de Coopération Scientifique), *Propriétés statistiques des systèmes dynamiques detérministes et aléatoires*, with the University of Houston, n. PICS05968. Part of this work was done while he was visiting the *Centro de Modelamiento Matemático, UMI2807*, in Santiago de Chile with a CNRS support (délégation).

bounded distortion. The main tool we use is the transfer (Perron-Frobenius) operator on induced subsystems endowed with the first return map.

We now explain in detail the content of this paper. Let us consider a non uniformly expanding map T defined on a compact subset $X \subset \mathbb{R}^n$, with or without discontinuities. Since we do not have necessarily bounded distortion or Markov partitions, the Hölder property is not preserved under the transfer operator. Therefore we will work on Banach spaces \mathcal{B} embedded in L^1 with respect to the Lebesgue measure, and we will give some conditions on \mathcal{B} under which the results apply, see Assumption B.

Let us now take a subset $\hat{X} \subset X$ and define the first return map \hat{T} . The first ingredient of our theorem is the Lasota-Yorke inequality for the transfer operator $\widehat{\mathscr{P}}$ of \widehat{T} with respect to the norms $\|\cdot\|_{\mathcal{B}}$ and $\|\cdot\|_{L^1}$. Hence, $\widehat{\mathscr{P}}$ has a fixed point \hat{h} that defines an absolutely continuous measure $\hat{\mu}$ invariant under T. The measure $\hat{\mu}$ can be extended to a measure μ on X invariant under T. We may assume ergodicity for $\hat{\mu}$, otherwise we take an ergodic component. Then the ergodicity of $\hat{\mu}$ gives ergodicity of μ . However, we also need some mixing property for μ . Therefore our *second ingredient* is to require that the function τ given by the first return time is *aperiodic*, which is equivalent to the weak mixing of μ for T. The *third ingredient* is precise tail estimates as they are required in the renewal theory approach. In this regard, let us call $||R_n||$ the operator norm (see below) of the n-th power of the transfer operator restricted to the level sets with first return time $\tau = n$; then we ask that $\sum_{k=n+1}^{\infty} ||R_k||$ decays at least as $n^{-\beta}$, with $\beta > 1$. Such a decay gives also an estimate, through the exponent β , of the error term denoted by the function $F_{\beta}(n)$ in the basic inequality (1.3) of Theorem A below. Whenever that error term goes to zero faster than $\sum_{k=n+1}^{\infty} \mu(\tau > k)$, the latter sum gives a lower bound for the decay of correlations and we will refer to this situation as the optimal rate: this will be shown to hold in the situations of Section 5.

The proof of aperiodicity in Theorem B is particularly technical. We use some results of the theory developed in the paper [ADSZ], where aperiodicity is proved for a large class of interval maps, and some methods in [AD] for skew product rigidity. We extend the aperiodicity result to the multidimensional setting without Markov partitions thus pursuing the program started in [ADSZ], which was just oriented to treat the non-Markov cases especially for one-dimensional systems.

Several examples will be presented and discussed in detail.

In the one-dimensional case we use the set of bounded variation functions for the Banach space \mathcal{B} , and we find that the decay rates are of order $n^{\beta-1}$ if near the fixed point the map has the form $T(x) \approx x + x^{1+\gamma}$, $\gamma \in (0,1)$ and $\beta = 1/\gamma$. Upper bounds for the decay of correlations for these kinds of maps were already given by Young [Yo2] and by Melbourne and Terhesiu, see Section 5.3 in [MT]. We then consider a large class of maps in higher dimensions that we introduced in a previous paper [HV], and in sections 4 and 5 we will specify the *roles* of the derivative and of the determinant in order to get a lower bound for the decay of correlations.

In particular we will obtain optimal rates under the assumption that all the pre-images of some neighborhood of p do not intersect discontinuities, (see Theorem E and examples in Subsection 5.2 for more details). This is satisfied for instance whenever T has a Markov partition, even countable, see Remark 5.1. Moreover in Example 5.5 and thereinafter we show the existence of these systems with all the pre-images of some neighborhood of p not intersecting discontinuities, but without any Markov structure.

We would like to point out two main issues which make the higher dimensional case more complicated. The first is due to *unbounded distortion* of the map. This is caused by different expansion rates in different directions as a point move away from the indifferent fixed point even if $DT_p = \text{id}$ at the fixed point (see Example 1, part (A) in [HV]). The second comes from the difficulty to estimate the decreasing rates of the norm $||R_n||$ for quasi-Hölder spaces: Theorems D and E deal with these situations under certain hypotheses. One surely needs more work to weaken those assumptions and achieve optimal decay for a much larger class of maps.

1 Assumptions and statements of results

Let $X \subset \mathbb{R}^m$ be a subset with positive Lebesgue measure ν . We assume $\nu(X) = 1$.

The transfer operator $\mathscr{P} = \mathscr{P}_{\nu} : L^{1}(X,\nu) \to L^{1}(X,\nu)$ is defined by $\int \psi \circ T\phi d\nu = \int \psi \mathscr{P}\phi d\nu \ \forall \phi \in L^{1}(X,\nu), \ \psi \in L^{\infty}(X,\nu).$

Let $\widehat{X} \subset X$ be a measurable subset of X with positive Lebesgue measure.

Recall that the first return map of T with respect to $\widehat{X} \subset X$ is defined by $\widehat{T}(x) = T^{\tau(x)}(x)$, where $\tau(x) = \min\{i \geq 1 : T^i x \in \widehat{X}\}$ is the return time. We put $\hat{\nu}$ the normalized Lebesgue measure on \widehat{X} . Then we let $\widehat{\mathscr{P}} = \widehat{\mathscr{P}}_{\hat{\nu}}$ be the transfer operator of \widehat{T} .

Moreover we define

$$R_n f = 1_{\widehat{X}} \cdot \mathscr{P}^n(f 1_{\{\tau=n\}}) \quad \text{and} \quad T_n f = 1_{\widehat{X}} \cdot \mathscr{P}^n(f 1_{\widehat{X}}) \tag{1.1}$$

for any function f on \widehat{X} . For any $z \in \mathbb{C}$, denote $R(z) = \sum_{n=1}^{\infty} z^n R_n$. It is clear

that $\widehat{\mathscr{P}} = R(1) = \sum_{n=1}^{\infty} R_n.$

For simplicity of notation, we regard the space $L^1(\hat{X}, \hat{\nu})$ as a subspace of $L^1(X, \nu)$ consisting of functions supported on \hat{X} , and we denote it by $L^1(\hat{\nu})$ or

sometimes by L^1 and when no ambiguity arises. We will denote $\mathbb{D} = \{z \in \mathbb{C} : |z| < 1\}$ and $\mathbb{S} = \{z \in \mathbb{C} : |z| = 1\}$.

Suppose that there is a seminorm $|\cdot|_{\mathcal{B}}$ for functions in $L^1(\widehat{X}, \hat{\nu})$. Consider the set $\mathcal{B} = \mathcal{B}(\widehat{X}) = \{f \in L^1(\widehat{X}, \hat{\nu}) : |f|_{\mathcal{B}} < \infty\}$. Define a norm on \mathcal{B} by

$$||f||_{\mathcal{B}} = |f|_{\mathcal{B}} + ||f||_1$$

for $f \in \mathcal{B}$, where $||f||_1$ is the L^1 norm. We assume that \mathcal{B} satisfies the requirements stated below; the assumptions (a) to (c) will be necessary to establish the spectral gap of the induced transfer operator, while conditions (d) to (f) will be useful to prove aperiodicity. We first define a set $U \subset \hat{X}$ to be *almost open* with respect to $\hat{\nu}$ if for $\hat{\nu}$ almost every point $x \in U$, there is a neighborhood V(x)such that $\hat{\nu}(V(x) \setminus U) = 0$.

- **Assumption B.** (a) (Compactness) \mathcal{B} is a Banach space and the inclusion $\mathcal{B} \hookrightarrow L^1(\hat{\nu})$ is compact; that is, any bounded closed set in \mathcal{B} is compact in $L^1(\hat{\nu})$.
- (b) (Boundedness) The inclusion $\mathcal{B} \hookrightarrow L^{\infty}(\hat{\nu})$ is bounded; that is, $\exists C_b > 0$ such that $\|f\|_{\infty} \leq C_b \|f\|_{\mathcal{B}}$ for any $f \in \mathcal{B}$.
- (c) (Algebra) \mathcal{B} is an algebra with the usual sum and product of functions, in particular there exists a constant C_a such that $||fg||_{\mathcal{B}} \leq C_a ||f||_{\mathcal{B}} ||g||_{\mathcal{B}}$ for any $f, g \in \mathcal{B}$.
- (d) (Denseness) The image of the inclusion $\mathcal{B} \hookrightarrow L^1(\hat{\nu})$ is dense in $L^1(\hat{\nu})$.
- (e) (Lower semicontinuity) For any sequence $\{f_n\} \subset \mathcal{B}$ with $\lim_{n \to \infty} f_n = f$ $\hat{\nu}$ -almost everywhere, $|f|_{\mathcal{B}} \leq \liminf |f_n|_{\mathcal{B}}$.
- (f) (Openness) For any nonnegative function $f \in \mathcal{B}$, the set $\{f > 0\}$ is almost open with respect to $\hat{\nu}$.

Remark 1.1. Assumption B(f) means that functions in \mathcal{B} are not far from continuous functions.

The possibility of computing a lower bound for the decay of correlations relies on a result first established by Sarig [Sr] and improved by Gouëzel [Go]. We now state the sufficient conditions on our systems which will allow us to apply those results and we will comment later on about such implication.

Assumption S. Let $X \subset \mathbb{R}^m$ be a compact subset and $\widehat{X} \subset X$ be a compact subset of X.

Let $T: X \to X$ be a map whose first return map with respect to \widehat{X} is $\widehat{T} = T^{\tau}$, and \mathcal{B} be a Banach space satisfying Assumption B(a) to (c). We assume the following. (S1) (Quasi compactness) There exist constants $B, \hat{D} > 0$ and $\hat{\eta} \in (0, 1)$ such that for any $f \in \mathcal{B}, z \in \overline{\mathbb{D}}$,

$$||R(z)^{n}f||_{\mathcal{B}} \le |z^{n}| (B\hat{\eta}^{n} ||f||_{\mathcal{B}} + \hat{D} ||f||_{1}).$$
(1.2)

Note that for z = 1 we obtain the usual Lasota-Yorke inequality for the operator $\widehat{\mathscr{P}}$.

- (S2) (Aperiodicity) The function $e^{it\tau}$ given by the return time is aperiodic, that is, the only solution for $e^{it\tau} = f/f \circ \hat{T}$ which holds almost everywhere with a measurable function $f: \hat{X} \to \mathbb{S}$, is provided by f constant almost everywhere and t = 0. It will follow that the measure $\hat{\mu}$ given by $\hat{\mu}(f) = \hat{\nu}(\hat{h}f)$, where \hat{h} is a fixed point of $\widehat{\mathcal{P}}$, is ergodic since aperiodicity is equivalent to weak-mixing (see e.g. |PP|).
- (S3) (Return times tail) The \mathcal{B} -norm of the operator R_n is summable and satisfies $\sum_{k=n+1}^{\infty} ||R_k||_{\mathcal{B}} = O(n^{-\beta})$ for some $\beta > 1$.

As we said above, a useful reformulation of the theorems in [Sr] and [Go] allows us to get the following result:

Theorem A. Let us suppose that Assumption (S) is satisfied; then there exists a constant C > 0 such that for any function $f \in \mathcal{B}$, $g \in L^{\infty}(X, \nu)$ with $\operatorname{supp} f$, $\operatorname{supp} g \subset \widehat{X}$,

$$\left|\operatorname{Cov}(f,g\circ T^n) - \left(\sum_{k=n+1}^{\infty}\mu(\tau>k)\right)\int fd\mu\int gd\mu\right| \le CF_{\beta}(n)\|g\|_{\infty}\|f\|_{\mathcal{B}}, \quad (1.3)$$

where $F_{\beta}(n) = 1/n^{\beta}$ if $\beta > 2$, $(\log n)/n^2$ if $\beta = 2$, and $1/n^{2\beta-2}$ if $2 > \beta > 1$.

- **Comments.** 1. Sarig and Gouëzel theory requires that in addition to condition (S3), two more assumptions are satisfied. The first condition asks that 1 is a simple isolated eigenvalue of R(1) and this is an immediate consequence of the quasi-compactness of $\widehat{\mathscr{P}}$ and of the ergodicity of $\hat{\mu}$.
 - 2. The second assumption requires that 1 is not an eigenvalue of R(z) for |z| = 1 with $z \neq 1$. Let us fix $0 < t < 2\pi$ and put $z = e^{it}$; if we suppose that R(z)f = f for some nonzero $f \in \mathcal{B}$, by the arguments developed in the proof of the Lemma 6.6 in [Go], that is equivalent to the equation $e^{-it\tau} f \circ \hat{T} = f$ almost everywhere. By the aperiodicity condition (S2) we conclude that t = 0 and f is a constant $\hat{\mu}$ -almost everywhere which is a contradiction.

Assumption (S2) is usually difficult to check. However, for piecewise expanding systems, the condition can be verified and we will give some sufficient conditions in Theorem B below.

The more general version of aperiodicity is the following. Let \mathbb{G} be a locally compact Abelian polish group. A measurable function $\phi: \hat{X} \to \mathbb{G}$ is *aperiodic* if the only solutions for $\gamma \circ \phi = \lambda f/f \circ T$ almost everywhere with $\gamma \in \widehat{\mathbb{G}}$, $|\lambda| = 1$ and a measurable function $f: \hat{X} \to \mathbb{G}$ are $\gamma = 1$, $\lambda = 1$ and f constant almost everywhere, see [ADSZ] and references therein. Here we only consider the case $\gamma = \text{id}$, and $\phi = e^{it\tau}$, and \mathbb{G} being the smallest compact subgroup of \mathbb{S} containing e^{it} .

We denote by $B_{\varepsilon}(\Gamma)$ the ε neighborhood of a set $\Gamma \subset X$. Recall that the notion of *almost open* is given before the statement of Assumption B. We now state a few conditions which must be satisfied by all the maps considered from now on.

- Assumption T. (a) (Piecewise smoothness) There are countably many disjoint sets U_1, U_2, \cdots almost open with respect to ν , with $\widehat{X} = \bigcup_{i=1}^{\infty} U_i$ a compact set, such that for each $i, \widehat{T}_i := \widehat{T}|_{U_i}$ extends to a $C^{1+\alpha}$ diffeomorphism from \overline{U}_i to its image, and $\tau|_{U_i}$ is constant; we will use the symbol \widehat{T}_i to denote the extension as well.
- (b) (Finite images) The collection $\{\widehat{T}U_i : i = 1, 2, \dots\}$ is finite, and $\nu(B_{\varepsilon}(\partial \widehat{T}U_i)) = O(\varepsilon) \quad \forall i = 1, 2, \dots$.
- (c) (Expansion) There exists $s \in (0,1)$ such that $d(\widehat{T}x,\widehat{T}y) \geq s^{-1}d(x,y)$ $\forall x, y \in \overline{U}_i \ \forall i \geq 1.$
- (d) (Topological mixing) $T: X \to X$ is topological mixing.

Remark 1.2. Conditions (b) and (c) in Assumption T correspond to conditions (F) and (U) in [ADSZ]. There is there a third assumption, (A), which is distortion and which is not necessarily guaranteed in our systems. With this precision, we could regard the systems satisfying Assumption T(a)-(c) as higher dimensional "AFU" systems. Returning to the finite image condition T (b), it is used in proof of Lemma 2.1 below, to get $\mu(A_{n,n_0}) \rightarrow 1$ as $n_0 \rightarrow \infty$ and this is a consequence of a "small image boundary" as explained in the first footnote of the proof of Theorem B.

Remark 1.3. We mention that if T has relatively prime return times on almost all points $x \in \widehat{X}$, then Condition (d) is satisfied. The former means that for any neighborhood U of x, there is a point $y \in U$ and return times $\tau'(x)$ and $\tau'(y)$ such that $T^{\tau'(x)}(x), T^{\tau'(x)}(x) \in U$ and the greatest common divisor $(\tau'(x), \tau'(y)) = 1$. Here $\tau'(x)$ and $\tau'(y)$ are not necessary the first return time.

Let us take now a partition ξ of \widehat{X} and consider a family of skew-products of the form

$$\widetilde{T} = \widetilde{T}_S : \widehat{X} \times Y \to \widehat{X} \times Y , \ \widetilde{T}_S(x, y) = \left(\widehat{T}x, \ S(\xi(x))(y)\right),$$
(1.4)

where (Y, \mathcal{F}, ρ) is a Lebesgue probability space, $\operatorname{Aut}(Y)$ is the collection of its automorphisms, that is, invertible measure-preserving transformations, and $S : \xi \to \operatorname{Aut}(Y)$ is arbitrary.

We then consider functions $\tilde{f} \in L^1(\hat{\nu} \times \rho)$ and define

$$|\widetilde{f}|_{\widetilde{\mathcal{B}}} = \int_{Y} |\widetilde{f}(\cdot, y)|_{\mathcal{B}} d\rho(y), \qquad \|\widetilde{f}\|_{\widetilde{\mathcal{B}}} = |\widetilde{f}|_{\widetilde{\mathcal{B}}} + \|\widetilde{f}\|_{L^{1}(\widehat{\nu} \times \rho)}.$$

Then we let

$$\widetilde{\mathcal{B}} = \{ \widetilde{f} \in L^1(\hat{\nu} \times \rho) : |\widetilde{f}|_{\widetilde{\mathcal{B}}} < \infty \}.$$

It is easy to see that with the norm $\|\cdot\|_{\widetilde{\mathcal{B}}}, \widetilde{\mathcal{B}}$ is a Banach space.

The transfer operator $\widetilde{\mathscr{P}} = \widetilde{\mathscr{P}}_{\hat{\nu} \times \rho}$ acting on $L^1(\hat{\nu} \times \rho)$ is defined as the dual of the operator $\tilde{f} \to \tilde{f} \circ \tilde{T}$ from $L^{\infty}(\hat{\nu} \times \rho)$ to itself. Note that if Y is a space consisting of a single point, then we can identify $\hat{X} \times Y$, \tilde{T} and $\widetilde{\mathscr{P}}$ with \hat{X}, \hat{T} and $\widehat{\mathscr{P}}$ respectively.

Theorem B. Let us suppose \widehat{T} satisfies Assumption T(a) to (d) and \mathcal{B} satisfies Assumption B(d) to (f), and $\widetilde{\mathscr{P}}$ satisfies the Lasota-Yorke inequality

$$|(\widetilde{\mathscr{P}f})|_{\widetilde{\mathcal{B}}} \le \widetilde{\eta}|\widetilde{f}|_{\widetilde{\mathcal{B}}} + \widetilde{D}||\widetilde{f}||_{L^1(\widehat{\nu} \times \rho)}$$
(1.5)

for some $\tilde{\eta} \in (0,1)$ and $\tilde{D} > 0$. Then the absolutely continuous invariant measure $\hat{\mu}$ obtained from the Lasota-Yorke inequality (1.2) is ergodic and $e^{it\tau}$ is aperiodic. Therefore Assumptions (S2) and (S3) follow.

Remark 1.4. It is well known that for $C^{1+\alpha}$, $\alpha > 1$, uniformly expanding maps or uniformly hyperbolic diffeomorphisms, the absolutely continuous invariant measures or the SRB measure μ are ergodic if the maps are topological mixing, see e.g. [Bo] for invertible case; the noninvertible case can be obtained similarly.

However, it is not the case if the conditions on $C^{1+\alpha}$ or uniformity of hyperbolicity fail. In [Qu] the author gives an example of C^1 uniformly expanding maps of the unit circle, and in [HPT] the authors provide an example of C^{∞} diffeomorphisms, where the Lebesgue measure is preserved and topological mixing does not give ergodicity. In the proof of the theorem we in fact give some additional conditions under which topological mixing implies ergodicity (see Lemma 2.2).

2 Aperiodicity

The proof of Theorem B is based on a result in [ADSZ]. We briefly mention the terminology used there.

A fibred system is a quintuple $(X, \mathcal{A}, \nu, T, \xi)$, where (X, \mathcal{A}, ν, T) is a nonsingular transformation on a σ -finite measure space and $\xi \subset \mathcal{A}$ is a finite or countable partition (mod ν) such that:

- (1) $\xi_{\infty} = \bigvee_{i=0}^{\infty} T^{-i} \xi$ generates \mathcal{A} ;
- (2) every $A \in \xi$ has positive measure;
- (3) for every $A \in \xi$, $T|_A : A \to TA$ is bimeasurable invertible with nonsingular inverse.

The transformation given in (1.4) is called the *skew product over* ξ . We will denote with ξ_n the *n*-join $\xi_n = \bigvee_{i=0}^{n-1} T^{-i}\xi$, and with $\xi_n(x)$ the element (cylinder) of the partition ξ_n containing the point x. Consider the corresponding transfer operator $\widetilde{\mathscr{P}} = \widetilde{\mathscr{P}}_{\nu \times \rho}$. A fibred system $(X, \mathcal{A}, \nu, T, \xi)$ with ν finite is called *skew-product rigid* if for every invariant function $\widetilde{h}(x, y)$ of $\widetilde{\mathscr{P}}$ of an arbitrary skew product \widetilde{T}_S , the set $\{\widetilde{h}(\cdot, y) > 0\}$ is almost open (mod ν) for almost every $y \in Y$. In [ADSZ], a set U being almost open (mod ν) means that for ν almost every $x \in U$, there is a positive integer n such that $\nu(\xi_n(x) \setminus U) = 0$. Since the partition ξ we are interested in satisfies $\nu(\partial A) = 0$ for any $A \in \xi_n$ and \widehat{T} is piecewise smooth, the fact that ξ_{∞} generates \mathcal{A} implies that the definition given there is the same as we defined for Assumption B(f).

A set that can be expressed in the form $\widehat{T}^n \xi_n(x)$, $n \ge 1$ and $x \in \widehat{X}$, is called an *image set*. A cylinder C of length n_0 is called a *cylinder of full returns*, if for almost all $x \in C$ there exist $n_k \nearrow \infty$ such that $\widehat{T}^{n_k} \xi_{n_k+n_0}(x) = C$. In this case we say that $\widehat{T}^{n_0}(C)$ is a *recurrent image set*.

Our proof of Theorem B is based on a result given in Theorem 2 in [ADSZ]:

Theorem. Let $(X, \mathcal{A}, \mu, T, \xi)$ be a skew-product rigid measure preserving fibred system whose image sets are almost open. Let \mathbb{G} be a locally compact Abelian polish group. If $\gamma \circ \phi = \lambda f/f \circ T$ holds almost everywhere, where $\phi : X \to \mathbb{G}, \xi$ measurable, $\gamma \in \widehat{\mathbb{G}}, \lambda \in \mathbb{S}$, then f is constant on every recurrent image set.

Warning: In the proof of Theorem B and the lemmas below we will work exclusively on the induced space \hat{X} and with measures $\hat{\nu}$ and $\hat{\mu}$ and density \hat{h} ; for this reason we will drop the hat on those notations.

Proof of Theorem B. Recall that μ is an \widehat{T} invariant measure with density h, where h is the fixed point of $\widehat{\mathscr{P}}$ in \mathcal{B} . By Lemma 2.2 we know that μ is ergodic; hence we only need to prove that $e^{it\tau}$ is aperiodic.

Let us denote with \mathcal{A} the Borel σ -algebra inherited from \mathbb{R}^m and take a countable partition ξ of \widehat{X} into $\{U_i\}$ or finer. We also require that each $A \in \xi$ is almost open, and $\nu(B_{\varepsilon}(\partial \widehat{T}\xi)) = O(\varepsilon)$, where $\partial \widehat{T}\xi = \bigcup_{A \in \xi} \partial(\widehat{T}A)$. Is it obvious that we can take smooth surfaces as the boundary of the elements of ξ , in addition to Assumption T(b) *. Since \widehat{T} is uniformly expanding by Assumption T(c), we know that each element of $\xi_{\infty} = \bigvee_{i=0}^{\infty} \widehat{T}^{-i}\xi$ contains at most one

^{*}This assumption is in fact used to get the measure of an ϵ -neighborhood of the boundary of $\hat{T}\xi$ of order ϵ .

point.[†] Therefore ξ_{∞} generates \mathcal{A} . We may regard that each $A \in \xi$ has positive measure, otherwise we can use $\widehat{X} \setminus A$ to replace \widehat{X} . Also, for every $A \in \xi$, $\widehat{T}|_A : A \to \widehat{T}A$ is a diffeomorphism, and therefore $\widehat{T}|_A$ is bimeasurable invertible with nonsingular inverse. Hence the quintuple $(\widehat{X}, \mathcal{A}, \mu, \widehat{T}, \xi)$ is a measure preserving fibred system.

The construction of ξ implies that $\mu(\partial\xi) = \nu(\partial\xi) = 0$; therefore $\mu(\partial\xi_n) = \nu(\partial\xi_n) = 0$ for any $n \ge 1$. We point out that the intersection of finite number of almost open sets is still almost open. Moreover, the differentiability of \hat{T} on each U_i implies that all elements $\xi_n(x)$ of ξ_n are almost open, and therefore all image sets $\hat{T}^n\xi_n(x)$ are almost open with respect to μ .

To get skew product rigidity, let us consider the skew product \widetilde{T}_S defined in (1.4) for any (Y, \mathcal{F}, ρ) . Let $\widetilde{\mathscr{P}} = \widetilde{\mathscr{P}}_{\nu \times \rho}$ be the transfer operator and \widetilde{h} an invariant function, that is, $\widetilde{\mathscr{P}h} = \widetilde{h}$. By Proposition 2.3 below we know that $\widetilde{h} \in \widetilde{B}$. Hence, for ρ -almost every $y \in Y$, $\widetilde{h}(\cdot, y) \in \mathcal{B}$. By Assumption B(f), $\{\widetilde{h}(\cdot, y) > 0\}$ is almost open mod ν . This gives the skew product rigidity.

So far we have verified all conditions in the theorem of [ADSZ] stated above. Applying the theorem to the equation $e^{it\tau} = f/f \circ \hat{T}$ almost everywhere, where $f: \hat{X} \to \mathbb{S}$ is a measurable function, we get that f is constant on every recurrent image sets J.

Now we prove aperiodicity, by following similar arguments in [Go]. Let us assume that the equation $e^{it\tau} = f/f \circ \hat{T}$ holds almost everywhere for some real number t and a measurable function $f: \hat{X} \to \mathbb{S}$. By Lemma 2.1 below we get that \hat{X} contains a recurrent image set J with $\mu(J) > 0$ and by the theorem above, we know that f is constant, say c, almost everywhere on J. Then by the absolute continuity of μ and the fact that $\{h > 0\}$ is ν -almost open, we can find an open set $J' \subset J$ of positive μ -measure. Thanks to Assumption T(d), T is topological mixing and therefore for all sufficiently large n, we have $T^{-n}J' \cap J' \neq \emptyset$. Since the intersection is open[‡], we get that $\mu(T^{-n}J' \cap J') > 0$ and as a consequence for any typical point x in $T^{-n}J' \cap J'$, there is k > 0 such that $T^n x = \hat{T}^k x$, and $n = \sum_{i=0}^{k-1} \tau(\hat{T}^i x)$. Since $e^{it\tau} = f/f \circ \hat{T}$ along the orbit of x, we have

$$e^{int} = e^{it\sum_{0}^{k-1}\tau(\widehat{T}^{i}x)} = \frac{f(x)}{f(\widehat{T}x)}\frac{f(\widehat{T}x)}{f(\widehat{T}^{2}x)}\cdots\frac{f(\widehat{T}^{k-1}x)}{f(\widehat{T}^{k}x)} = \frac{f(x)}{f(\widehat{T}^{k}x)} = \frac{c}{c} = 1.$$

Since this is true for all large n, by replacing n by n + 1 we get that $e^{it} = 1$. It follows that t = 0 and $f = f \circ \hat{T}$ almost everywhere which implies that f must

[†]In fact, if $x, y \in \xi_{\infty}$, then for any i > 0, $\widehat{T}^i x$ and $\widehat{T}^i y$ are always in the same elements of ξ , and hence in the same U_{n_i} for some $n_i > 0$. On the other hand, by Assumption T(c) we have $d(\widehat{T}^i x, \widehat{T}^i y) \ge s^{-i} d(x, y)$. If $d(x, y) \neq 0$, then $d(\widehat{T}^i x, \widehat{T}^i y) \to \infty$, contradicting the facts that \widehat{X} is compact. We in fact recall that in Lebesgue spaces a necessary and sufficient condition for $\xi_n \to \mathcal{A}$ is that there exists a set of zero measure $N \subset \widehat{X}$ such that for $x, y \in \widehat{X}/N$ (with $x \neq y$) there exists $n \ge 1$ and $U \in \xi_n$ such that $x \in U$ but $y \notin U$.

^{\ddagger}Strictly speaking that intersection contains open sets since T and all its powers, although not continuous, are local diffeomorphisms, on each domain where they are injective.

be a constant almost everywhere since μ is ergodic.

To prove Lemma 2.1, we need a result from Lemma 2 in Section 4 in [ADSZ]. We state it as the next lemma. The setting for the lemma is a conservative fibred system and it can be applied directly to our case.

Lemma. A cylinder $C \in \xi_{n_0}$ is a cylinder of full returns if and only if there exists a set K of positive measure such that for almost every $x \in K$, there are $n_i \to \infty$ with $\widehat{T}^{n_i}\xi_{n_i+n_0}(x) = C$.

Lemma 2.1. There is a recurrent image set J contained in \widehat{X} with $\mu(J) > 0$.

Proof. We first recall that s is given in Assumption T(c); then let us take $C_{\xi} > 0$ such that diam $D \leq C_{\xi}$ for all $D \in \xi$ and set

$$\begin{split} A'_{k,n_0} &= \{ x \in \widehat{X} : x \notin B_{C_{\xi}s^{k+n_0}}(\partial \widehat{T}\xi) \} \\ A_{n,n_0} &= \bigcap_{k=0}^{n-1} \widehat{T}^{n-k} A'_{k,n_0}. \end{split}$$

By the construction of ξ , there is C' > 0 such that $\nu(A'_{k,n_0}) \ge 1 - C'C_{\xi}s^{k+n_0}$; moreover assumption B(b) guarantees that $\|h\|_{\infty} < \infty$. Therefore if we take $C = C'C_{\xi}\|h\|_{\infty}/(1-s)$, then $\mu(A'_{k,n_0}) \ge 1 - C'C_{\xi}\|h\|_{\infty}s^{k+n_0} = 1 - C(1-s)s^{k+n_0}$. Since μ is an invariant measure, $\mu(A_{n,n_0}) \ge 1 - C(1-s)\sum_{i=0}^{n-1}s^{i+n_0} \ge 1 - Cs^{n_0}$. If we choose n_0 large enough, then $\mu(A_{n,n_0})$ is bounded below by a positive number for all n > 0, and the bound can be chosen arbitrarily close to 1 by taking n_0 sufficiently large.

Note that ξ_n is a partition with at most countably many elements. For each $n_0 > 0$, let B'_{n_0} be the union of a finite number of elements of ξ_{n_0} such that $\mu(B'_{n_0}) > 1 - Cs^{n_0}/2$. Then set $B_{n,n_0} = B'_{n_0} \cap \widehat{T}^{-n}B'_{n_0}$; clearly, $\mu(B_{n,n_0}) \ge 1 - Cs^{n_0}$. If we now put $C_{n,n_0} = A_{n,n_0} \cap B_{n,n_0}$, then we have $\mu(C_{n,n_0}) \ge 1 - 2Cs^{n_0}$. Hence, $\sum_{n=0}^{\infty} \mu(C_{n,n_0}) = \infty$ for all large n_0 .

A generalized Borel-Cantelli Lemma by Kochen and Stone (see [Ya]), gives that for any given $n_0 > 0$, the set of points that belong to infinitely many C_{n,n_0} has the measure bounded below by

$$\limsup_{n \to \infty} \frac{\sum_{1 \le i < k \le n} \mu(C_{i,n_0}) \mu(C_{k,n_0})}{\sum_{1 \le i < k \le n} \mu(C_{i,n_0} \cap C_{k,n_0})}.$$

Notice that if $n_0 \to \infty$, then $\mu(C_{i,n_0}) \to 1$ as $n_0 \to \infty$ and uniformly in *i* by the previous lower bound on $\mu(C_{n,n_0})$. Hence the upper limit goes to 1 as $n_0 \to \infty$. If we now se

$$\Gamma_{n_0} = \{ x \in X : x \in C_{n,n_0} \text{ infinitely often} \},\$$

the above argument gives $\mu(\Gamma_{n_0}) \to 1$ as $n_0 \to \infty$.

We observe that for a one-to-one map T, $T(A \cap T^{-1}B) = B$ if and only if $B \subset TA$. Since $\xi_n(x) = \xi(x) \cap \widehat{T}^{-1}(\xi_{n-1}(\widehat{T}x))$, and \widehat{T} is a local diffeomorphism,

we know that $\widehat{T}\xi_n(x) = \xi_{n-1}(\widehat{T}x)$ if and only if $\xi_{n-1}(\widehat{T}x) \subset \widehat{T}\xi(x)$. Inductively, $\widehat{T}^n\xi_{n+n_0}(x) = \xi_{n_0}(\widehat{T}^nx)$ if and only if $\xi_{n-i+n_0}(\widehat{T}^ix) \subset \widehat{T}\xi(\widehat{T}^{i-1}x)$ for $i = 1, \dots, n$. If $x \in A_{n,n_0}$ for some $n, n_0 > 0$, then $\widehat{T}^{n-i}x \notin B_{C_{\xi}s^{i+n_0}}(\partial\widehat{T}\xi)$ for all $i = 1, \dots, n$. Since the diameter of each member of ξ is less than C_{ξ} , by Assumption T(c), diam $\xi_n(x) \leq C_{\xi}s^n$ for any $x \in \widehat{X}$ and $n \geq 0$. We get $\xi_{n-i+n_0}(\widehat{T}^ix) \subset \widehat{T}\xi(\widehat{T}^{i-1}x)$ and therefore $\widehat{T}^n\xi_{n+n_0}(x) = \xi_{n_0}(\widehat{T}^nx)$. Consequently, if $x \in \Gamma_{n_0}$, then $x \in C_{n_i,n_0} = A_{n_i,n_0} \cap B_{n_i,n_0}$ for infinitely many n_i . Hence, $\widehat{T}^{n_i}\xi_{n_i+n_0}(x) = \xi_{n_0}(\widehat{T}^{n_i}x)$ and $\widehat{T}^{n_i}x \in B_{n_0}$ for infinitely many n_i ,

We now take $n_0 > 0$ such that $\mu(\Gamma_{n_0}) > 0$; since B_{n_0} consists of only finitely many elements in ξ_{n_0} , we know that there is an element $C \in \xi_{n_0}$ with $C \subset B_{n_0}$ such that

$$\mu\{x: \widehat{T}^n \xi_{n+n_0}(x) = \xi_{n_0}(\widehat{T}^n x) = C \text{ infinitely often}\} > 0.$$
(2.1)

By the above lemma from [ADSZ], C is a cylinder of full returns. Hence, $J = \hat{T}^{n_0}C$ is a recurrent image set. Since μ is an invariant measure, (2.1) implies $\mu(C) > 0$ and therefore $\mu(J) > 0$.

Lemma 2.2. Let us suppose that T and \mathcal{B} satisfy Assumption T(d) and B(f) respectively. Then there is only one absolutely continuous invariant measure μ which is ergodic.

Proof. Suppose μ has two ergodic components μ_1 and μ_2 whose density functions are h_1 and h_2 respectively. Hence, $\nu(\{h_1 > 0\} \cap \{h_2 > 0\}) = 0$. Since $h_1, h_2 \in \mathcal{B}$, the sets $\{h_1 > 0\}$ and $\{h_2 > 0\}$ are almost open. We can take open sets U_1 and U_2 such that $\nu(U_1 \setminus \{h_1 > 0\}) = 0$ and $\nu(U_2 \setminus \{h_1 > 0\}) = 0$. Since T is topological mixing, there is n > 0 such that $T^{-n}U_1 \cap U_2 \neq \emptyset$. Hence, $\nu(T^{-n}U_1 \cap U_2) > 0$ and therefore $\nu(U_1 \cap T^nU_2) > 0$. It follows that there is k > 0 such that $\nu(U_1 \cap \widehat{T}^kU_2) > 0$. Since $\widehat{\mathscr{P}}h_2 = h_2, h_2(x) > 0$ implies $h_2(\widehat{T}^kx) > 0$. Hence $\nu(\widehat{T}^kU_2 \setminus \{h_2 > 0\}) = 0$. Therefore, $\nu(\{h_1 > 0\} \cap \{h_2 > 0\}) \ge \nu(U_1 \cap \widehat{T}^kU_2) > 0$, which is a contradiction. \Box

We are left with the proof that any fixed point \hat{h} of $\hat{\mathcal{P}}$ belongs to \mathcal{B} . The result was proved for Gibbs-Markov maps in [AD]. We show that it holds in more general cases. To simplify the notation we will write from now on $L^1(\nu \times \rho)$ instead of $L^1(\hat{X} \times Y, \nu \times \rho)$.

Proposition 2.3. Suppose that \mathcal{B} satisfies Assumption B(d) and (e), and $\widetilde{\mathscr{P}}$ satisfies Lasota-Yorke inequality (1.5). Then any $L^1(\nu \times \rho)$ function \tilde{h} on $\widehat{X} \times Y$ that satisfies $\widetilde{\mathscr{P}}_{\nu \times \rho} \tilde{h} = \tilde{h}$ belongs to $\widetilde{\mathcal{B}}$.

Proof. By Assumption B(d), \mathcal{B} is dense in $L^1(\widehat{X}, \nu)$; it is easy to see that $\widetilde{\mathcal{B}}$ is dense in $L^1(\nu \times \rho)$ too. Hence, for any $\varepsilon > 0$ we can find a nonnegative function $\widetilde{f}_{\varepsilon} \in \widetilde{\mathcal{B}}$ such that $\|\widetilde{f}_{\varepsilon} - \widetilde{h}\|_{L^1(\nu \times \rho)} < \varepsilon$. By the stochastic ergodic theorem,

see Krengel ([Kr]), there exists a nonnegative function $\tilde{h}_{\varepsilon} \in L^1(\nu \times \rho)$ and a subsequence $\{n_k\}$ such that

$$\lim_{k \to \infty} \frac{1}{n_k} \sum_{\ell=0}^{n_k - 1} \widetilde{\mathscr{P}}^{\ell} \widetilde{f}_{\varepsilon} = \widetilde{h}_{\varepsilon} \qquad \nu \times \rho \text{-a.e.}$$
(2.2)

and $\widetilde{\mathscr{P}}\widetilde{h}_{\varepsilon} = \widetilde{h}_{\varepsilon}$.

Notice that Lasota-Yorke inequality (1.5) implies that for any $\tilde{f} \in \tilde{\mathcal{B}}, \ell \geq 1$,

$$|\widetilde{\mathscr{P}}^{\ell}\widetilde{f}|_{\widetilde{\mathcal{B}}} \leq \widetilde{\eta}^{\ell}|\widetilde{f}|_{\widetilde{\mathcal{B}}} + \widetilde{D}^{*}\|\widetilde{f}\|_{L^{1}(\nu \times \rho)} \leq \widetilde{D}_{2}\|\widetilde{f}\|_{\widetilde{\mathcal{B}}},$$
(2.3)

where $\widetilde{D}^* = \widetilde{D}\widetilde{\eta}/(1-\widetilde{\eta}) \geq \widetilde{D}(\widetilde{\eta} + \dots + \widetilde{\eta}^{\ell-1})$ and $\widetilde{D}_2 = 1 + \widetilde{D}^*$. Denote $\psi_k = \frac{1}{n_k} \sum_{\ell=0}^{n_k-1} \widetilde{\mathscr{P}}^\ell f_{\varepsilon}$; by (2.3) $\psi_k \leq \widetilde{D}_2 \|\widetilde{f}\|_{\widetilde{\mathcal{B}}}$. On the other hand (2.2) implies that $\liminf_{k\to\infty} \psi_k(x,y) = \widetilde{h}_{\varepsilon}(x,y)$ for ν -a.e. $x \in \widehat{X}$, ρ -a.e. $y \in Y$. Hence, by Assumption B(e) and Fatou's lemma we obtain

$$\begin{aligned} |\widetilde{h}_{\varepsilon}|_{\widetilde{\mathcal{B}}} &= \int_{Y} |\lim_{k \to \infty} \psi_{k}(\cdot, y)|_{\mathcal{B}} d\rho(y) \leq \int_{Y} \liminf_{k \to \infty} |\psi_{k}(\cdot, y)|_{\mathcal{B}} d\rho(y) \\ &\leq \liminf_{k \to \infty} \int_{Y} |\psi_{k}(\cdot, y)|_{\mathcal{B}} d\rho(y) = \liminf_{k \to \infty} |\psi_{k}|_{\widetilde{\mathcal{B}}} \leq \widetilde{D}_{2} ||\widetilde{f}_{\varepsilon}||_{\widetilde{\mathcal{B}}}. \end{aligned}$$

$$(2.4)$$

This means that $\tilde{h}_{\varepsilon} \in \widetilde{\mathcal{B}}$.

By Fatou's Lemma and the fact that $\widetilde{\mathscr{P}}$ is a contraction on $L^1(\nu \times \rho)$, it follows immediately that (2.2) and $\widetilde{\mathscr{P}h} = \widetilde{h}$ imply

$$\|\widetilde{h} - \widetilde{h}_{\varepsilon}\|_{L^{1}(\nu \times \rho)} \leq \liminf_{k \to \infty} \frac{1}{n_{k}} \sum_{l=0}^{n_{k}-1} \|\widetilde{\mathscr{P}}^{\ell}(\widetilde{h} - \widetilde{f}_{\varepsilon})\|_{L^{1}(\nu \times \rho)} \leq \|\widetilde{h} - \widetilde{f}_{\varepsilon}\|_{L^{1}(\nu \times \rho)} \leq \varepsilon.$$

By the first inequality of (2.3) we know that for any $n \ge 1$,

$$\|\widetilde{h}_{\varepsilon}\|_{\widetilde{\mathcal{B}}} = \|\widetilde{\mathscr{P}}^n \widetilde{h}_{\varepsilon}\|_{\widetilde{\mathcal{B}}} \le \widetilde{\eta}^n \|\widetilde{h}_{\varepsilon}\|_{\widetilde{\mathcal{B}}} + \widetilde{D}^* \|\widetilde{h}_{\varepsilon}\|_{L^1(\nu \times \rho)}.$$

If we now send *n* to infinity we get $\|\widetilde{h}_{\varepsilon}\|_{\widetilde{\mathcal{B}}} \leq \widetilde{D}^* \|\widetilde{h}_{\varepsilon}\|_{L^1(\nu \times \rho)} \leq \widetilde{D}^* (\|\widetilde{h}\|_{L^1(\nu \times \rho)} + \varepsilon)$. We then replace ε with a decreasing sequence $c_n \to 0$ as $n \to \infty$. Since \widetilde{h}_{c_n} converges in $L^1(\nu \times \rho)$ to \widetilde{h} , there is a subsequence n_i such that $\lim_{i\to\infty} \widetilde{h}_{c_{n_i}} = \widetilde{h}$, $\nu \times \rho$ -a.e.. Then by the same arguments used in (2.4), we get

$$|\widetilde{h} - \widetilde{h}_{c_n}|_{\widetilde{\mathcal{B}}} \leq \liminf_{i \to \infty} |\widetilde{h}_{c_{n_i}} - \widetilde{h}_{c_n}|_{\widetilde{\mathcal{B}}} \leq 2 \sup_{0 \leq \varepsilon \leq 1} \|\widetilde{h}_{\varepsilon}\|_{\widetilde{\mathcal{B}}} \leq 2\widetilde{D}_1(\|\widetilde{h}\|_{L^1(\nu \times \rho)} + 1).$$

We have thus obtained $\tilde{h} - \tilde{h}_{c_n} \in \tilde{\mathcal{B}}$ and as a consequence $h = (h - h_{c_n}) + h_{c_n} \in \tilde{\mathcal{B}}$ and this completes the proof.

3 Systems on the interval

In this section we take X = [0, 1] and ν be the Lebesgue measure on X.

We remind that for a map $T: X \to X$ and a subset $\widehat{X} \subset X$, the corresponding first return map is denoted by $\widehat{T}: \widehat{X} \to \widehat{X}; \widehat{\nu}$ will be again the normalized Lebesgue measure on \widehat{X} .

Let us now assume that $T: X \to X$ is a map satisfying the following conditions.

- **Assumption T'.** (a) (Piecewise smoothness) There are points $0 = a_0 < a_1 < \cdots < a_K = 1$ such that for each j, $T_j = T|_{I_j}$ is a C^2 diffeomorphism on its image, where $I_j = (a_{j-1}, a_j)$.
 - (b) (Fixed point) T(0) = 0.
 - (c) (Expansion) There exists $z \in I_1$ such that $T(z) \in I_1$ and $\Delta := \inf_{x \in \widehat{X}} |T'(x)| > 2$ for any $x \in \widehat{X}$, where $\widehat{X} = [z, 1]$.
 - (d) (Distortion) $\Gamma := \sup_{x \in [z,1]} |\widehat{T}''(x)| / |\widehat{T}'(x)|^2 < \infty.$
 - (e) (Topological mixing) $T: I \to I$ is topological mixing.

We now set J = [0, z) and $\widehat{X} = \widehat{X}_J = X \setminus J$. $I_0 = TJ \setminus J \subset I_1$. We also denote the first return map $\widehat{T} = \widehat{T}_J$ by \widehat{T}_{ij} if $\widehat{T} = T_1^i T_j$. Further, we put $I_{01} = I_1 \setminus J$, $I_{0j} = I_j \setminus T_j^{-1}J$ if j > 1, and $I_{ij} = \widehat{T}_{i,j}^{-1}I_0$ for i > 0. Hence, $\{I_{ij} : i = 0, 1, 2, \cdots\}$ form a partition of $I_j = (a_j, b_j)$ for $j = 2, \cdots, K$. Also, we denote $\overline{I}_{ij} = [a_{ij}, b_{ij}]$ for any $i = 0, 1, 2, \cdots$ and $j = 1, \cdots, K$.

Recall that the variation of a real or complex valued function f on [a, b] is defined by

$$V_{[a,b]}(f) := \sup_{\xi \in \Xi} \sum_{i=1}^{n} |f(x^{(\ell)}) - f(x^{(\ell-1)})|,$$

where ξ is a finite partition of [a, b] given by $a = x^{(0)} < x^{(1)} < \cdots < x^{(n)} = b$ and Ξ is the set of all such partitions. A function $f \in L^1([a, b], \nu)$, where ν denotes the Lebesgue measure, is of bounded variation if $V_{[a,b]}(f) = \inf_g V_{[a,b]}(g) < \infty$, where the infimum is taken over all the functions $g = f \nu$ -a.e.. Let \mathcal{B} be the set of functions $f \in L^1(\hat{X}, \hat{\nu}), f : \hat{X} \to \mathbb{R}$ with $V_{\hat{X}}(f) < \infty$. For $f \in \mathcal{B}$, denote by $|f|_{\mathcal{B}} = V_{\hat{X}}(f)$, the total variation of f. Then we define $||f||_{\mathcal{B}} = ||f||_1 + |f|_{\mathcal{B}}$, where the L^1 norm is intended with respect to $\hat{\nu}$. It is well known that $|| \cdot ||_{\mathcal{B}}$ is a norm, and with this norm, \mathcal{B} becomes a Banach space.

To obtain the decay rates, we also assume that there are constants $0 < \gamma < 1$, $\gamma' > \gamma$ and $\tilde{C} > 0$ such that in a neighborhood of the indifferent fixed point p = 0,

$$T(x) = x + \tilde{C}x^{1+\gamma} + O(x^{1+\gamma'}),$$

$$T'(x) = 1 + \tilde{C}(1+\gamma)x^{\gamma} + O(x^{\gamma'}),$$

$$T''(x) = \tilde{C}\gamma(1+\gamma)x^{\gamma-1} + O(x^{\gamma'-1}).$$

(3.1)

For any sequences of numbers $\{a_n\}$ and $\{b_n\}$, we write $a_n \sim b_n$ if $\lim_{n \to \infty} a_n/b_n = 1$, and $a_n \approx b_n$ if $c_1 b_n \leq a_n \leq c_2 b_n$ for some constants $c_2 \geq c_1 > 0$.

$$d_{ij} = \sup\{|\hat{T}'_{ij}(x)|^{-1} : x \in I_{ij}\}, \quad d_n = \max\{d_{n,j} : 2 \le j \le K\}.$$
 (3.2)

Theorem C. Let \widehat{X} , \widehat{T} and \mathcal{B} be defined as above, and suppose that T satisfies Assumption T'(a) to (e). Then Assumption B(a) to (f) and assumptions (S1) to (S3) are satisfied and $||R_n|| = O(d_n)$. Hence, if $d_n = O(n^{-(\beta+1)})$ for some $\beta > 1$, then there exists C > 0 such that for any functions $f \in \mathcal{B}$, $g \in L^{\infty}(X, \nu)$ with supp f, supp $g \subset \widehat{X}$, (1.3) holds.

In particular, if T satisfies (3.1) near 0, then
$$\sum_{k=n+1}^{\infty} \mu(\tau > k) = O(n^{-(\frac{1}{\gamma}-1)})$$

and $d_n = O(n^{-(\frac{1}{\gamma}+1)})$. Since $\frac{1}{\gamma} - 1 < \frac{1}{\gamma}$ and $\frac{1}{\gamma} - 1 < 2(\frac{1}{\gamma} - 1)$ we have

$$\operatorname{Cov}(f, g \circ T^n) \sim \sum_{k=n+1}^{\infty} \mu(\tau > k) \int f d\mu \int g d\mu \ \approx \frac{1}{n^{\frac{1}{\gamma} - 1}}.$$

It is well known that if the map T allows a Markov partition, then the decay of correlations is of order $O(n^{-(\frac{1}{\gamma}-1)})$ (see e.g. [Hu], [Sr], [LSV], [PY]). For non-Markov case, the upper bound estimate is given in [Yo2] and in [MT].

Proof of Theorem C. Thanks to Lemma 3.1 proved below, \mathcal{B} satisfies Assumption B(a) to (f); moreover by Lemma 3.2, we know that condition S(1) is satisfied. Notice that all requirements of Assumption T hold, since part (a), (c) and (d) follow from Assumption T'(a), (c) and (e) directly, and part (b) follows from the definition of \hat{T} . Moreover Lemma 3.2 (iii) gives (1.5). Hence Theorem B can be applied and therefore conditions S(2) and S(3) are satisfied.

The estimate $||R_n|| = O(d_n)$ follows from Lemma 3.3: we have thus proved the decay of correlations (1.3).

Suppose that T also satisfies (3.1); we denote with $z_n \in I_1$ the point such that $T^n(z_n) = z$. It is well known that $z_n \sim (\gamma n)^{-1/\gamma}$ (see e.g. Lemma 3.1 in [HV]), and then we obtain $(T_1^{-n})'(x) = O(n^{-\frac{1}{\gamma}-1})$; it follows that $d_n = O(n^{-\frac{1}{\gamma}-1})$. Since the density function h is bounded on \hat{X} , $\mu(\tau > k) \leq C_1 \nu(\tau > k) \leq C_2 z_k$ for some $C_1, C_2 > 0$. Hence $\sum_{k=n+1}^{\infty} \mu(\tau > k) = O(n^{-\frac{1}{\gamma}+1})$.

Lemma 3.1. \mathcal{B} is a Banach space satisfying Assumption B(a) to (f) with $C_a = C_b = 1$.

Proof. These are standard facts, see for instance the proofs in Chapter 1 in [Br]. $\hfill \Box$

Lemma 3.2. There exist constants $\eta \in (0,1)$ and $D, \overline{D} > 0$ satisfying

- (i) for any $f \in \mathcal{B}$, $|\widehat{\mathscr{P}}f|_{\mathcal{B}} \leq \eta |f|_{\mathcal{B}} + D ||f||_{L^1(\hat{\nu})};$
- (ii) for any $f \in \mathcal{B}$, $||R(z)f||_{\mathcal{B}} \le |z| (\eta ||f||_{\mathcal{B}} + \bar{D} ||f||_{L^1(\hat{\nu})})$; and
- (iii) for any $f \in \widetilde{\mathcal{B}}$, $\|\widetilde{\mathscr{P}}\widetilde{f}\|_{\widetilde{\mathcal{B}}} \leq \eta \|\widetilde{f}\|_{\widetilde{\mathcal{B}}} + D\|\widetilde{f}\|_{L^1(\hat{\nu} \times \rho)}$.

Proof. (i) Let us denote $x_{ij} = \widehat{T}_{ij}^{-1}(x)$, and $\widehat{g}(x_{ij}) = |\widehat{T}'_{ij}(x_{ij})|^{-1}$; we have

$$\widehat{\mathscr{P}}f(x) = \sum_{j=1}^{K} \sum_{i=0}^{\infty} f(\widehat{T}_{ij}^{-1}x)\widehat{g}(\widehat{T}_{ij}^{-1}x)\mathbf{1}_{\widehat{T}I_{ij}}(x).$$

We now take a partition ξ of $\widehat{T}I_{ij}$ into $\widehat{T}_{ij}a_{ij} = x^{(0)} < x^{(1)} < \cdots < x^{(k_{ij})} = \widehat{T}_{ij}b_{ij}$, where we assume $\widehat{T}_{ij}a_{ij} < \widehat{T}_{ij}b_{ij}$ without loss of generality. Whenever $\widehat{T}I_{ij}$ intersects more than one intervals $I_k = (a_k, b_k)$ in the case i = 0, then we put the endpoints a_k and b_k into the partition. Denote $x_{ij}^{(\ell)} = \widehat{T}_{ij}^{-1}x^{(\ell)}$. We have

$$\sum_{\ell=1}^{k_{ij}} \left| f(x_{ij}^{(\ell)}) \widehat{g}(x_{ij}^{(\ell)}) - f(x_{ij}^{(\ell-1)}) \widehat{g}(x_{ij}^{(\ell-1)}) \right|$$

$$\leq \sum_{\ell=1}^{k_{ij}} \widehat{g}(x_{ij}^{(\ell)}) \left| f(x_{ij}^{(\ell)}) - f(x_{ij}^{(\ell-1)}) \right| + \sum_{\ell=1}^{k_{ij}} \left| f(x_{ij}^{(\ell-1)}) \right| \left| \widehat{g}(x_{ij}^{(\ell)}) - \widehat{g}(x_{ij}^{(\ell-1)}) \right|.$$
(3.3)

By (3.2), $\widehat{g}(x_{ij}^{(\ell)}) \leq d_{ij}$ and by definition $\sum_{\ell=1}^{k_{ij}} \left| f(x_{ij}^{(\ell-1)}) - f(x_{ij}^{(\ell)}) \right| \leq V_{I_{ij}}(f)$. Also, by the mean value theorem and Assumption T'(d),

$$\frac{|g(\widehat{x}_{ij}^{(\ell)}) - \widehat{g}(x_{ij}^{(\ell-1)})|}{x_{ij}^{(\ell)} - x_{ij}^{(\ell-1)}} \le |\widehat{g}'(c_{ij}^{(\ell)})| = |\widehat{T}''(c_{ij}^{(\ell)})| / |\widehat{T}'(c_{ij}^{(\ell)})|^2 \le \Gamma$$

where $c_{ij}^{(\ell)} \in [x_{ij}^{(\ell-1)}, x_{ij}^{(\ell)}]$. Using the fact that

$$\lim_{\max\{|x_{ij}^{(\ell)} - x_{ij}^{(\ell-1)}|\} \to 0} \sum_{\ell=1}^{k_{ij}} \left| f(x_{ij}^{(\ell-1)}) \right| (x_{ij}^{(\ell)} - x_{ij}^{(\ell-1)}) = \int_{a_{ij}}^{b_{ij}} |f| d\hat{\nu},$$

we get from (3.3) that

$$V_{\widehat{T}I_{ij}}((f \cdot \widehat{g}) \circ \widehat{T}_{ij}^{-1}) \le d_{ij}V_{I_{ij}}(f) + \Gamma \int_{I_{ij}} |f| d\hat{\nu}.$$
(3.4)

Denote $c = \min\{\nu(\widehat{T}I_{ij}) : i = 1, 2, \cdots, 1 \le j \le K\}$, where c > 0 because there is only a finite number of images $\widehat{T}I_{ij}$. It can be shown that (see e.g. [Br], Ch. 3)

$$V_{\hat{X}}(\widehat{\mathscr{P}}f) \le 2\sum_{j=1}^{K} \sum_{i=0}^{\infty} V_{\widehat{T}I_{ij}}((f \cdot \widehat{g}) \circ \widehat{T}_{ij}^{-1}) + 2c^{-1} \|f\|_{1}.$$

By Assumption T'(c), $d_{ij} \leq \Delta^{-1}$ for all $i = 1, 2, \cdots$ and $j = 1, \cdots, K$. Hence

$$|\widehat{\mathscr{P}}f|_{\mathcal{B}} = V_{\hat{X}}(\widehat{\mathscr{P}}f) \le 2\Delta^{-1}V(f) + 2\Gamma \int |f|d\hat{\nu} + 2c^{-1}||f||_1 = \eta|f|_{\mathcal{B}} + D||f||_1,$$

where $\eta = 2\Delta^{-1} < 1$ and $D = 2\Gamma + 2c^{-1} > 0$.

Part (ii) and (iii) can be proved similarly to the proofs of corresponding part of Lemma 4.2. $\hfill \Box$

Lemma 3.3. There exists a constant $C_R > 0$ such that $||R_n||_{\mathcal{B}} \leq C_R d_n$ for all n > 0.

Proof. For $f \in \mathcal{B}$, denote

$$R_{ij}f = 1_{\widehat{X}} \cdot \mathscr{P}^i(f 1_{I_{ij}})(x). \tag{3.5}$$

Hence $R_i = \sum_{j=1}^{K} R_{ij}$ and $\widehat{\mathscr{P}} = \sum_{i=0}^{\infty} \sum_{j=1}^{K} R_{ij}$ by definition and linearity of $\widehat{\mathscr{P}}$.

Assume i > 0; since $\widehat{T}_{ij}[a_{ij}, b_{ij}] = I_0 \subset I$, by (3.2), $\hat{\nu}(I_{ij}) \leq d_{ij}\hat{\nu}(I_0) < d_{ij}$. Hence, by Assumption B(b),

$$\int_{I_{ij}} |f| d\hat{\nu} \le \|f\|_{\infty} \hat{\nu}(I_{ij}) \le C_b \|f\|_{\mathcal{B}} \cdot d_{ij} \hat{\nu}(I_0) \le C_b d_{ij} \|f\|_{\mathcal{B}}.$$
 (3.6)

Note that $V_{I_{ij}}(f) \leq V(f) = |f|_{\mathcal{B}} < ||f||_{\mathcal{B}}$. By (3.4),

$$V_{\widehat{T}I_{ij}}((f \cdot \widehat{g}) \circ \widehat{T}_{ij}^{-1}) \le d_{ij} \|f\|_{\mathcal{B}} + \Gamma C_b d_{ij} \|f\|_{\mathcal{B}} = (1 + \Gamma C_b) d_{ij} \|f\|_{\mathcal{B}}.$$
 (3.7)

Since $R_{ij}f(x) = 1_{\widehat{X}}(x) \cdot (f \cdot \widehat{g}) \circ \widehat{T}_{ij}^{-1}(x)$, we have

$$|R_{ij}f|_{\mathcal{B}} \leq 2V_{\widehat{T}I_{ij}}((f \cdot \widehat{g}) \circ \widehat{T}_{ij}^{-1}) + 2\frac{1}{\widehat{\nu}(I_0)} \int_{I_{ij}} |f| d\widehat{\nu}.$$

Moreover by (3.6) and (3.7),

$$|R_{ij}f|_{\mathcal{B}} \leq 2(1+\Gamma C_b)d_{ij}||f||_{\mathcal{B}} + 2C_b d_{ij}||f||_{\mathcal{B}}.$$

On the other hand, by (3.5) and (3.6), we have

$$\|R_{ij}f\|_{L^1} = \int_{\widehat{X}} \widehat{\mathscr{P}}^{i+1}(f1_{I_{ij}})d\hat{\nu} = \int_{I_{ij}} fd\hat{\nu} \le \int_{I_{ij}} |f|d\hat{\nu} \le C_b d_{ij} \|f\|_{\mathcal{B}}.$$

Hence, we get

$$||R_{ij}f||_{\mathcal{B}} = |R_{ij}f|_{\mathcal{B}} + ||R_{ij}f||_{L^1} \le [2(1+\Gamma C_b) + 3C_b]d_{ij}||f||_{\mathcal{B}}$$

By the definition of R_{ij} and d_n , we have

$$\|R_n f\|_{\mathcal{B}} \le \sum_{j=2}^K \|R_{n-1,j} f\|_{\mathcal{B}} \le K' (2 + 2\Gamma C_b + 3C_b) d_n,$$

where K' < K is the number of preimages of I_0 that are not in I_1 . The result follows now with $C_R = K'(2 + 2\Gamma C_b + 3C_b)$.

4 Multidimensional spaces: generalities and the role of the derivative

The main difficulty to investigate the statistical properties for higher dimensional systems with an indifferent fixed point p is that near p the system could have *unbounded distortion* in the following sense: there are uncountably many points z near p such that for any neighborhood V of z, we can find $\hat{z} \in V$ with the ratio

$$|\det DT_1^{-n}(z)|/|\det DT_1^{-n}(\hat{z})|$$

unbounded as $n \to \infty$ (see Example in Section 2 in [HV]). For this reason we need a more extensive analysis of the expanding features around the neutral fixed point which will be accomplished by adding Assumption T " below.

4.1 Setting and statement of results.

Let $X \subset \mathbb{R}^m$, $m \ge 1$, be again a compact subset with $\overline{\operatorname{int} X} = X$, d the Euclidean distance, and ν the Lebesgue measure on X with $\nu(X) = 1$.

Assume that $T: X \to X$ is a map satisfying the following assumptions.

- **Assumption T''.** (a) (Piecewise smoothness) There are finitely many disjoint open sets U_1, \dots, U_K with piecewise smooth boundary such that $X = \bigcup_{i=1}^{K} \overline{U_i}$ and for each $i, T_i := T|_{U_i}$ can be extended to a $C^{1+\hat{\alpha}}$ diffeomorphism $T_i: \widetilde{U_i} \to B_{\varepsilon_1}(T_iU_i)$, where $\widetilde{U_i} \supset U_i$, $\hat{\alpha} \in (0, 1]$ and $\varepsilon_1 > 0$.
 - (b) (Fixed point) There is a fixed point $p \in U_1$ such that $T^{-1}p \notin \partial U_j$ for any $j = 1, \ldots, K$.
 - (c) (Topological mixing) $T: X \to X$ is topologically mixing.

Remark 4.1. Assumption T''(b) allows us to get a good structure for the first return map around any pre-images of p different from p itself. In particular there is an open neighborhood for each of those pre-images which is partitioned

in level sets ordered with increasing first return time starting from 2 and with the same (large) image for the induced map. This induction scheme turns out to be particularly useful when we consider the transfer operator on the quasi-Hölder function space; in this regard we also refer to our previous paper [HV].

Before continuing with the list of assumptions we need to introduce a few more quantities and notations.

For any $\varepsilon_0 > 0$, denote

$$G_U(x,\varepsilon,\varepsilon_0) = 2\sum_{j=1}^K \frac{\nu(T_j^{-1}B_\varepsilon(\partial TU_j) \cap B_{(1-s)\varepsilon_0}(x))}{\nu(B_{(1-s)\varepsilon_0}(x))}.$$

From now on we assume that the indifferent fixed point p = 0.

For any $x \in U_i$, we define s(x) as the inverse of the slowest expansion near x, that is,

$$s(x) = \min\{s : d(x, y) \le sd(Tx, Ty), y \in U_i, d(x, y) \le \min\{\varepsilon_1, 0.1|x|\}\}.$$

where the factor 0.1 forces the points y to stay in a ball around x which does not intersect the origin, though any other small factor would work as well.

Take an open neighborhood Q of p such that $TQ \subset U_1$, then let

$$s = s(Q) = \max\{s(x) : x \in X \setminus Q\}.$$
(4.1)

Let $\widehat{T} = \widehat{T}_Q$ be the first return map with respect to $\widehat{X} = \widehat{X}_Q = X \setminus Q$. Then for any $x \in U_j$, we have $\widehat{T}(x) = T_j(x)$ if $T_j(x) \notin Q$, and $\widehat{T}(x) = T_1^i T_j(x)$ for some i > 0 if $T_j(x) \in Q$. Denote $\widehat{T}_{ij} = T_1^i T_j$ for $i \ge 0$.

Further, we take $Q_0 = TQ \setminus Q$. Then we denote $U_{01} = U_1 \setminus Q$, $U_{0j} = U_j \setminus T_j^{-1}Q$ if j > 1, and $U_{ij} = \hat{T}_{ij}^{-1}Q_0$ for i > 0. Hence, $\{U_{ij} : i = 0, 1, 2, \cdots\}$ form a partition of U_j for $j = 2, \cdots, K$.

For $0 < \varepsilon \leq \varepsilon_0$, we denote

$$G_Q(x,\varepsilon,\varepsilon_0) = 2\sum_{j=1}^K \sum_{i=0}^\infty \frac{\nu(\hat{T}_{ij}^{-1}B_\varepsilon(\partial Q_0) \cap B_{(1-s)\varepsilon_0}(x))}{\nu(B_{(1-s)\varepsilon_0}(x))}$$

and

$$G(x,\varepsilon,\varepsilon_0) = G_U(x,\varepsilon,\varepsilon_0) + G_Q(x,\varepsilon,\varepsilon_0), \quad G(\varepsilon,\varepsilon_0) = \sup_{x\in\widehat{X}} G(x,\varepsilon,\varepsilon_0).$$
(4.2)

Assumption T''. (continued)

(d) (Expansion) T satisfies: $0 < s(x) < 1 \quad \forall x \in X \setminus \{p\}.$

Moreover, there exists an open region Q with $p \in Q \subset \overline{Q} \subset TQ \subset \overline{TQ} \subset U_1$ and constants $\alpha \in (0, \hat{\alpha}], \eta \in (0, 1)$, such that for all ε_0 small,

$$s^{\alpha} + \lambda \le \eta < 1,$$

where s is defined in (4.1) and

$$\lambda = 2 \sup_{0 < \varepsilon \le \varepsilon_0} \frac{G(\varepsilon, \varepsilon_0)}{\varepsilon^{\alpha}} \varepsilon_0^{\alpha}.$$
(4.3)

(e) (Distortion) For any b > 0, there exist $\zeta > 0$ such that for any small ε_0 and $\varepsilon \in (0, \varepsilon_0)$, we can find $0 < N = N(\varepsilon) \le \infty$ with

$$\frac{|\det DT_1^{-n}(y)|}{|\det DT_1^{-n}(x)|} \leq 1 + \zeta \varepsilon^{\alpha} \quad \forall y \in B_{\varepsilon}(x), \ x \in B_{\varepsilon_0}(Q_0), \ n \in (0, N],$$

and

$$\sum_{n=N}^{\infty} \sup_{y \in B_{\varepsilon}(x)} |\det DT_1^{-n}(y)| \le b\varepsilon^{m+\alpha} \quad \forall x \in B_{\varepsilon_0}(Q_0),$$

where α is given in part (d) and m is the dimension of the ambient space.

For sake of simplicity of notations, we may assume $\hat{\alpha} = \alpha$.

Remark 4.2. We stress that the measure $\nu(T_j^{-1}B_{\varepsilon}(\partial TU_j))$ usually plays an important role in the study of statistical properties of systems with discontinuities. Here $G_U(x, \varepsilon, \varepsilon_0)$ gives a quantitative measurement of the competition between the expansion and the accumulation of discontinuities near x. We refer to [Ss], Section 2, for more details about its geometric meaning. Furthermore it is proved, still in [Ss] Lemma 2.1, that if the boundary of U_i consists of piecewise C^1 codimension one embedded compact submanifolds, then $G_U(\varepsilon, \varepsilon_0) \leq 2N_U \frac{\gamma_{m-1}}{\gamma_m} \frac{s\varepsilon}{(1-s)\varepsilon_0} (1+o(1))$, where N_U is the maximal number of smooth components of the boundary of all U_i that meet in one point and γ_m is the volume of the unit ball in \mathbb{R}^m .

Remark 4.3. If $T^{-1}TQ \cap \partial U_j = \emptyset$ for any j, then for any small ε_0 , either $G_Q(x, \varepsilon, \varepsilon_0) = 0$ or $G_U(x, \varepsilon, \varepsilon_0) = 0$, and therefore we have $G(x, \varepsilon, \varepsilon_0) = \max\{G_U(x, \varepsilon, \varepsilon_0), G_Q(x, \varepsilon, \varepsilon_0)\}$.

Remark 4.4. If T has bounded distortion (see below), then G_Q is roughly equal to the ratio between the volume of $B_{\varepsilon_0}(\partial Q_0)$ and the volume of Q_0 . Therefore if ε_0 is small enough, then $\sup_{x \in \widehat{X}} \{G_Q(x, \varepsilon, \varepsilon_0)\}$ is bounded by $\sup_{x \in \widehat{X}} \{G_U(x, \varepsilon, \varepsilon_0)\}$.

Remark 4.5. We include Assumption T''(e) since near the fixed point the distortion for DT_1 is unbounded in general. It requires that either the distortion of DT_1^{-n} is small, or $|\det DT_1^{-n}|$ itself is small.

Remark 4.6. There are some sufficient conditions under which Assumption T''(d) and (e) could be easily verified. We refer [HV] for more details, see in particular Theorems B and C in that paper.

If near p the distortion is bounded, then Assumption T''(e) is automatically satisfied and it will be stated as follows (it could be regarded as the case $N(\varepsilon) = \infty$ for any $\varepsilon \in (0, \varepsilon_0)$):

Assumption T". (variant)

(e') (Bounded distortion) There exist J > 0 such that for any small ε_0 and $\varepsilon \in (0, \varepsilon_0)$,

$$\frac{|\det DT_1^{-n}(y)|}{|\det DT_1^{-n}(x)|} \le 1 + J\varepsilon^{\alpha} \quad \forall y \in B_{\varepsilon}(x), \ x \in B_{\varepsilon_0}(Q_0), \ n \ge 0.$$

Remark 4.7. It is well known that if dim X = m = 1, any system that has the form given by (4.4) below near the fixed point, satisfies Assumption T'(e'). The systems given in Example 4.1 satisfy it too.

To estimate the decay rates, we often consider the following special cases: there are constants $\gamma' > \gamma > 0$, $C_i, C'_i > 0$, i = 0, 1, 2, such that in a neighborhood of the indifferent fixed point p = 0:

$$|x| (1 - C'_0 |x|^{\gamma} + O(|x|^{\gamma'})) \leq |T_1^{-1}x| \leq |x| (1 - C_0 |x|^{\gamma} + O(|x|^{\gamma'})),$$

$$1 - C'_1 |x|^{\gamma} + O(|x|^{\gamma'}) \leq ||DT_1^{-1}(x)|| \leq 1 - C_1 |x|^{\gamma} + O(|x|^{\gamma'}), \qquad (4.4)$$

$$C'_2 |x|^{\gamma - 1} + O(|x|^{\gamma' - 1}) \leq ||D^2 T_1^{-1}(x)|| \leq C_2 |x|^{\gamma - 1} + O(|x|^{\gamma' - 1}).$$

where $||DT_1^{-1}||, ||DT||$ etc., denote the operator norms.

We now define the space of functions particularly adapted to study the action of the transfer operator on the class of maps just introduced. If Ω is a Borel subset of \hat{X} , we define the oscillation of f over Ω by the difference of essential supremum and essential infimum of f over Ω :

$$\operatorname{osc}(f,\Omega) = \operatorname{Esup}_{\Omega} f - \operatorname{Einf}_{\Omega} f.$$

We notice that the function $x \to osc(f, B_{\epsilon}(x))$ is measurable.

For $0 < \alpha < 1$ and $\varepsilon_0 > 0$, we define the quasi-Hölder seminorm of f with $\operatorname{supp} f \subset \widehat{X}$ as[§]

$$|f|_{\mathcal{B}} = \sup_{0 < \epsilon \le \epsilon_0} \epsilon^{-\alpha} \int_{\widehat{X}} \operatorname{osc}(f, B_{\epsilon}(x)) d\hat{\nu}(x), \qquad (4.5)$$

[§]Since the boundary of \hat{X} is piecewise smooth, we could define the space of the function directly on \hat{X} instead of \mathbb{R}^m as it was done in [Ss].

where $\hat{\nu}$ is the normalized Lebsegue measure on \hat{X} , and we take the space of functions as

$$\mathcal{B} = \left\{ f \in L^1(\widehat{X}, \widehat{\nu}) : |f|_{\mathcal{B}} < \infty \right\},\tag{4.6}$$

and then equip it with the norm

$$\|\cdot\|_{\mathcal{B}} = \|\cdot\|_{L^{1}(\widehat{X},\widehat{\nu})} + |\cdot|_{\mathcal{B}}.$$
(4.7)

Clearly, the space \mathcal{B} does not depend on the choice of ε_0 , though $|\cdot|_{\mathcal{B}}$ does.

Let $s_{ij} = \sup\{\|D\widehat{T}_{ij}^{-1}(x)\| : x \in B_{\varepsilon_0}(Q_0)\}$, and $s_n = \max\{s_{n-1,j} : j = 2, \cdots, K\}$.

Theorem D. Let \hat{X} , \hat{T} and \mathcal{B} be defined as above. Suppose T satisfies Assumption T''(a) to (e). Then there exist $\varepsilon_0 \geq \varepsilon_1 > 0$ such that Assumption B(a) to (f) and conditions S(1) to S(3) are satisfied and $||R_n|| = O(s_n^{\alpha})$. Hence, if $\sum_{k=n+1}^{\infty} s_n^{\alpha} = O(n^{-\beta})$ for some $\beta > 1$, then there exists C > 0 such that for any functions $f \in \mathcal{B}$, $g \in L^{\infty}(X, \nu)$ with supp f, supp $g \subset \hat{X}$, (1.3) holds.

Before giving the proof, we present an example.

Example 4.1. Assume that T satisfies Assumption T''(a) to (d), and near the fixed point p = 0, the map T satisfies

$$T(z) = z(1 + |z|^{\gamma} + O(|z|^{\gamma'})),$$

where $z \in X \subset \mathbb{R}^m$ and $\gamma' > \gamma$.

Denote $z_n = T_1^{-n} z$; we showed in Lemma 3.1 in [HV] that $|z_n| = \frac{1}{(\gamma n)^{1/\gamma}} + Q(-1)$, where $\bar{z}_n < \infty$. Using this fact we can shall that T satisfies also

 $O\left(\frac{1}{n^{1/\bar{\gamma}}}\right)$, where $\bar{\gamma} < \gamma$. Using this fact we can check that T satisfies also Assumption T''(e'); hence, the theorem can be applied.

If the dimension m = 1, then T^n maps the interval $[z_{n+1}, z_n] = [z_{n+1}, T(z_{n+1})]$ to its image $[z_1, z_0]$ bijectively. It follows that $||DT_1^{-n}||$ is roughly proportional to $|z_n|^{1+\gamma}/(|z_0| - |z_1|)$, since the length of the interval $[z_{n+1}, T(z_{n+1})]$ is roughly equal to $|T(z_{n+1}) - z_{n+1}| \sim |z_n|^{1+\gamma}$, see also Lemma 3.1 and Lemma 3.2 in [HV] for a more formal derivation. So $s_n = O\left(\frac{1}{n^{1+1/\gamma}}\right)$ and $\sum_{k=n+1}^{\infty} s_k^{\alpha} = O\left(\frac{1}{n^{1+1/\gamma}}\right)$.

 $O\left(\frac{1}{n^{\frac{\alpha}{\gamma}+\alpha-1}}\right)$. If $\gamma \in (0,1)$ is such that $\alpha(1/\gamma+1) > 1$, the series is convergent.

Also, as stated in Theorem C in the last section, $\sum_{k=n+1}^{\infty} \mu(\tau > k) = O\left(\frac{1}{n^{\frac{1}{\gamma}-1}}\right)$. So if $\alpha(1/\gamma + 1) > 1/\gamma$, the sum involving s_k^{α} decreases faster. We get that the decay rate is given by

$$\Big|\mathrm{Cov}(f,g\circ T^n)\Big|=O\Big(\sum_{k=n+1}^\infty \mu(\tau>k)\Big)=O\Big(\frac{1}{n^{\beta-1}}\Big),$$

for $f \in \mathcal{B}$, $g \in L^{\infty}(X, \nu)$ with supp f, supp $g \subset \widehat{X}$ and with $\beta = \frac{1}{\gamma}$. This gives the same results as in Theorem C for quasi Hölder test functions instead that for functions of bounded variation.

On the other hand, if $m \geq 2$, then T_1^{-n} maps a sphere about the fixed point of radius |z| to a sphere of radius $|z_n|$, if higher order terms are ignored. Hence, DT_1^{-n} contracts vectors in the tangent space of the sphere at the rate of order $|z_n|$. To see the contracting rates along the radial direction, i.e., the direction orthogonal to the tangent space of the spheres, we note that restricted to each ray the map has the form $T(r) = r(1 + r^{\gamma} + O(r^{\gamma'}))$. Hence, by the above arguments for one dimensional case, DT_1^{-n} contracts vectors in the radial direction at the rate of order $|z_n|^{1+\gamma}$. Therefore the norm $||DT_1^{-n}||$ is roughly proportional to $|z_n|$, and $s_n = O\left(\frac{1}{n^{1/\gamma}}\right)$ and $\sum_{k=n+1}^{\infty} s_k^{\alpha} = O\left(\frac{1}{n^{(\alpha/\gamma)-1}}\right)$. If $\gamma \in (0, 1/2)$ is such that $\alpha/\gamma > 1$, the series is convergent. By defining $\beta := \frac{\alpha}{\gamma} - 1$ we can now consider the three cases $\beta > 2$ 1 $\leq \beta \leq 2$ $\beta = 2$ in order to

we can now consider the three cases $\beta > 2, 1 < \beta < 2, \beta = 2$ in order to determine the error term $F_{\beta}(n)$. Let us take, for instance, $\beta > 2$, which requires $\alpha/\gamma > 3$.

Note that $\nu(\tau > n)$ is of the same order as $|z_n|^m$, and therefore $\mu(\tau > n) = O\left(\frac{1}{n^{m/\gamma}}\right)$. It follows that $\sum_{k=n+1}^{\infty} \mu(\tau > k) = O\left(\frac{1}{n^{(m/\gamma)-1}}\right)$. Since the order is higher, by (1.3), we get $\left|\operatorname{Cov}(f, g \circ T^n)\right| \leq C/n^{\beta}$.

4.2 Proof of Theorem D

The proof of Theorem D requires a few preparatory lemmas.

First of all and in order to deduce the spectral properties of $\hat{\mathcal{P}}$ from the Lasota-Yorke inequality, one needs to verify Assumption B on the space of functions \mathcal{B} .

Lemma 4.1. \mathcal{B} is a Banach space satisfying Assuptions B(a) to (f) with $C_a = 2C_b = 2\gamma_m^{-1}\epsilon_0^{-m}$, where γ_m is the volume of the unit ball in \mathbb{R}^m .

Proof. Parts (a), (b) and (c) are stated in Propositions 3.3 and 3.4 in [Ss] with $C_b = \max\{1, \varepsilon^{\alpha}\}/\gamma_m \varepsilon_0^m$ and $C_a = 2\max\{1, \varepsilon^{\alpha}\}/\gamma_m \varepsilon_0^m$. Part (d) follows from the fact that Hölder continuous functions with compact support in \hat{X} are dense in $L^1(\hat{X}, \hat{\nu})$.

Let us now assume $f(u) = \lim_{n \to \infty} f_n(u)$ for $\hat{\nu}$ -a.e. $u \in \mathbb{R}^m$. Take $x \in \mathbb{R}^m$, and $\varepsilon \in (0, \varepsilon_0)$. It is easy to see that for almost every pair of $y, z \in B_{\varepsilon}(x)$, we have

$$|f(y) - f(z)| \le \lim_{n \to \infty} |f_n(y) - f_n(z)| \le \liminf_{n \to \infty} \operatorname{osc}(f_n, B_{\varepsilon}(x)).$$

Hence, $\operatorname{osc}(f, B_{\varepsilon}(x)) \leq \liminf_{n \to \infty} \operatorname{osc}(f_n, B_{\varepsilon}(x))$. By Fatou's lemma, we have

$$\int \operatorname{osc}(f, B_{\varepsilon}(x)) d\hat{\nu} \leq \liminf_{n \to \infty} \int \operatorname{osc}(f_n, B_{\varepsilon}(x)) d\hat{\nu}.$$

This implies $|f|_{\mathcal{B}} \leq \liminf_{n \to \infty} |f_n|_{\mathcal{B}}$. We get part (e).

It leaves to show part (f). For a function $f \in \mathcal{B}$, denote

$$\mathcal{D}_n(f) = \Big\{ x \in \mathbb{R}^m : \liminf_{\varepsilon \to 0} \operatorname{osc}(f, B_\varepsilon(x)) > \frac{1}{n} \Big\}, \quad \mathcal{D}(f) = \bigcup_{n=1}^\infty \mathcal{D}_n(f).$$

Clearly $\mathcal{D}(f)$ is the set of discontinuity points of f. If $\hat{\nu}(\mathcal{D}(f)) > 0$, then there exists N > 0 such that $\operatorname{Leb}(\mathcal{D}_N(f)) > \iota > 0$. Notice that $\mathcal{D}_N(f) = \bigcup_{k \ge 1} S_k$, where $S_k = \bigcap_{n \ge k} \{x : \operatorname{osc}(f, B_{\frac{1}{n}}(x)) > \frac{1}{N}\}$ is an increasing sequence of measurable sets.

For k big enough we still have $\hat{\nu}(S_k) > \iota$ and therefore, for such a k:

$$|f|_{\mathcal{B}} \ge \sup_{\varepsilon > 0} \varepsilon^{-a} \int_{\mathcal{D}_N(f)} \operatorname{osc}(f, B_{\varepsilon}(x)) d\hat{\nu}(x) \ge \sup_{\varepsilon > 0} \varepsilon^{-a} \int_{S_k} \operatorname{osc}(f, B_{\varepsilon}(x)) d\hat{\nu}(x) = \infty$$

This means $f \notin \mathcal{B}$; in other words, any $f \in \mathcal{B}$ satisfies $\hat{\nu}(\mathcal{D}(f)) = 0$.

Take any $f \in \mathcal{B}$ with $f \geq 0$ almost everywhere. If f(x) = 2c > 0 for some $x \notin \mathcal{D}(f)$, then there is $\varepsilon > 0$ such that $\operatorname{osc}(f, B_{\varepsilon}(x)) \leq c$. Hence, $f(x') \geq c > 0$ for almost every point $x' \in B_{\varepsilon}(x)$. So $B_{\varepsilon}(x) \setminus \{f > 0\}$ has Lebesgue measure zero. This implies that $\{f > 0\}$ is almost open and therefore part (f) follows. \Box

Before stating the next lemma, we recall that the space \mathcal{B} depends on the exponent α and the value of the seminorms on ϵ_0 : as we did above, we will not index \mathcal{B} with these two parameters. Moreover all the integrals in the next proof will be performed over \hat{X} .

Lemma 4.2. There exists $\varepsilon_* > 0$ such that for any $\varepsilon_0 \in (0, \varepsilon_*)$, we can find constants $\eta \in (0, 1)$ and $D, \hat{D} > 0$ satisfying

- (i) for any $f \in \mathcal{B}$, $|\widehat{\mathscr{P}}f|_{\mathcal{B}} \leq \eta |f|_{\mathcal{B}} + D ||f||_{L^1(\hat{\nu})};$
- (ii) for any $f \in \mathcal{B}$, $||R(z)f||_{\mathcal{B}} \le |z| (\eta ||f||_{\mathcal{B}} + \hat{D} ||f||_{L^1(\hat{\nu})})$; and
- (iii) for any $\widetilde{f} \in \widetilde{\mathcal{B}}$, $\|\widetilde{\mathscr{P}}\widetilde{f}\|_{\widetilde{\mathcal{B}}} \leq \eta \|\widetilde{f}\|_{\widetilde{\mathcal{B}}} + D\|\widetilde{f}\|_{L^1(\widehat{\nu} \times \rho)}$.

Proof. By Assumption T'' (d), $s^{\alpha} + \lambda < 1$. Therefore if we first choose b small enough, we obtain ζ according to Assumption T''(e), and then we can take ε_0 small enough in order to get

$$\eta := (1 + \zeta \varepsilon_0^{\alpha})(s^{\alpha} + \lambda) + 2\gamma_m^{-1}bK' < 1,$$
(4.8)

where K' is the number of j such that $U_{ij} \neq \emptyset$. Clearly, η is decreasing with ε_0 . Let us define:

$$D := 2\zeta + 2(1 + \zeta \varepsilon_0^{\alpha})\lambda/\varepsilon_0^{\alpha} + 2\gamma_m^{-1}bK' > 0.$$

$$(4.9)$$

For any $x \in \widehat{X}$, let us denote $x_{ij} = \widehat{T}_{ij}^{-1}x$, $\widehat{g}_{ij}(x) = |\det D\widehat{T}_{ij}(x)|^{-1}$ and for $f \in \mathcal{B}$:

$$R_{ij}f = 1_{\widehat{X}} \cdot \mathscr{P}^i(f1_{U_{ij}})(x). \tag{4.10}$$

Clearly,

$$R_{ij}f(x) = f(x_{ij})\hat{g}(x_{ij})\mathbf{1}_{U_{ij}}(x_{ij}).$$
(4.11)

Hence $R_i = \sum_{j=1}^{K} R_{ij}$ and $\widehat{\mathscr{P}} = \sum_{i=0}^{\infty} \sum_{j=1}^{K} R_{ij}$ by definition and the linearity of $\widehat{\mathscr{P}}$. We also define

$$G_{ij}(x,\varepsilon,\varepsilon_0) = 2 \frac{\nu(\widehat{T}_{ij}^{-1}B_{\varepsilon}(\partial \widehat{T}U_{ij}) \cap B_{(1-s)\varepsilon_0}(x))}{\nu(B_{(1-s)\varepsilon_0}(x))}.$$

Clearly, $G(x, \varepsilon, \varepsilon_0) = 2 \sum_{i=0}^{\infty} \sum_{j=1}^{K} G_{ij}(G(x, \varepsilon, \varepsilon_0)).$ For any $\varepsilon \in (0, \varepsilon_0]$, take $N = N(\varepsilon) > 0$ as in Assumption T"(e).

For $i \leq N(\varepsilon)$ and by the proof of Proposition 6.2 in [HV], we know that

$$\operatorname{osc}(R_{ij}f, B_{\varepsilon}(x)) = \operatorname{osc}\left((f\widehat{g}) \circ \widehat{T}_{ij}^{-1} \mathbf{1}_{\widehat{T}U_{ij}}, B_{\varepsilon}(x)\right)$$
$$= \operatorname{osc}\left((f\widehat{g}) \circ \widehat{T}_{ij}^{-1}, B_{\varepsilon}(x)\right) \mathbf{1}_{\widehat{T}U_{ij}}(x) + \left[2 \operatorname{Esup}_{B_{\varepsilon}(x)}(f\widehat{g}) \circ \widehat{T}_{ij}^{-1}\right] \mathbf{1}_{B_{\varepsilon}(\partial\widehat{T}U_{ij})}(x).$$
(4.12)

The computation in that proof also gives

$$\operatorname{osc}(f\widehat{g}, \ \widehat{T}_{ij}^{-1}B_{\varepsilon}(x) \cap U_{ij})$$

$$\leq (1+\zeta\varepsilon^{\alpha})\operatorname{osc}(f, \ B_{s\varepsilon}(x_{ij}) \cap U_{ij})\widehat{g}(x_{ij}) + 2\zeta\varepsilon^{\alpha}|f(x_{ij})|\widehat{g}(x_{ij})$$

Notice that $\operatorname{osc}(f, B_{s\varepsilon}(x_{ij}) \cap U_{ij}) \leq \operatorname{osc}(f, B_{s\varepsilon}(x_{ij}))$. By integrating and using (4.11) we get

$$\int \operatorname{osc} \left((f\hat{g}) \circ \hat{T}_{ij}^{-1}, B_{\varepsilon}(\cdot) \right) \mathbf{1}_{\hat{T}U_{ij}} d\hat{\nu} \leq \int \left[(1 + \zeta \varepsilon^{\alpha}) R_{ij} \operatorname{osc} (f, B_{s\varepsilon}(\cdot)) + 2\zeta \varepsilon^{\alpha} R_{ij} |f| \right] d\hat{\nu}.$$

$$(4.13)$$

On the other hand, by the same arguments as in Section 4 of [Ss], we get

$$\int 2 \left[\operatorname{Esup}_{B_{\varepsilon\varepsilon}(x)}(f\widehat{g}) \circ \widehat{T}_{ij}^{-1} \right] \mathbf{1}_{B_{\varepsilon}(\partial \widehat{T}U_{ij})}(x) d\widehat{\nu}$$

$$\leq 2(1 + \zeta \varepsilon^{\alpha}) \int_{\widehat{X}} G_{ij}(x, \varepsilon, \varepsilon_0) \left[|f|(x) + \operatorname{osc}(f, B_{\varepsilon_0}(x)) \right] d\widehat{\nu}.$$

$$(4.14)$$

Therefore by (4.12), (4.13) and (4.14),

$$|R_{ij}f|_{\mathcal{B}} = \sup_{0<\varepsilon\leq\varepsilon_{0}} \varepsilon^{-\alpha} \int \operatorname{osc}(R_{ij}f, B_{\varepsilon}(\cdot)) d\hat{\nu}$$

$$\leq \sup_{0<\varepsilon\leq\varepsilon_{0}} \varepsilon^{-\alpha} \int \left[(1+\zeta\varepsilon^{\alpha})R_{ij}\operatorname{osc}(f, B_{s\varepsilon}(\cdot)) + 2\zeta\varepsilon^{\alpha}R_{ij}|f| \right] d\hat{\nu}$$

$$+ \sup_{0<\varepsilon\leq\varepsilon_{0}} \varepsilon^{-\alpha} 2(1+\zeta\varepsilon^{\alpha}) \int_{\widehat{X}} G_{ij}(x,\varepsilon,\varepsilon_{0}) \left[|f|(x) + \operatorname{osc}(f, B_{\varepsilon_{0}}(x)) \right] d\hat{\nu}.$$

$$(4.15)$$

For $i > N(\varepsilon)$, by the definition of oscillation we obtain directly that

$$\operatorname{osc}(R_{ij}f, B_{\varepsilon}(x)) \leq 2 \|f\|_{\infty} \sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)} \widehat{g}.$$

Hence, by Assumption B(b) with $C_b = \gamma_m^{-1} \varepsilon_0^{-m}$, we have

$$|R_{ij}f|_{\mathcal{B}} = \sup_{0 < \varepsilon \le \varepsilon_0} \varepsilon^{-\alpha} \int \operatorname{osc}(R_{ij}f, B_{\varepsilon}(\cdot)) d\hat{\nu}$$

$$\leq 2||f||_{\infty} \sup_{0 < \varepsilon \le \varepsilon_0} \varepsilon^{-\alpha} \int \sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)} \widehat{g} d\hat{\nu}$$

$$\leq 2(\gamma_m \varepsilon_0^m)^{-1} (|f|_{\mathcal{B}} + ||f||_1) \sup_{0 < \varepsilon \le \varepsilon_0} \varepsilon^{-\alpha} \int \sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)} \widehat{g} d\hat{\nu}.$$
(4.16)

(i) We first note that for all $0 < \varepsilon \leq \varepsilon_0$,

$$\varepsilon^{-\alpha} \sum_{i=0}^{N(\varepsilon)} \sum_{j=1}^{K} \int R_{ij} \operatorname{osc}(f, B_{s\varepsilon}(\cdot)) d\hat{\nu} \leq \varepsilon^{-\alpha} \int \widehat{\mathscr{P}} \operatorname{osc}(f, B_{s\varepsilon}(\cdot)) d\hat{\nu} \leq s^{\alpha} (s\varepsilon)^{-\alpha} \int \operatorname{osc}(f, B_{s\varepsilon}(\cdot)) d\hat{\nu} \leq s^{\alpha} |f|_{\mathcal{B}},$$

$$\varepsilon^{-\alpha} \sum_{i=0}^{N(\varepsilon)} \sum_{j=1}^{K} \int 2(1+\zeta\varepsilon^{\alpha}) G_{ij}(\cdot, \varepsilon, \varepsilon_{0}) [|f| + \operatorname{osc}(f, B_{\varepsilon_{0}}(\cdot))] d\hat{\nu} \leq \varepsilon^{-\alpha} 2(1+\zeta\varepsilon^{\alpha}) G(\varepsilon, \varepsilon_{0}) \int [|f| + \operatorname{osc}(f, B_{\varepsilon_{0}}(\cdot))] d\hat{\nu}$$

$$\leq (1+\zeta\varepsilon^{\alpha}) \lambda [\varepsilon_{0}^{-\alpha} ||f||_{1} + |f|_{\mathcal{B}}],$$

$$(4.17)$$

where we used (4.2) and (4.3). Also, by Assumption T''(e) and Assumption B(b) with $C_b = \gamma_m^{-1} \varepsilon_0^{-m+\alpha}$, we have that for all $0 < \varepsilon \leq \varepsilon_0$:

$$\varepsilon^{-\alpha} \|f\|_{\infty} \int \sum_{N(\varepsilon)}^{\infty} \sum_{j=1}^{K'} \sup_{\widehat{T}_{ij}^{-1} B_{\varepsilon}(x)} \widehat{g} \, d\hat{\nu} \le \varepsilon^{-\alpha} \|f\|_{\infty} \cdot bK' \varepsilon^{m+\alpha} \le \gamma_m^{-1} bK' \|f\|_{\mathcal{B}}.$$
(4.19)

Since $\widehat{\mathscr{P}}f(x) = \sum_{i=0}^{\infty} \sum_{j=1}^{K} R_{ij}f(x)$, by (4.15) and (4.16), and using (4.17) to (4.19), we obtain that $|\widehat{\mathscr{P}}f|_{\mathcal{B}}$ is bounded by

$$\sup_{0<\varepsilon\leq\varepsilon_{0}}\varepsilon^{-\alpha}\Big[\int\sum_{i=0}^{\infty}\sum_{j=1}^{K}\operatorname{osc}(R_{ij}f,B_{\varepsilon}(x))d\hat{\nu}+\int\sum_{i=0}^{\infty}\sum_{j=1}^{K}\operatorname{osc}(R_{ij}f,B_{\varepsilon}(x))d\hat{\nu}\Big]$$

$$\leq (1+\zeta\varepsilon_{0}^{\alpha})s^{\alpha}|f|_{\mathcal{B}}+2\zeta\|f\|_{1}+(1+\zeta\varepsilon_{0}^{\alpha})\lambda(\varepsilon_{0}^{-\alpha}\|f\|_{1}+|f|_{\mathcal{B}})+2\gamma_{m}^{-1}bK'\|f\|_{\mathcal{B}}$$

$$\leq [(1+\zeta\varepsilon_{0}^{\alpha})(s^{\alpha}+\lambda)+2\gamma_{m}^{-1}bK']|f|_{\mathcal{B}}+[2\zeta+2(1+\zeta\varepsilon_{0}^{\alpha})\lambda/\varepsilon_{0}^{\alpha}+2\gamma_{m}^{-1}bK']\|f\|_{1}.$$

By definition of η in (4.8) and D in (4.9) we get the desired inequality.

(ii) We begin to note that for any real valued function f and $z \in \mathbb{C}$, we have $\operatorname{osc}(zf, B_{\varepsilon}(x)) = |z| \operatorname{osc}(f, B_{\varepsilon}(x))$. Moreover we point out that if $\{a_n\}$ is a sequence of positive numbers and $z \in \overline{\mathbb{D}}$, then $|\sum_{n=1}^{\infty} z^n a_n| \leq |z| \sum_{n=1}^{\infty} a_n$. Hence we have

$$|R(z)f|_{\mathcal{B}} \leq |z| \sup_{0 < \varepsilon \leq \varepsilon_0} \varepsilon^{-\alpha} \sum_{i=0}^{\infty} \sum_{j=1}^{K} \int \operatorname{osc}(R_{ij}f, B_{\varepsilon}(x)) d\hat{\nu} \leq |z| |\widehat{\mathscr{P}}f|_{\mathcal{B}}.$$

By part (i), the inequality becomes

$$|R(z)f|_{\mathcal{B}} \le |z|(\eta|f|_{\mathcal{B}} + D||f||_1).$$

Since $\widehat{\mathscr{P}}$ and R_n are positive operators, we get

$$\|R(z)f\|_{1} \leq \sum_{n=1}^{\infty} \|z^{n}R_{n}f\|_{1} \leq |z| \sum_{n=1}^{\infty} \|R_{n}|f|\|_{1} = |z| \|\widehat{\mathscr{P}}|f|\|_{1} = |z| \|f\|_{1},$$

from which

$$||R(z)f||_{\mathcal{B}} \le |z|(\eta||f||_{\mathcal{B}} + (D+1)||f||_1).$$

We finally get the expected result with $\hat{D} = D + 1$.

(iii) The transfer operator \mathscr{P} has the form (see also [ADSZ])

$$(\widetilde{\mathscr{P}}\widetilde{f})(x,y) = \sum_{n=0}^{\infty} \sum_{j=1}^{K} \widetilde{f}(\widehat{T}_{ij}^{-1}x, S(U_{ij})^{-1}(y)) g(\widehat{T}_{ij}^{-1}x) \mathbf{1}_{\widehat{T}U_{ij}}(x,y),$$

for any $\widetilde{f} \in \widetilde{\mathcal{B}}$, where $S(U_{ij}): Y \to Y$ are automorphisms. Let us denote:

 $(\widetilde{R}_{ij}\widetilde{f})(x,y) = \widetilde{f}(\widehat{T}_{ij}^{-1}x, S(U_{ij})^{-1}(y))g(\widehat{T}_{ij}^{-1}x)1_{\widehat{T}U_{ij}}(x,y).$

Following the same computations as above, we get formulas similar to (4.15) and (4.16) but with R_n and \widehat{T}_{ij} replaced by \widetilde{R}_n and \widetilde{T}_{ij} respectively, and $f(\cdot)$ replaced by $\widetilde{f}(\cdot, y)$. Denote $y_1 = S(U_{ij})^{-1}(y)$; instead of (4.15) and (4.16), we get that for $i < N(\varepsilon)$,

$$\begin{split} |\widetilde{R}_{ij}\widetilde{f}(\cdot,y)|_{\mathcal{B}} &= \sup_{0<\varepsilon\leq\varepsilon_{0}}\varepsilon^{-\alpha}\int \operatorname{osc}(\widetilde{R}_{ij}\widetilde{f}(\cdot,y_{1}),B_{\varepsilon}(\cdot))d\hat{\nu} \\ &\leq \sup_{0<\varepsilon\leq\varepsilon_{0}}\varepsilon^{-\alpha}\int \Big[\Big((1+\zeta\varepsilon^{\alpha})\widetilde{R}_{ij}\operatorname{osc}\big(\widetilde{f}(\cdot,y_{1}),\ B_{s\varepsilon}(\cdot)\big)+2\zeta\varepsilon^{\alpha}\widetilde{R}_{ij}|\widetilde{f}(\cdot,y_{1})|\Big) \\ &+2G_{ij}(x,\varepsilon,\varepsilon_{0})(1+\zeta\varepsilon^{\alpha})\Big(\operatorname{osc}(\widetilde{f}(\cdot,y_{1}),B_{\varepsilon}(\cdot))+|\widetilde{f}(\cdot,y_{1})|\Big)\Big]d\hat{\nu}, \end{split}$$

and for $i \geq N(\varepsilon)$,

$$\begin{split} |\widetilde{R}_{ij}\widetilde{f}(\cdot,y)|_{\mathcal{B}} &= \sup_{0<\varepsilon\leq\varepsilon_0} \varepsilon^{-\alpha} \int \operatorname{osc}(\widetilde{R}_{ij}\widetilde{f}(\cdot,y_1),B_{\varepsilon}(\cdot))d\hat{\nu} \\ &\leq 2(\gamma_m\varepsilon_0^m)^{-1}(|\widetilde{f}(\cdot,y_1)|_{\mathcal{B}} + \|(\widetilde{f}\cdot,y_1)\|_{L^1(\nu)})\varepsilon^{-\alpha}\sup_{0<\varepsilon\leq\varepsilon_0}\int \sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)}\widehat{g}d\hat{\nu}. \end{split}$$

We observe that for any $x, S(U_{ij}): Y \to Y$ preserves the measure ρ ; we set

$$\bar{f}(x) = \int_{\mathbb{S}} \tilde{f}(x, y_1) d\rho(y), \quad \overline{\operatorname{osc}}\big(\tilde{f}(\cdot), B_{\varepsilon}(\cdot)\big) = \int_{\mathbb{S}} \operatorname{osc}\big(\tilde{f}(\cdot, y_1), B_{\varepsilon}(\cdot)\big) d\rho(y).$$

By integrating with respect to y, and using Fubini's theorem, we get

$$\begin{split} |\widetilde{R}_{ij}\widetilde{f}|_{\widetilde{\mathcal{B}}} &\leq \sup_{0<\varepsilon\leq\varepsilon_0} \varepsilon^{-\alpha} \int \Big[\Big((1+\zeta\varepsilon^{\alpha})\widetilde{R}_{ij}\overline{\operatorname{osc}}\big(\widetilde{f}(\cdot), \ B_{s\varepsilon}(\cdot)\big) + 2\zeta\varepsilon^{\alpha}\widetilde{R}_{ij}|\overline{f}(\cdot)| \Big) \\ &+ 2G_{ij}(x_{ij},\varepsilon,\varepsilon_0)(1+\zeta\varepsilon^{\alpha}) \Big(\overline{\operatorname{osc}}\big(\widetilde{f}(\cdot), B_{\varepsilon}(\cdot)\big) + |\overline{f}(\cdot)| \Big) \Big] d\hat{\nu} \end{split}$$

and

$$|\widetilde{R}_{ij}\widetilde{f}|_{\widetilde{\mathcal{B}}} \leq 2(\gamma_m \varepsilon_0^m)^{-1} (|\widetilde{f}|_{\widetilde{\mathcal{B}}} + \|\widetilde{f}\|_{L^1(\hat{\nu} \times \rho)}) \varepsilon^{-\alpha} \sup_{0 < \varepsilon \leq \varepsilon_0} \int \sup_{\widehat{T}_{ij}^{-1} B_{\varepsilon}(x)} \widehat{g} d\hat{\nu}.$$

Using Fubini's theorem again, we also have $|\tilde{f}|_{\tilde{\mathcal{B}}} = \sup_{0 < \varepsilon \leq \varepsilon_0} \varepsilon^{-\alpha} \int \overline{\operatorname{osc}}(\tilde{f}(\cdot), B_{\varepsilon}(\cdot)) d\hat{\nu},$ and $|\tilde{f}|_{L^1(\hat{\nu}\times\rho)} = \int |\bar{f}(\cdot)| d\hat{\nu}$. Using the same arguments as in the proof of part (i) we get

$$\begin{split} |\widetilde{P}\widetilde{f}(\cdot,y)|_{\widetilde{\mathcal{B}}} &\leq \sum_{n=0}^{\infty} \sum_{j=1}^{K} |\widetilde{R}_{ij}\widetilde{f}|_{\widetilde{\mathcal{B}}} \leq (1+\zeta\varepsilon_{0}^{\alpha})s^{\alpha}|\widetilde{f}|_{\widetilde{\mathcal{B}}} + 2\zeta \|\widetilde{f}\|_{L^{1}(\hat{\nu}\times\rho)} \\ &+ (1+\zeta\varepsilon_{0}^{\alpha})\lambda \left(|\widetilde{f}|_{\widetilde{\mathcal{B}}} + \varepsilon_{0}^{-\alpha}\|\widetilde{f}\|_{L^{1}(\hat{\nu}\times\rho)}\right) + 2\gamma_{m}^{-1}bK' \left(|\widetilde{f}|_{\widetilde{\mathcal{B}}} + \|\widetilde{f}\|_{L^{1}(\hat{\nu}\times\rho)}\right), \end{split}$$

and therefore the result of part (iii) with the same η and D given in (4.8) and (4.9) respectively.

Lemma 4.3. There exists a constant $C_R > 0$ such that $||R_n||_{\mathcal{B}} \leq C_R s_n^{\alpha}$ for all n > 0.

Proof. Since $R_i = \sum_j R_{ij}$, we only need to prove the results for R_{ij} . Let us take $\varepsilon \in (0, \varepsilon_0]$, choose any b > 0 and let $N(\varepsilon)$ be given by Assumption T''(e).

We first consider the case $n = i + 1 \leq N(\varepsilon)$.

By the definition of R_{ij} given in (4.10), we have for any $f \in \mathcal{B}$,

$$\int R_{ij} f d\hat{\nu} = \int \mathbf{1}_{\widehat{X}} \cdot \mathscr{P}^{i+1}(f \mathbf{1}_{U_{ij}}) d\hat{\nu} = \int_{\widehat{X}} f \mathbf{1}_{U_{ij}} d\hat{\nu} = \int_{U_{ij}} f d\hat{\nu}.$$
(4.20)

We now denote $d_{ij} = \sup \{ |\det D\widehat{T}_{ij}^{-1}(x)| : x \in B_{\varepsilon}(Q_0) \}$. Since for any x, $|\det D\widehat{T}_{ij}^{-1}(x)| \leq ||D\widehat{T}_{ij}^{-1}(x)||$, we have $d_{ij} \leq s_{ij}$. Since $\widehat{T}U_{ij} = Q_0$,

$$\nu(U_{ij}) \le d_{ij}\nu(Q_0) \le s_{ij}\nu(Q_0).$$
(4.21)

Hence by Assumption B(b),

$$\int R_{ij} f d\hat{\nu} \le \|f\|_{L^{\infty}(\hat{\nu})} \nu(U_{ij}) \le C_b \nu(Q_0) s_{ij} \|f\|_{\mathcal{B}}.$$
(4.22)

By similar arguments as for (4.20), we have

$$\int_{\widehat{X}} R_{ij} \operatorname{osc}(f, \ B_{s_{ij}\varepsilon}(\cdot)) d\hat{\nu} \le \int_{\widehat{X}} \operatorname{osc}(f, \ B_{s_{ij}\varepsilon}(\cdot)) \mathbf{1}_{U_{ij}} d\hat{\nu} \le s_{ij}^{\alpha} \varepsilon^{\alpha} |f|_{\mathcal{B}}.$$
 (4.23)

We note that for each j, $\widehat{T}U_{ij} = Q_0$ and the "thickness" of $\widehat{T}_{ij}^{-1}B_{\varepsilon}(\partial Q_0)$ is of order $s_{ij}\varepsilon$, since ∂Q_0 consists of piecewise smooth surfaces. So $G_{ij}(\varepsilon,\varepsilon_0) \leq$ $C_G \varepsilon s_{ij}$ for some C_G independent of i and j. Therefore we have

$$\int_{\widehat{X}} \varepsilon^{-\alpha} 2(1+\zeta\varepsilon^{\alpha}) G_{ij}(\cdot,\varepsilon,\varepsilon_0) \big[|f| + \operatorname{osc}(f,B_{\varepsilon_0}(\cdot)) \big] d\widehat{\nu}$$

$$\leq 2(1+\zeta\varepsilon^{\alpha}) C_G \varepsilon^{1-\alpha} s_{ij} \big[||f||_{L^1(\widehat{\nu})} + \varepsilon_0^{\alpha} |f|_{\mathcal{B}} \big].$$

Hence by (4.15) we get that

$$|R_{ij}f|_{\mathcal{B}} \le C'_R s^{\alpha}_{ij} \big[\|f\|_{L^1(\hat{\nu})} + |f|_{\mathcal{B}} \big] = C'_R s^{\alpha}_{ij} \|f\|_{\mathcal{B}}$$
(4.24)

for $C'_R = (1 + \zeta \varepsilon_0^{\alpha})(1 + 2C_G \varepsilon_0^{1-\alpha}) + 2\zeta C_b \hat{\nu}(Q_0).$ We now consider the case $n = i+1 > N(\varepsilon)$. As we mentioned in Remark 4.7, in this case $m \ge 2$. By definition, there is $C_s > 0$ such that $\hat{g}(x_{ij}) \le C_s^2 s_{ij}^2$ for any $x_{ij} \in \widehat{T}_{ij}^{-1}B_{\varepsilon}(Q_0)$ with $j = 2, \dots, K$. By Assumption T''(e) we know that for any $x \in B_{\varepsilon}(Q_0)$,

$$\left(\sup_{\widehat{T}_{i,j}^{-1}B_{\varepsilon}(x)}\widehat{g}\right)^{1/2} \leq \left(\sum_{\ell=N(\varepsilon)}^{\infty}\sup_{\widehat{T}_{\ell j}^{-1}B_{\varepsilon}(x)}\widehat{g}\right)^{1/2} \leq \sqrt{b}\varepsilon^{(m+\alpha)/2} \leq \sqrt{b}\varepsilon^{\alpha}.$$

Therefore we obtain

$$\sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)}\widehat{g} = (\sup_{\widehat{T}_{ij}^{-1}B_{\varepsilon}(x)}\widehat{g})^{1/2} (\sup_{\widehat{T}_{i,j}^{-1}B_{\varepsilon}(x)}\widehat{g})^{1/2} \le C_s s_{ij}\sqrt{b}\varepsilon^{\alpha}$$

and substitute in (4.16) to get $(\alpha \leq 1)$:

$$|R_{ij}f|_{\mathcal{B}} \le C_R'' s_{ij} ||f||_{\mathcal{B}} \le C_R'' s_{ij}^{\alpha} ||f||_{\mathcal{B}}$$

for $C_R'' = 2(\gamma_m \varepsilon_0^m)^{-1} \sqrt{b} C_s$. Finally, by (4.22), we have

$$||R_{ij}f||_1 \le \int R_{ij}|f|d\hat{\nu} \le C_b\nu(Q_0)s_{ij}||f||_{\mathcal{B}}.$$

Thus we have $||R_{ij}f||_{\mathcal{B}} = (C'_R + C''_R + C_b\nu(Q_0))s^{\alpha}_{ij}||f||_{\mathcal{B}}$, which implies the result of the lemma. We are finally ready to give the proof of Theorem D.

Proof of Theorem D. We first choose $\varepsilon_0 > 0$ as in Lemma 4.2, and define \mathcal{B} correspondingly by using that ε_0 . By Proposition 3.3 in [Ss], \mathcal{B} is complete and hence is a Banach space. Then Assumption B(a) to (f) follow from Lemma 4.1.

By Lemma 4.2 we know that conditions (S1) is satisfied. Assumption T''(a), (d) and (c) imply Assumption T (a), (c) and (d) respectively. Assumption T(b) is implied by the construction of the first return map. Lemma 4.2(iii) gives (1.5). Therefore all conditions for Theorem B are satisfied; hence we obtain conditions (S2) and (S3). The fact that $||R_n|| = O(s_n^{\alpha})$ follows from Lemma 4.3.

5 Multidimensional spaces: the role of the determinant in getting an optimal bound

In this section we put additional conditions on the map T that we studied in the previous chapter in order to get optimal estimates for the decay of correlations for observable supported in \tilde{X} . As we anticipated in the Introduction, if $||R_n||$ decreases, in some norm, as $|\det DT^{-n}|$, then it usually has the same order as $\mu(\tau = n)$, which approaches to 0 faster than $\mu(\tau > n)$. Since $\sum_{k \ge n} \mu(\tau > k)$ gives the optimal decay rates of correlations and $\sum_{k \ge n} ||R_k||$ determines the order of the error terms $F_{\beta}(n)$, we can get lower estimates for decay rates.

5.1 Assumptions and statement of the results.

Let us suppose that T satisfies Assumption T''(a), (d) and (e) in the last section. We replace part (b) and (c) by the following

- **Assumption T''.** (b') (Fixed point and a neighborhood) There is a fixed point $p \in U_1$ and a neighborhood V of p such that $T^{-n}(V) \cap \partial U_j = \emptyset$ for any $j = 1, \ldots, K$ and for any $n \ge 0$.
- (c') (Topological exactness) $T: X \to X$ is topologically exact, that is, for any $x \in X, \varepsilon > 0$, there is an $\widetilde{N} = \widetilde{N}(x, \varepsilon) > 0$ such that $T^{\widetilde{N}}B_{\varepsilon}(x) = X$.

Remark 5.1. Clearly maps with a Markov partition, even countable, satisfy Assumption T''(b') provided the neutral fixed point is in the interior of a partition element. In Exercise 5.5 we will introduce a class of non-Markov maps that satisfy T''(b') as well.

Remark 5.2. Assumption T'(b') will allow us to get a better estimate for $||R_n||_{\mathcal{B}}$ which in turn will give us optimal bounds. To understand the difference with the results of Section 4, we recall that there, starting from (4.23), we got the estimate in (4.24) $|R_{ij}f|_{\mathcal{B}} \leq C'_R s^{\alpha}_{ij} ||f||_{\mathcal{B}}$ for some constant $C'_R > 0$, and hence $||R_{ij}f||_{\mathcal{B}}$ decreases as the speed of s^{α}_{ij} does. This was precisely the statement of Lemma 4.3, where s_{ij} was given by the norm $||D\widehat{T}^{-1}_{ij}||$ of the derivatives. With

Assumption T'(b') and by considering a different and smaller Banach space we can get the new estimates (5.10), which lead to the upper bound $|R_{ij}f|_{\mathcal{Q}} \leq C'_2 d_{ij} ||f||_{\mathcal{B}}$ in (5.12), where d_{ij} is given by the determinant $|\det D\widehat{T}_{ij}^{-1}|$. On the other hand, estimates of the norm $|R_{ij}f|_{\mathcal{H}}$ can be obtained and decrease with the same order. Other explications and details will be given in the proof.

Since we want to reserve the symbol \mathcal{B} for the functional space upon which we want to get the renewal type results leading to the bounds on the decay of correlations, we begin to rename the seminorm and the Banach space defined in (4.6) and (4.7) with \mathcal{Q} , instead of \mathcal{B} . We remind that such a seminorm will depend on α and on ϵ_0 , the latter dependence affecting only the value of the seminorms. Then (4.7) will be now written as:

$$||f||_{\mathcal{Q}} = ||f||_{L^1(\hat{\nu})} + |f|_{\mathcal{Q}}.$$

Recall that V is a neighborhood of p given in Assumption T"(b'). We denote the preimages $T_{i_k}^{-1} \dots T_{i_1}^{-1} V$ by $V_{i_1 \dots i_k}$ or V_I where $I = i_1 \dots i_k$. We also denote with \mathcal{I} the set of all possible words $i_1 \dots i_k$ such that $T_{i_k}^{-1} \dots T_{i_1}^{-1} V$ is well defined, where $i_k \in \{1, \dots, K\}$ and k > 0.

For an open set O, let $\mathcal{H} := \mathcal{H}_{\varepsilon_1}^{\alpha} = \mathcal{H}_{\varepsilon_1}^{\alpha}(O, H)$ be the set of Hölder functions f on O that satisfy $|f(x) - f(y)| \leq Hd(x, y)^{\alpha}$ for any $x, y \in O$ with $d(x, y) \leq \varepsilon_1$.

Let \hat{h} be a fixed point of the transfer operator $\widehat{\mathscr{P}}$, which will be unique under the assumptions of the theorem below. We now define \mathcal{B} by

$$\mathcal{B} := \mathcal{B}^{\alpha}_{\varepsilon_{0},\varepsilon_{1}} = \left\{ f \in \mathcal{Q} : \exists H > 0 \ s.t. \ (f/\hat{h})|_{V_{I}} \in \mathcal{H}^{\alpha}_{\varepsilon_{1}}(V_{I},H) \ \forall I \in \mathcal{I} \right\},$$
(5.1)

and for any $f \in \mathcal{B}$, let

$$|f|_{\mathcal{H}} := |f|_{\mathcal{H}_{\varepsilon_1}^{\alpha}} = \inf\{H : (f/\hat{h})|_{V_I} \in \mathcal{H}_{\varepsilon_1}^{\alpha}(V_I, H) \ \forall I \in \mathcal{I}\}.$$

Sublemma 5.3 and 5.4 below imply that $\hat{h} > 0$ on all V_I , and therefore the definition makes sense. Then we take $|\cdot|_{\mathcal{Q}} + |\cdot|_{\mathcal{H}}$ as a seminorm for $f \in \mathcal{B}$ and define the norm in \mathcal{B} by

$$\|\cdot\|_{\mathcal{B}} = \|\cdot\|_{1} + |\cdot|_{\mathcal{Q}} + |\cdot|_{\mathcal{H}}.$$
(5.2)

Clearly, $\mathcal{B} \subset \mathcal{Q}$ and $||f||_{\mathcal{B}} \ge ||f||_{\mathcal{Q}}$ if $f \in \mathcal{B}$.

We now remind that for any sequences of numbers $\{a_n\}$ and $\{b_n\}$, we use $a_n \sim b_n$ if $\lim_{n \to \infty} a_n/b_n = 1$, and $a_n \approx b_n$ if $c_1b_n \leq a_n \leq c_2b_n$ for some constants $c_2 \geq c_1 > 0$.

Let $d_{ij} = \sup\{|\det D\widehat{T}_{ij}^{-1}(x)| : x \in B_{\varepsilon_0}(Q_0)\}, \text{ and } d_n = \max\{d_{n-1,j} : j = 2, \cdots, K\}.$

Theorem E. Let \hat{X} , \hat{T} and \mathcal{B} be defined as above and suppose that T satisfies Assumption T''(a), (b'), (c'), (d) and (e). Then there exist $\varepsilon_0 \geq \varepsilon_1 > 0$

such that Assumption B(a) to (f) and conditions S(1) to S(4) are satisfied and $||R_n||_{\mathcal{B}} = O(d_n^{m/(m+\alpha)})$. Hence, if $\sum_{k=n+1}^{\infty} d_n^{m/(m+\alpha)} = O(n^{-\beta})$ for some $\beta > 1$, then there exists C > 0 such that for any functions $f \in \mathcal{B}$, $g \in L^{\infty}(X, \nu)$ with supp f, supp $g \subset \hat{X}$, (1.3) holds.

Moreover, if T satisfies (4.4) near p = 0, then $\sum_{k=n+1}^{\infty} \mu(\tau > k) \approx n^{-(\frac{m}{\gamma}-1)}$. In this case, if $d_n = O(n^{-\beta'})$ for some $\beta' > 1$ and if

$$\beta = \beta' \cdot \frac{m}{m+\alpha} - 1 > \max\{2, \frac{m}{\gamma} - 1\},\tag{5.3}$$

then

$$\operatorname{Cov}(f, g \circ T^n) \sim \sum_{k=n+1}^{\infty} \mu(\tau > k) \int f d\mu \int g d\mu \approx \frac{1}{n^{\frac{m}{\gamma}-1}}.$$
 (5.4)

In particular, if Assumption T''(e') in Section 4.1 stating bounded distortion also holds, then the above statements remain true if we replace $m/(m + \alpha)$ in (5.3) by 1.

Remark 5.3. Whenever T satisfies (4.4) near p, Assumption T''(c') implies that h is bounded away from 0 on the sets $\{\tau > n\}$; hence $\mu(\tau > n)$ and $\nu(\tau > n)$ have the same order and $\sum_{k=n+1}^{\infty} \mu(\tau > k) \approx n^{-(\frac{m}{\gamma}-1)}$. This is the case in Example 5.1, 5.2 and 5.4 below.

On the other hand, if Assumption T''(c') only holds for an invariant subset of X like in Example 5.3, then \hat{h} may be only supported on a part of the set $\{\tau > n\}$, and therefore $\mu(\tau > n)$ may decrease faster. In this case, $\sum_{k=n+1}^{\infty} \mu(\tau > k) = o(n^{-(\frac{m}{\gamma}-1)})$.

5.2 Examples

Before giving the proof, we present a few examples. The first four examples concern various decay rates, where we will always assume that T satisfies Assumption T''(a), (b'), (c') and (d). Example 5.5 and thereinafter are for maps satisfying Assumption T''(b').

Example 5.1. Let us assume m = 3, and near the fixed point p = (0, 0, 0), the map T has the form

$$T(w) = \left(x(1+|w|^2 + O(|w|^3)), \ y(1+|w|^2 + O(|w|^3)), \ z(1+2|w|^2 + O(|w|^3))\right)$$

where $w = (x, y, z)$ and $|w| = \sqrt{x^2 + y^2 + z^2}$.

This map is very similar to that studied in Example 1 in [HV], although it is now in a three dimensional space. We can still use the same arguments to show that Assumption T'' (e) is satisfied.

We set $w_n = T_1^{-n}w$; clearly, $|w| + |w|^3 + O(|w|^4) \le |T(w)| \le |w| + 2|w|^3 + O(|w|^4)$. By standard arguments we know that

$$\frac{1}{\sqrt{4n}} + O\left(\frac{1}{\sqrt{n^3}}\right) \le |w_n| \le \frac{1}{\sqrt{2n}} + O\left(\frac{1}{\sqrt{n^3}}\right)$$

(see also Lemma 3.1 in [HV]). Since we are in a three dimensional space, we now have $\nu(\tau > k) \approx \frac{1}{k^{m/\gamma}} = \frac{1}{k^{3/2}}$, and therefore $\sum_{k=n+1}^{\infty} \nu(\tau > k) \approx \frac{1}{n^{1/2}}$. It is easy to see that det $DT(w) = 1 + 6x^2 + 6y^2 + 8z^2 + O(|w|^3)$. So we have $|\det DT_1^{-1}(w)| \le 1 - 6|w|^2 + O(|w|^3)$. By Lemma 3.2 in [HV] with $r(t) = 1 + 6x^2 + 6y^2 + 8z^2$

It is easy to see that det $DT(w) = 1 + 6x^2 + 6y^2 + 8z^2 + O(|w|^3)$. So we have $|\det DT_1^{-1}(w)| \le 1 - 6|w|^2 + O(|w|^3)$. By Lemma 3.2 in [HV] with $r(t) = 1 - 6t^2 + O(t^3)$, $\gamma = 2$, C' = 6 and C = 1, we get that $|\det DT_1^{-n}(x)| = O(1/n^3)$. Hence we have $\beta' = 3$ and $\beta = 3m/(m+\alpha) - 1 > 5/4$. Since $m/\gamma - 1 = 1/2$, (5.3) holds, and therefore we have (5.4) with the decay rate of order $1/n^{\frac{1}{2}}$; contrarily to Example 4.1, we now got an optimal bound.

Example 5.2. Assume m = 2, and near the fixed point p = (0,0), the map T has the form

$$T(z) = \left(x(1+|z|^{\gamma} + O(|z|^{\gamma'})), \ y(1+2|z|^{\gamma} + O(|z|^{\gamma'})) \right)$$

where $z = (x, y), |z| = \sqrt{x^2 + y^2}, \gamma \in (0, 1)$ and $\gamma' > \gamma$.

By methods similar to Example 1 in [HV] we can check that Assumption T" (e) is satisfied. Denote $z_n = T_1^{-n}z$. Since $|z| + |z|^{1+\gamma} + O(|z|^{\gamma'}) \leq |T(z)| \leq |z| + 2|z|^{\gamma+1} + O(|z|^{\gamma'})$, we have

$$\frac{1}{(2\gamma n)^{1/\gamma}} + O\left(\frac{1}{n^{\delta}}\right) \le |z_n| \le \frac{1}{(\gamma n)^{1/\gamma}} + O\left(\frac{1}{n^{\delta}}\right)$$

for some $\delta > 1/\gamma$. So $\nu(\tau > k) \approx \frac{1}{k^{2/\gamma}}$, and therefore $\sum_{k=n+1}^{\infty} \nu(\tau > k) \approx \frac{1}{n^{\frac{2}{\gamma}-1}}$. It is possible to show that $|\det DT(z)| = 1 + \frac{(3+\gamma)x^2 + (3+2\gamma)y^2}{|z|^{2-\gamma}} +$

 $O(|z|^{\gamma'})$. Therefore $|\det DT_1^{-1}(z)| \le 1 - (3+\gamma)|z|^{\gamma} + O(|z|^{\gamma'})$, and $|\det DT_1^{-n}(z)| = O(1/n^{1+3/\gamma})$. Hence $\beta' = 1 + \gamma/3$ and $\beta = (1 + 3/\gamma) \cdot 2/(2 + \alpha) - 1 > 2/\gamma - 1$. Therefore (5.3) holds, and the decay rates is of order $1/n^{\frac{2}{\gamma}-1}$.

Example 5.3. Assume m = 2, and take the same map as in Example 1 in [HV], namely, near the fixed point p = (0,0), the map T has the form

$$T(x,y) = \left(x(1+x^2+y^2), \ y(1+x^2+y^2)^2\right).$$

The map allows an infinite absolutely continuous invariant measure. However, it can be arranged in such a way that there is an invariant component that supports a finite absolutely continuous invariant measure μ . Near the fixed point, the region supporting this component has the form

$$\{z = (x, y) : |y| < x^2\}$$

We may regard X as this component, and $T: X \to X$ satisfies the assumptions.

We can check that the map has bounded distortion near the fixed point restricted to this region. Hence, the map verifies Assumption T''(e').

Since $|z_n| = O(1/\sqrt{n})$ and for $z = (x, y), |y| \le x^2$, we get $\nu(\tau > k) \approx \frac{1}{k^{3/2}}$,

and $\sum_{k=n+1}^{\infty} \nu(\tau > k) \approx \frac{1}{n^{1/2}}.$

On the other hand, $|\det DT(z)| = 1 + 5x^2 + 7y^2 + O(|z|^4)$. Since $|y| \le x^2$, $|z| = |x| + O(|z|^2)$; thus $|\det DT(z)| = 1 + 5|z|^2 + O(|z|^4)$, and therefore $|\det DT_1^{-n}(z)| = O(1/n^{5/2})$. So $\beta' = 5/2$ and $\beta = 3/2$. We obtain that the decay rate is of order $1/n^{1/2}$.

Example 5.4. Assume $m \ge 3$ and near the fixed point p = (0, 0, 0), the map T has the form

$$T(z) = z (1 + |z|^{\gamma} + O(|z|^{\gamma+1})),$$

where $m > \gamma > 0$.

These examples are comparable with those in Example 4.1, except for the stronger topological assumptions which we now put on the maps. We know that those maps satisfy Assumption, T''(e').

We set $z_n = T_1^{-n}z$, then we have $|z_n| = 1/(n\gamma)^{1/\gamma} + O(1/(n\gamma)^{\frac{1}{\gamma}+1})$ and $|\det DT(z)| = 1 + (m+\gamma)|z|^{\gamma} + O(|z|^{\gamma+1})$. Hence, we get that $|\det DT_1^{-n}| \approx 1/n^{\frac{m}{\gamma}+1}$, (for the relative computations see Lemma 3.1 and 3.2 in [HV]). Therefore $\beta' = \frac{m}{\gamma} + 1$ and $\beta = m/\gamma$.

On the other hand, we see that $\nu(\tau > k) = O(1/k^{m/\gamma})$, and then $\sum_{k=n+1}^{\infty} \nu(\tau > k)$

 $k) \approx \frac{1}{n^{\frac{m}{\gamma}-1}}$. Since $m > \gamma$, the invariant measure μ is finite and $\beta > 1$. We get that the decay rate is of order $1/n^{\frac{m}{\gamma}-1}$.

Example 5.5. Let us take X = [-100, 100] and a partition $\xi = \{U_0, U_i^+, U_i^- : i = 1, ..., 9\}$ of X into 19 subintervals such that $U_0 = [-10, 10], U_i^- = [-10i - 10, -10i)$ and $U_i^+ = (10i, 10i + 10]$. Also set $\partial \xi = \bigcup_{U \in \xi} \partial U$.

We then define a piecewise smooth expanding map $T : X \to X$ with an indifferent fixed point p = 0 as following:

- (i) $T(\operatorname{int} U_i^{\pm}) = \operatorname{int} X$ for $i \neq -8, 8$ and $|T_i'(x)| \ge 10$ for all $x \notin [-3, 3] \cup \partial \xi$;
- (ii) $T(x) = x + 4|x|^{1.5}$ for $x \in [-3, 3]$;

- (iii) T is increasing on U_9^{\pm} and maps int U_9^{\pm} to int X linearly, that is, T(x) = 20(x-95) on U_9^{+} and T(x) = 20(x+95) on U_9^{-} ;
- (iv) $T(U_8^-) = [-100, e_+)$ and $T(U_8^+) = (e_-, 100]$, where $e_{\pm} \in E_{\pm}$, and $E_{\pm} = \{x \in U_9^{\pm} : T^n(x) \in U_9^+ \cup U_9^- \ \forall n \ge 0\}.$

It is clear that T satisfies Assumption T''(a), (b), (c'), (d) and (e'); moreover (iv) above shows that the partition ξ is not Markov. By the choice of E_{\pm} , the orbits $\{T^n(e_{\pm}) : n > 0\}$ are contained in $E_{+} \cap E_{-}$, and therefore in $U_{9}^{+} \cup U_{9}^{-}$. Note that all possible image sets $\{T^n(U) : U \in \bigvee_{i=0}^{n-1}T^{-i}(\xi)\}$ have the form [-100, 100], $[-100, T^n(e_{\pm})]$, $[T^n(e_{\pm}), 100]$ or $[T^n(e_{\pm}), T^n(e_{\mp})]$ up to the endpoints. So if we take V = [-2, 2], then $V \cap T^k(\partial U) = \emptyset$ for any $U \in \xi$ and $k \geq 0$. It follows that $T^{-k}(V) \cap \partial U = \emptyset$ for any $U \in \xi$ and $k \geq 0$. Hence, Assumption T''(b') holds.

Remark 5.4. We mention here that $T|_{U_9^{\pm}}$ do not have to be linear. Also, the role of U_8^{\pm} and U_9^{\pm} can be replaced by any pairs U_i^{\pm} and U_j^{\pm} for $i, j \neq 0$ and $i \neq j$.

The same idea can be used to generate example of maps in higher dimensional spaces. For example, in the plane we can take $X = [-100, 100] \times [-100, 100]$, and partition X in to squares $U_{ij}^{\pm\pm}$ of size 10×10 , except for $U_0 = [-10, 10] \times [-10, 10]$. Near the origin we can define $T(x, y) = (x(1 + x^2 + y^2), y(1 + x^2 + y^2)^2)$ as in Example 5.3. Then we let $U_{i,9}^{\pm\pm}$ and $U_{i,8}^{\pm\pm}$, or $U_{9,j}^{\pm\pm}$ and $U_{8,j}^{\pm\pm}$, or both, where $i, j = \pm 0, \pm 1, \dots \pm 9$, will play the same role as U_9^{\pm} and U_8^{\pm} in the above example. That is, the map can be arranged in such a way that under T^n the images of the boundaries of all sets in the partition are contained in the region $\{(x, y) \in X : 90 \le |y| \le 100\}$ or $\{(x, y) \in X : 90 \le |x| \le 100\}$, or both. By this way, we can construct a map T that satisfies all conditions given by Assumption T''(a), (b'), (c'), (d) and (e).

In fact, systems satisfying Assumption T''(a), (b'), (c'), and (d) are dense in the set of the systems satisfying Assumption T''(a), (b), (c') and (d) in the C^1 topology. This means that for any system satisfying Assumption T''(a), (b), (c') and (d), we can make an arbitrarily small C^1 perturbation to get a map \overline{T} such that there exists a small neighborhood V of p with $\overline{T}^{-n}(V) \cap \partial U_j = \emptyset$ for any $j = 1, \ldots, K$ and for any $n \ge 0$. To see this, we first note that for any fixed n_0 , we can get that $\overline{T}^{-n}(p) \cap \partial U_j = \emptyset$ for any $0 < n \le n_0$ by using a small perturbation, and then get that $\overline{T}^{-n}V \cap \partial U_j = \emptyset$ for any $0 < n \le n_0$ by taking Vsmall enough. Further, for any connected component $V_i^{(n)}$ of $\overline{T}^{-n}V$, we require that $d(V_i^{(n)}, \partial U_j) \ge \dim V_i^{(n)}$ for any $j = 1, \ldots, K$. Now we consider the case $n > n_0$. If $V_i^{(n)} \cap \partial U_j \neq \emptyset$, then we can use a small perturbation $\phi_i^{(n)}$ with both $d(\phi_i^{(n)}, \mathrm{id})$ and $\|D\phi_i^{(n)}\|$ small enough to get $d(V_i^{(n)}, \partial U_j) \ge \dim V_i^{(n_2)}$. Notice that Assumption $T''(\mathrm{d})$ implies s < 1/4. It is easy to see that if $V_{i_2}^{(n_2)}$ intersects the $(2 \operatorname{diam} V_{i_1}^{(n_1)})$ -neighborhood of some $V_{i_1}^{(n_1)}$ with $n_2 > n_1$, then diam $V_{i_2}^{(n_2)} < (1/4) \operatorname{diam} V_{i_1}^{(n_1)}$. Hence, we can require $d(\phi_i^{(n)}, \operatorname{id})$ and $\|D\phi_i^{(n)}\|$ decrease with n at least by a fact 1/4 at each step. Then after a sequence of perturbations we still have $d(V_i^{(n)}, \partial U_j) \ge (1/2) \operatorname{diam} V_i^{(n)}$ for any n > 0 and the C^1 norm of the composition of the sequence of perturbations are still small. Hence the resulting map \overline{T} satisfies Assumption T''(b'), and obviously satisfies Assumption T''(a), (c'), and (d) as well. We leave the details to the reader.

5.3 Proof of Theorem E

Proof of Theorem E. We begin to choose $\varepsilon_0 > 0$ satisfying Lemma 4.2 in the previous section, and then we take $\varepsilon_1 \in (0, \varepsilon_0]$ as in Lemma 5.2 below. We reduce ε_1 further if necessary such that $\eta' := \eta + D_{\mathcal{H}}(\varepsilon_0)\varepsilon_1^{\alpha} < 1$, where $\eta < 1$ is given in Lemma 4.2 and $D_{\mathcal{H}}(\varepsilon_0) > 0$ is given in Lemma 5.2. Then we take $\mathcal{B} := \mathcal{B}^{\alpha}_{\varepsilon_0,\varepsilon_1}$ as in (5.1); with the norm given in (5.2), \mathcal{B} satisfies Assumption B(a) to (f) by Lemma 5.1.

Thanks to Lemmata 4.2 and 5.2, condition S(1) is satisfied with constants η and D replaced by η' , defined as above, and $D + D_{\mathcal{H}}(\varepsilon_0)\varepsilon_1^{\alpha}$ respectively, where D is the number given in Lemma 4.2.

Assumption T''(a), (d) and (c') imply Assumption T (a), (c) and (d) respectively. Assumption T(b) follows from the construction of the first return map. Lemma 4.2(iii) and 5.2(iii) give (1.5). Therefore all the conditions for Theorem B are satisfied; hence we obtain conditions S(3) and S(4).

The facts that $||R_n||_{\mathcal{B}} = O(d_n^{m/(m+\alpha)})$, and $||R_n||_{\mathcal{B}} = O(d_n)$ if Assumption T''(e') is satisfied, follow from Lemma 5.5: therefore we have established the decay of correlations (1.3).

If T also satisfies (4.4), then we know that for any z close to p, $|T_1^{-n}z|$ is of order $n^{-1/\gamma}$. Hence $\hat{\nu}\{\tau > k\}$ has the order $k^{-m/\gamma}$, and $\sum_{k=n+1}^{\infty} k^{-\frac{m}{\gamma}} = O(n^{-\frac{m}{\gamma}+1})$. Then the rest of the theorem is clear.

Lemma 5.1. \mathcal{B} is a Banach space satisfying Assumption B(a) to (f) with $C_a = 2C_b = 2\gamma_m^{-1}\varepsilon_0^{-m+\alpha}$, where γ_m is the volume of the unit ball in \mathbb{R}^m .

Proof. We already know that Q is a Banach space, and the proof of the completeness of \mathcal{B} follows from standard arguments.

Now we verify Assumption B(a) to (f).

By Lemma 4.1, the unit ball of \mathcal{Q} is compact in $L^1(\widehat{X}, \hat{\nu})$. Since $||f||_{\mathcal{B}} \geq ||f||_{\mathcal{Q}}$ for any $f \in \mathcal{B} \subset \mathcal{Q}$, the unit ball of \mathcal{B} is contained in the unit ball of \mathcal{Q} . Since \mathcal{B} is closed in \mathcal{Q} , the unit ball of \mathcal{B} is also compact. This is Assumption B(a).

Moreover, for any $f \in \mathcal{Q}$, $||f||_{\infty} \leq C_b ||f||_{\mathcal{Q}} \leq C_b ||f||_{\mathcal{B}}$ with $C_b = \gamma_m^{-1} \varepsilon_0^{-m+\alpha}$; we have thus got Assumption B(b).

By invoking again Lemma 4.1, we have, for any $f,g \in \mathcal{Q} : ||fg||_{\mathcal{Q}} \leq C_a ||f||_{\mathcal{Q}} ||g||_{\mathcal{Q}}$, where $C_a = 2\gamma_m^{-1}\varepsilon_0^{-m+\alpha} = 2C_b$. It is easy to check that

$$|fg|_{\mathcal{H}} \le ||f||_{\infty} |g|_{\mathcal{H}} + ||g||_{\infty} |f|_{\mathcal{H}} \le C_b ||f||_{\mathcal{Q}} |g|_{\mathcal{H}} + C_b ||g||_{\mathcal{Q}} |f|_{\mathcal{H}}.$$

Hence,

$$\|fg\|_{\mathcal{B}} = \|fg\|_{\mathcal{Q}} + |fg|_{\mathcal{H}} \le C_a \|f\|_{\mathcal{Q}} \|g\|_{\mathcal{Q}} + C_b \|f\|_{\mathcal{Q}} |g|_{\mathcal{H}} + C_b \|g\|_{\mathcal{Q}} |f|_{\mathcal{H}}$$
$$\le C_a (\|f\|_{\mathcal{Q}} + |f|_{\mathcal{H}}) (\|g\|_{\mathcal{Q}} + |g|_{\mathcal{H}}) = C_a \|f\|_{\mathcal{B}} \|g\|_{\mathcal{B}}.$$

Therefore Assumption B(c) follows with $C_a = 2\gamma_m^{-1}\varepsilon_0^{-m+\alpha} = 2C_b$.

Similarly, part (d) of Assumption B follows from the fact that \mathcal{B} contains all Hölder functions, which are in turn dense in $L^1(\hat{X}, \hat{\nu})$.

Assume $f(x) = \lim_{n \to \infty} f_n(x)$ for $\hat{\nu}$ -a.e. $x \in X$. By the proof of Lemma 4.1 we have $|f|_{\mathcal{Q}} \leq \liminf_{n \to \infty} |f_n|_{\mathcal{Q}}$; moreover for any $y, z \in V_I$, where $I \in \mathcal{I}$,

$$\frac{|f(y) - f(z)|}{d(y, z)^{\alpha}} \le \lim_{n \to \infty} \frac{|f_n(y) - f_n(z)|}{d(y, z)^{\alpha}} \le \liminf_{n \to \infty} |f_n|_{\mathcal{H}}.$$

Therefore $|f|_{\mathcal{H}} \leq \liminf_{n \to \infty} |f_n|_{\mathcal{H}}$; since $|f|_{\mathcal{B}} = |f|_{\mathcal{Q}} + |f|_{\mathcal{H}}$, we get part (e).

Since $\mathcal{B} \subset \mathcal{Q}$, part (f) follows directly from the fact that \mathcal{Q} satisfies Assumption B(f).

Lemma 5.2. Let ε_0 be as in Lemma 4.2. There exists $D_{\mathcal{H}} = D_{\mathcal{H}}(\varepsilon_0), \bar{D}_{\mathcal{H}} = \bar{D}_{\mathcal{H}}(\varepsilon_0) > 0$ and $\varepsilon_- \in (0, \varepsilon_0]$ such that for any $\varepsilon_1 \in (0, \varepsilon_-]$, and by using the notation for the Banach space introduced in (5.1):

- (i) for any $f \in \mathcal{B}^{\alpha}_{\varepsilon_{0},\varepsilon_{1}}, |\widehat{\mathscr{P}}f|_{\mathcal{H}_{\varepsilon_{1}}} \leq s^{\alpha}|f|_{\mathcal{H}_{\varepsilon_{1}}} + D_{\mathcal{H}}\varepsilon_{1}^{\alpha}||f||_{\mathcal{Q}_{\varepsilon_{0}}};$
- (ii) for any $f \in \mathcal{B}^{\alpha}_{\varepsilon_{0},\varepsilon_{1}}, |R(z)f|_{\mathcal{H}_{\varepsilon_{1}}} \leq |z| \left(s^{a} |f|_{\mathcal{H}_{\varepsilon_{1}}} + \bar{D}_{\mathcal{H}} \varepsilon_{1}^{\alpha} \|f\|_{\mathcal{Q}_{\varepsilon_{0}}} \right);$
- (iii) and for any $f \in \widetilde{\mathcal{B}}^{\alpha}_{\varepsilon_{0},\varepsilon_{1}} | \widetilde{\mathscr{P}}\widetilde{f}|_{\widetilde{\mathcal{H}}_{\varepsilon_{1}}} \leq s^{\alpha} |\widetilde{f}|_{\widetilde{\mathcal{H}}_{\varepsilon_{1}}} + D_{\mathcal{H}}\varepsilon_{1}^{\alpha} \|\widetilde{f}\|_{\widetilde{\mathcal{Q}}_{\varepsilon_{0}}}.$

Proof. (i) Let $\varepsilon_* \in (0, \varepsilon_0]$, $J_{\hat{h}} > 0$ as in the proof of Sublemma 5.4 below. Suppose $\varepsilon \in (0, \varepsilon_*]$, and $|f|_{\mathcal{H}_{\varepsilon_1}} = H$ for some f. Take $x, y \in V_I$ for some $I \in \mathcal{I}$ with $d(x, y) = \varepsilon \leq \varepsilon_*$. Then by Assumption T''(e), we can take $\zeta > 0$, $N = N(\varepsilon) > 0$ for b = 1. Notice that

$$\frac{\widehat{\mathscr{P}}f(x)}{\hat{h}(x)} - \frac{\widehat{\mathscr{P}}f(y)}{\hat{h}(y)} = \sum_{j=1}^{K} \sum_{i=1}^{\infty} \frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} \Big(\frac{f(x_{ij})}{\hat{h}(x_{ij})} - \frac{f(y_{ij})}{\hat{h}(y_{ij})}\Big) \\
+ \sum_{j=1}^{K} \sum_{i=1}^{N} \frac{f(y_{ij})}{\hat{h}(y_{ij})} \Big(\frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} - \frac{\hat{g}(y_{ij})\hat{h}(y_{ij})}{\hat{h}(y)}\Big) \\
+ \sum_{j=1}^{K} \sum_{i=N+1}^{\infty} \frac{f(y_{ij})}{\hat{h}(y_{ij})} \Big(\frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} - \frac{\hat{g}(y_{ij})\hat{h}(y_{ij})}{\hat{h}(y)}\Big).$$
(5.5)

Since $|f|_{\mathcal{H}} = H$, we have $|f(x_{ij})/\hat{h}(x_{ij}) - f(y_{ij})/\hat{h}(y_{ij})| \leq Hd(x_{ij}, y_{ij})^{\alpha} \leq s^{\alpha}Hd(x, y)^{\alpha}$. Now, $\widehat{\mathscr{P}}\hat{h} = \hat{h}$ implies

$$\sum_{j=1}^{K} \sum_{i=1}^{\infty} \hat{g}(x_{ij}) \hat{h}(x_{ij}) / \hat{h}(x) = 1.$$
(5.6)

Thus the first sum in (5.5) is bounded by $s^{\alpha}Hd(x,y)^{\alpha} \leq s^{\alpha}|f|_{\mathcal{H}}d(x,y)^{\alpha}$.

Note that by our assumption, V_I does not intersect discontinuities.[¶] By Sublemma 5.4, $\hat{h}(y)/\hat{h}(x) \leq e^{J_h d(x,y)^{\alpha}}$, and by Assumption T''(e), $\hat{g}(y)/\hat{g}(x) \leq e^{\zeta d(x,y)^{\alpha}}$ if $i \leq N(\varepsilon)$. So $[\hat{g}(y_{ij})\hat{h}(y_{ij})/\hat{h}(y)]/[\hat{g}(x_{ij})\hat{h}(x_{ij})/\hat{h}(x)] \leq e^{\zeta' d(x,y)^{\alpha}}$ for some $\zeta' > 0$. We take $\varepsilon_{-} \in (0, \varepsilon_*]$ small enough such that $e^{\zeta \varepsilon_1^{\alpha}} - 1 \leq 2\zeta' \varepsilon_1^{\alpha}$ for any $\varepsilon_1 \leq (0, \varepsilon_-]$. Then for $d(x, y) = \varepsilon \leq \varepsilon_1$, we have

$$\left|\frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} - \frac{\hat{g}(y_{ij})\hat{h}(y_{ij})}{\hat{h}(y)}\right| \le 2\zeta' \frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} \cdot d(x,y)^{\alpha}.$$
 (5.7)

Therefore by (5.6), the second sum in (5.5) is bounded by

$$\sum_{j=1}^{K} \sum_{i=1}^{N} \frac{f(y_{ij})}{\hat{h}(y_{ij})} \frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} \cdot 2\zeta' d(x,y)^{\alpha} \le 2\zeta' \hat{h}_{*}^{-1} \|f\|_{\infty} d(x,y)^{\alpha},$$

where \hat{h}_* is the essential lower bound of \hat{h} given by Sublemma 5.3.

By Assumption T''(e), the third sum in (5.5) is bounded by

$$\sum_{j=1}^{K} \sum_{i=N+1}^{\infty} \frac{f(y_{ij})}{\hat{h}(y_{ij})} \frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} \le \hat{h}_{*}^{-2} \|\hat{h}\|_{\infty} \|f\|_{\infty} \cdot K' b\varepsilon^{m+\alpha}$$
$$= \hat{h}_{*}^{-2} \|\hat{h}\|_{\infty} C_{b} \|f\|_{\mathcal{B}} \cdot K' b\varepsilon^{m} d(x, y)^{\alpha} = C_{b} K' b\varepsilon_{1}^{m} \hat{h}_{*}^{-2} \|\hat{h}\|_{\infty} \|f\|_{\mathcal{B}} d(x, y)^{\alpha}$$

where C_b is given in Lemma 4.1 which depends on ε_0 .

Hence the result of part (1) holds with $D_{\mathcal{H}} = C_b \hat{h}_*^{-1} (2\zeta' + K' b \varepsilon_1^m \hat{h}_*^{-1} \|\hat{h}\|_{\infty}).$

Part (ii) and (iii) can be proved by using the same estimates with the same adjustments as in the proof of Lemma 4.2. $\hfill \Box$

Sublemma 5.3. There is a $\hat{h}_* > 0$ such that $\hat{h}(x) \ge \hat{h}_*$ for ν -a.e. $x \in \widehat{X}$.

Proof. By Lemma 3.1 in [Ss], there is a ball $B_{\varepsilon}(z) \subset \widehat{X}$ such that $\operatorname{Einf}_{B_{\varepsilon}(x)} \hat{h} \geq \hat{h}_{-}$ for some constant $\hat{h}_{-} > 0$. By Assumption T''(c'), there is $\widetilde{N} > 0$ such that $T^{\widetilde{N}}B_{\varepsilon}(z) \supset X$. Then for any $x \in \widetilde{X}$, there is $y_0 \in B_{\varepsilon}(z)$ such that $T^{\widetilde{N}}y_0 = x$.

This implies that the potential \hat{g}_{ij} of the transfer operator is continuous. Such a potential has in fact the form $\hat{g}_{ij}(x) = |\det D\hat{T}_{ij}(x)|^{-1}$, where $\hat{T}_{ij} = T_1^i T_j$, being T_1 and T_j different determinations of the map T. In the computation of the transfer operator, \hat{g} is computed in the point $T_j^{-1}T_1^{-i}x$, where x belongs to the sets of Hölder continuity V_I which are in turn the preimages of V. The continuity of the potential is necessary to get the invariance of the new Banach space under the action of $\widehat{\mathscr{P}}$.

Since $|\det DT|$ is bounded above, we have $g_* := \inf\{g(y): y \in X\} > 0$. Hence, for $\hat{\nu}$ -almost every x,

$$\hat{h}(x) = (\mathscr{P}^{\widetilde{N}}\hat{h})(x) = \sum_{T^{\widetilde{N}}y=x} \hat{h}(y) \prod_{i=0}^{\widetilde{N}-1} g(T^{i}y) \ge \hat{h}(y_{0}) \prod_{i=0}^{\widetilde{N}-1} g(T^{i}y_{0}) \ge \hat{h}_{-}g_{*}^{\widetilde{N}}.$$

The result follows with $\hat{h}_* = \hat{h}_- g_*^{\widetilde{N}}$.

Sublemma 5.4. Let ε_0 be as in Lemma 4.2. Then there exists $J_{\hat{h}} > 0$ and $\varepsilon_* \in (0, \varepsilon_0]$ such that for any $x, y \in V_I$ with $d(x, y) \leq \varepsilon_*$, $I \in \mathcal{I}$,

$$\frac{\hat{h}(x)}{\hat{h}(y)} \le e^{J_{\hat{h}}d(x,y)^{\alpha}}$$

Proof. Since \hat{h} is the unique fixed point of $\widehat{\mathscr{P}}$, we know that $\hat{h} = \lim_{n \to \infty} \widehat{\mathscr{P}}^n 1_{\widehat{X}}$, where the convergence is in $L^1(\hat{\nu})$. Now we consider the sequence $f_n := \widehat{\mathscr{P}}^n 1_{\widehat{X}}$.

We will prove that there is $J_{\hat{h}} > 0$ and $\varepsilon_* \in (0, \varepsilon_0]$ such that for any $n \ge 0$ and for any $x, y \in V_I$, $I \in \mathcal{I}$, with $d(x, y) \le \varepsilon_*$,

$$\frac{f_n(y)}{f_n(x)} \le e^{J_{\hat{h}} d(x,y)^{\alpha}}.$$
(5.8)

Clearly (5.8) is true for n = 0 since $f_0(x) = 1$ for any x. We assume that it is true up to f_{n-1} ; we then consider f_n .

Note that $f_n/\hat{h} = (1/\hat{h})\widehat{\mathscr{P}}^n(h\cdot 1_{\widehat{X}}/\hat{h}) = \widehat{\mathcal{L}}^n(1_{\widehat{X}}/\hat{h})$, where $\widehat{\mathcal{L}}$ is the normalized transfer operator defined by $\widehat{\mathcal{L}}(f) = (1/\hat{h})\widehat{\mathscr{P}}(\hat{h}f)$. Then there are $f_* \ge \hat{h}_*/\hat{h}^*$ and $f^* \le \hat{h}^*/\hat{h}_*$ such that $f_* \le f_n(x) \le f^*$ for every $x \in \widehat{X}$ and $n \ge 0$, where \hat{h}^* and \hat{h}_* are the essential upper and lower bound of \hat{h} respectively. Let also set: $g_* = \inf_x f_1(x) = \inf_x \sum_{j=1}^K \sum_{i=0}^\infty \hat{g}(x_{ij})$.

Let us set again b = 1; then put $\zeta > 0$ as in Assumption T''(e). Let us take $J_{\hat{h}} > 2\zeta s^{\alpha}/(1-s^{\alpha})$ so that we have $(J_{\hat{h}}+\zeta)s^{\alpha} \leq J_{\hat{h}}(1+s^{\alpha})/2$. Then we choose $\varepsilon_* \in (0, \varepsilon_0]$ small enough such that for any $\varepsilon \in [0, \varepsilon_*]$,

$$e^{J_{\hat{h}}(1+s^{\alpha})\varepsilon^{\alpha}/2} + \frac{f^*K'b\varepsilon^{m+\alpha}}{f_*(g_*-K'b\varepsilon^{m+\alpha})} \leq e^{J_{\hat{h}}\varepsilon^{\alpha}}.$$

For any x, y in the same V_I with $d(x, y) =: \varepsilon \leq \varepsilon_*$, we choose $N = N(\varepsilon)$ as in Assumption T''(e). Let us denote with $[f_n]_N(x) = \sum_{j=1}^K \sum_{i=0}^N \hat{g}(x_{ij}) f_{n-1}(x_{ij})$ and $\{f_n\}_N(x) = f_n(x) - [f_n]_N(x) = \sum_{j=1}^K \sum_{i=N+1}^\infty \hat{g}(x_{ij}) f_{n-1}(x_{ij})$. We have

$$\begin{split} \frac{[f_n]_N(y)}{[f_n]_N(x)} &= \frac{\sum_{j=1}^K \sum_{i=0}^N \hat{g}(y_{ij}) f_{n-1}(y_{ij})}{\sum_{j=1}^K \sum_{i=0}^N \hat{g}(x_{ij}) f_{n-1}(x_{ij})} \\ &\leq \sup_{1 \leq j \leq K; 0 < i \leq N} e^{\zeta d(x_{ij}, y_{ij})^\alpha} e^{J_{\hat{h}} d(x_{ij}, y_{ij})^\alpha} \leq e^{(\zeta + J_{\hat{h}}) s^\alpha d(x, y)^\alpha} \leq e^{J_{\hat{h}}(1 + s^\alpha) \varepsilon^\alpha / 2}. \end{split}$$

We also get

$$\{f_n\}_N(y) = \sum_{j=1}^K \sum_{i=N+1}^\infty \hat{g}(y_{ij}) f_{n-1}(y_{ij}) \le f^* \sum_{j=1}^K \sum_{i=N+1}^\infty \hat{g}(y_{ij}) \le f^* K' b e^{m+\alpha}.$$

On the other hand,

$$[f_n]_N(x) = \sum_{j=1}^K \sum_{i=N+1}^\infty \hat{g}(y_{ij}) f_{n-1}(y_{ij}) \ge f_* \sum_{j=1}^K \sum_{i=1}^N \hat{g}(y_{ij}) \ge f_*(g_* - K'be^{m+\alpha}).$$

By the choice of ε_* , we obtain

$$\frac{f_n(y)}{f_n(x)} \leq \frac{[f_n]_N(y) + \{f_n\}_N(y)}{[f_n]_N(x)} \leq e^{J_{\hat{h}}(1+s^\alpha)\varepsilon^\alpha/2} + \frac{f^*K'b\varepsilon^{m+\alpha}}{f_*(g_* - K'b\varepsilon^{m+\alpha})} \leq e^{J_{\hat{h}}\varepsilon^\alpha}.$$

This implies (5.8) holds for n since we have set $\varepsilon = d(x, y)$.

Lemma 5.5. There exists a constant $C_R > 0$ such that $||R_n||_{\mathcal{B}} \leq C_R d_n^{m/(m+\alpha)}$ for all n > 0.

If, moreover, T satisfies Assumption T'(e'), then $||R_n||_{\mathcal{B}} \leq C_R d_n$ for all n > 0.

Proof. Since $R_i = \sum_j R_{ij}$, we only need to prove the results for R_{ij} .

Let $s_{ij}(x)$ be the norm of $||D\hat{T}_{ij}^{-1}(x)||$, and $s_{ij} = \max\{s_{i,j}(x) : x \in B_{\varepsilon_0}(Q_0)\}$. Note that $\{\tau > i\} \subset T^{-1}V$ for all large *i*. We may suppose that *i* is sufficiently large so that $B_{s_{ij}\varepsilon_1}(U_{ij}) \subset \hat{T}_{ij}^{-1}V$; we then take $f \in \mathcal{B}$ with $||f||_{\mathcal{B}} = 1$. By using (4.20) and (4.21), we apply arguments similar to (4.22) and get

$$||R_{ij}f||_1 = \int_{U_{ij}} |f| d\hat{\nu} \le ||f||_{\infty} \hat{\nu}(U_{ij}) \le C_b \hat{\nu}(Q_0) d_{ij} ||f||_{\mathcal{B}}.$$
 (5.9)

Next, we consider $|R_{ij}f|_{\mathcal{B}}$. Note that for any $I \in \mathcal{I}$, $f|_{V_I} \in \mathcal{H}^{\alpha}(V_I, H)$ for some $H \leq ||f||_{\mathcal{B}}$. So $\operatorname{osc}(f/\hat{h}, B_{s\varepsilon}(\cdot)) \leq 2^{\alpha}s^{\alpha}\varepsilon^{\alpha}H \leq 2^{\alpha}s^{\alpha}\varepsilon^{\alpha}||f||_{\mathcal{B}}$. Moreover Sublemma 5.4 implies that $\operatorname{osc}(\hat{h}, B_{\varepsilon}(x)) \leq 2^{\alpha} J_{\hat{h}}' \varepsilon^{\alpha}$ for all x with $B_{\varepsilon}(x) \in V_{I}$ and with $J_{\hat{h}}' \geq J_{\hat{h}} > 0$. By Proposition 3.2(3) in [Ss] we now have:

$$\operatorname{osc}(f, B_{s_{ij}\varepsilon}(\cdot)) \leq \operatorname{osc}(f/\hat{h}, B_{s_{ij}\varepsilon}(\cdot))\hat{h}_* + \operatorname{osc}(\hat{h}, B_{s_{ij}\varepsilon}(\cdot)) ||f||_{\infty}/\hat{h}_* \leq b_1 \varepsilon^{\alpha} ||f||_{\mathcal{B}},$$

where $b_1 = 2^{\alpha} (H \hat{h}_* + J'_{\hat{h}} C_b h_*^{-1}) s_{ij}^{\alpha}$. By arguments similar to (4.20) and (4.23),

$$\int R_{ij} \operatorname{osc}(f, \ B_{s_{ij}\varepsilon}(\cdot)) d\hat{\nu} = \int_{U_{ij}} \operatorname{osc}(f, \ B_{s_{ij}\varepsilon}(\cdot)) d\hat{\nu}$$

$$\leq b_1 \varepsilon^{\alpha} \|f\|_{\mathcal{B}} \hat{\nu}(U_{ij}) \leq b_1 \varepsilon^{\alpha} d_{ij} \hat{\nu}(Q_0) \|f\|_{\mathcal{B}} \leq a_1 \varepsilon^{\alpha} d_{ij} \|f\|_{\mathcal{B}},$$

(5.10)

where $a_1 = b_1 \nu(Q_0)$. Also,

$$\hat{\nu}\big(\widehat{T}_{ij}^{-1}B_{\varepsilon}(\partial\widehat{T}U_{ij})\big) = \int_{B_{\varepsilon}(\partial\widehat{T}U_{ij})} \hat{g}d\hat{\nu} \le d_{ij} \cdot \hat{\nu}\big(B_{\varepsilon}(\partial U_0)\big) \le d_{ij} \cdot b_2\varepsilon,$$

for some $b_2 > 0$ independent of ε . Hence,

$$G_{ij}(x,\varepsilon,\varepsilon_0) = 2d_{ij} \cdot b_2 \varepsilon / \hat{\nu}(B_{(1-s)\varepsilon_0}(x)) \le a_2 d_{ij}\varepsilon, \qquad (5.11)$$

where $a_2 = 2b_2/\hat{\nu}(B_{(1-s)\varepsilon_0}(x))$. Note that $\int \operatorname{osc}(f, B_{\varepsilon_0}(x_{ij}))d\hat{\nu} \leq \varepsilon_0^{\alpha}|f|_{\mathcal{Q}}$, and $\|f\|_1 + \varepsilon_0^{\alpha}|f|_{\mathcal{Q}} \leq \|f\|_{\mathcal{Q}} \leq \|f\|_{\mathcal{B}}$. Therefore for any $\varepsilon \in (0, \varepsilon_0]$ and $i < N(\varepsilon)$ and by using (4.15), (5.10), (5.9) and (5.11) we get

$$|R_{ij}f|_{\mathcal{Q}} \leq \left[(1+\zeta\varepsilon^{\alpha})a_1 + 2\zeta C_b\nu(Q_0) + 2(1+\zeta\varepsilon^{\alpha})a_2\varepsilon^{1-\alpha} \right] d_{ij} ||f||_{\mathcal{B}}$$

$$\leq C_2' d_{ij} ||f||_{\mathcal{B}},$$
(5.12)

where $C'_2 = (1 + \zeta \varepsilon^{\alpha})a_1 + 2\zeta C_b \nu(Q_0) + 2(1 + \zeta \varepsilon^{\alpha})a_2 \varepsilon^{1-\alpha}.$

For $\varepsilon \in (0, \varepsilon_0]$, $i > N(\varepsilon)$ and by Assumption T''(e) we have $d_{ij} \leq b\varepsilon^{m+\alpha}$. Hence, $\varepsilon^{-a} \leq (b^{-1}d_{ij})^{-\alpha/(m+\alpha)}$. Hence by (4.16), we have

$$|R_{ij}f|_{\mathcal{Q}} \leq 2(\gamma_m \varepsilon_0^m)^{-1} \cdot ||f||_{\mathcal{Q}} \cdot \varepsilon^{-\alpha} \cdot d_{ij}$$

$$\leq 2(\gamma_m \varepsilon_0^m)^{-1} b^{\alpha/(m+\alpha)} d_{ij}^{1-\alpha/(m+\alpha)} ||f||_{\mathcal{Q}} \leq C_2'' d_{ij}^{m/m+\alpha} ||f||_{\mathcal{B}},$$
(5.13)

where $C_2'' = 2(\gamma_m \varepsilon_0^m)^{-1} b^{\alpha/(m+\alpha)}$. Therefore we get that $|R_{ij}f|_{\mathcal{Q}} \leq C_2 d_i^{m/m+\alpha}$, where $C_2 = \max\{C_2', C_2''\}$.

Now we consider $|R_{ij}f|_{\mathcal{H}}$. As in the proof of Lemma 5.2, for any $x, y \in U_{ij}$,

$$\left|\frac{R_{ij}f(x)}{\hat{h}(x)} - \frac{R_{ij}f(y)}{\hat{h}(y)}\right| \leq \left|\frac{\hat{g}(x_{ij})f(x_{ij})}{\hat{h}(x)} - \frac{\hat{g}(y_{ij})f(y_{ij})}{\hat{h}(y)}\right| \\
= \frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} \left|\frac{f(x_{ij})}{\hat{h}(x_{ij})} - \frac{f(y_{ij})}{\hat{h}(y_{ij})}\right| \\
+ \frac{|f(y_{ij})|}{\hat{h}(y_{ij})} \left|\frac{\hat{g}(x_{ij})\hat{h}(x_{ij})}{\hat{h}(x)} - \frac{\hat{g}(y_{ij})\hat{h}(y_{ij})}{\hat{h}(y)}\right|.$$
(5.14)

Note that $\left|f(x_{ij})/\hat{h}(x_{ij}) - f(y_{ij})/\hat{h}(y_{ij})\right| \leq |f|_{\mathcal{H}} d(x_{ij}, y_{ij})^{\alpha} \leq ||f||_{\mathcal{B}} s_{ij}^{\alpha} d(x, y)^{\alpha}$ and $\hat{g}(x_{ij})\hat{h}(x_{ij})/\hat{h}(x) \leq (\hat{h}^*/\hat{h}_*)d_{ij}$. Then the first term in the right hand side of (5.14) is bounded by $a_3 d_{ij} ||f||_{\mathcal{B}} d(x, y)^{\alpha}$, where $a_3 = (\hat{h}^*/\hat{h}_*)s_{ij}^{\alpha}$.

Let us take $\varepsilon = d(x, y)$; if $i \leq N(\varepsilon)$, then by (5.7),

$$|\hat{g}(x_{ij})\hat{h}(x_{ij})/\hat{h}(x) - \hat{g}(y_{ij})\hat{h}(y_{ij})/\hat{h}(y)| \le 2\zeta'(\hat{h}^*/\hat{h}_*)d_{ij}d(x,y)^{\alpha}.$$

^{||}The estimate (5.10) shows the difference with the analogous bound (4.23) and justifies the introduction of the new Banach space. In fact we can now use the local Hölder property for f to get an upper bound of the integral of the oscillation simultaneously in terms of the volume of U_{ij} , of ϵ and of the norm of f. The change of variable sending U_{ij} to Q_0 , will finally produce the determinant d_{ij} which will give a better upper bound for $||R_n||$.

Since $f(y_{ij})/\hat{h}(y_{ij}) \leq ||f||_{\infty}/\hat{h}_* \leq C_b \hat{h}_*^{-1} ||f||_{\mathcal{B}}$, the last term in (5.14) is bounded by $a_4 d_{ij} ||f||_{\mathcal{B}} d(x, y)^{\alpha}$, where $a_4 = 2C_b J'(\hat{h}^*/\hat{h}_*^2)$. Therefore we obtain $|R_{ij}f|_{\mathcal{H}} \leq C'_3 d_{ij} ||f||_{\mathcal{B}}$, where $C'_3 = b_1 + b_2$.

If $i \geq N(\varepsilon)$, then by the first inequality of (5.14), the left side of the inequality is bounded by $\max\{\hat{g}(x_{ij})f(x_{ij})/\hat{h}(x), \hat{g}(y_{ij})\hat{h}(y_{ij})/\hat{h}(y)\} \leq d_{ij}||f||_{\infty}/\hat{h}_{*}$. By the same arguments as for (5.13) we get that

$$|R_{ij}f|_{\mathcal{H}} \le \varepsilon^{-\alpha} d_{ij} ||f||_{\infty} / \hat{h}_* \le C_b \hat{h}_*^{-1} b^{\alpha/(m+\alpha)} d_{ij}^{m/(m+\alpha)} ||f||_{\mathcal{B}} = C_3'' d_{ij}^{m/(m+\alpha)} ||f||_{\mathcal{B}},$$

where $C_{3}'' = C_{b} \hat{h}_{*}^{-1} b^{\alpha/(m+\alpha)} ||f||_{\mathcal{B}}$. Then we conclude that $|R_{ij}f|_{\mathcal{H}} \leq C_{3} d_{ij}^{m/(m+\alpha)} ||f||_{\mathcal{B}}$, where $C_{3} = \max\{C_{3}', C_{3}''\}$.

The conclusion of the first part follows by setting $C_R = C_1 + C_2 + C_3$.

If T satisfies Assumption T''(e'), then we can regard $N(\varepsilon) = \infty$ for any $\varepsilon > 0$. Hence we obtain $||R_{ij}f||_{\mathcal{B}} \leq C_R d_{ij}||f||_{\mathcal{B}}$ with $C_R = C_1 + C_2 + C'_3$. \Box

Acknowledgments

We wish to thank Ian Melbourne for his interest in our maps, for his helpful comments and advices.

We would like to thank also Romain Aimino who was trapped in interminable discussions on aperiodicity and function spaces.

We finally thank the anonymous referee for a very careful reading of the paper and whose comments and suggestions helped us to improve our article.

References

- [AD] J. Aaronson and M. Denker, Local limit theorems for partial sums of stationary sequences generated by Gibbs-Markov maps, Stoch. & Dynam., 1 (2001), 193–237
- [ADSZ] J. Aaronson, M. Denker, O. Sarig and R. Zweimüller, Aperiodicity of cocycles and conditional local limit theorems, *Stoch. & Dynam.*, 4 (2004), 31–62
- [BG] A. Boyarsky and P. Góra, Laws of Chaos : Invariant Measures and Dynamical Systems in One Dimension, Probability and its Applications, Birkhauser, 1997
- [Bo] R. Bowen Equilibrium states and the ergodic theory of Anosov diffeomorphisms, Lecture Notes in Math. 470, Springer, New York, 1975
- [Br] A. Broise, Transformations dilatantes de l'intervalle et théorèmes limites, 5-110, Astérisque, 238 (1996)

- [Go] S. Gouëzel, Sharp polynomial estimates for the decay of correlations, Israel J. Math., 139 (2004), 29–65
- [He] H. Hennion, Sur un théorème spectral et son application aux noyaux lipchitziens, *Proc. Amer. Math. Soc.*, **118** (1993), 627–634
- [HH] H. Hennion and L. Hervé, Limit theorems for Markov chains and Stochastic Properties of Dynamical Systems by Quasicompactness, Lect. Notes Math., 1766, Springer-Verlag, 2001
- [Hu] H. Hu, Decay of correlations for piecewise smooth maps with indifferent fixed points, *Ergodic Theory Dynam. Systems*, 24 (2004), 495–524
- [HPT] H. Hu, Ya. Pesin and A. Talitskaya, A Volume Preserving Diffeomorphism with Essential Coexistence of Zero and Nonzero Lyapunov Exponents Comm. Math. Phys. 319 (2013), 331–378
- [HV] H. Hu and S. Vaienti, Absolutely Continuous Invariant Measures for Nonuniformly Expanding Maps, Ergodic Theory Dynam. Systems, 29 (2009), 1185–1215
- [IM] C.T. Ionescu Tulcea and G. Marinescu, Théorie ergodique pour des classes d'opérations non complètement continues (French), Ann. of Math., 52 (1950), 140–147
- [Kk] S. Kakutani, Induced measure preserving transformations, Proc. Imp. Acad. Tokyo, 19 (1943), 635–641
- [Kr] U. Krengel, Ergodic theorems, de Gruyter Studies in Mathematics, 6. Walter de Gruyter & Co., Berlin, 1985.
- [LY] A. Lasota and J. Yorke, On the existence of invariant measures for piecewise monotonic transformations, *Trans. Amer. Math. Soc.*, 186, (1973) 481–488
- [LSV] C. Liverani, B.Saussol and S. Vaienti, A probabilistic approach to intermittency, Ergodic Theory Dynam. Systems, 19 (1999), 671–685
- [MT] I. Melbourne, D. Terhesiu, Decay of correlations for nonuniformly expanding systems with general return times, *Ergodic Theory Dyn. Syst.*, 34, (2014) 893-918
- [PP] W. Parry and M Pollicott, Zeta functions and the periodic orbit structure of hyperbolic dynamics, Astérisque, 187-188 (1990)
- [PY] M. Pollicott and M. Yuri, Statistical Properties of maps with indifferent periodic points, Comm. Math. Phys., 217 (2001), 503–520

- [Qu] A. Quas, Non-ergodicity for C¹ expanding maps and g-measures (English summary), Ergodic Theory Dynam. Systems, 16 (1996), 531–543
- [Sr] O. Sarig, Subexponential decay of correlations, Invent. Math., 150 (2002), 629–653
- [Ss] B. Saussol, Absolutely continuous invariant measures for multidimensional expanding maps, Israel J. Math., 116 (2000), 223–248
- [Ya] J.-A. Yan, A Simple Proof of Two Generalized Borel-Cantelli Lemmas in Lecture Notes in Mathematics, 1874, Springer-Verlag, 2006, 77–79
- [Yo2] L.-S. Young, Recurrence times and rates of mixing, Israel J. Math., 110 (1999), 153–188
- [Zm] W. Zeimer, Weakly Differentiable Functions, Graduate Text in Mathematics, 120, Springer (1995)
- [Z1] R. Zweimüller, Ergodic structure and invariant densities of non-Markovian interval maps with indifferent fixed points, *Nonlinearity*, 11 (1998), 1263–1276
- [Z2] R. Zweimüller, Ergodic properties of infinite measure-preserving interval maps with indifferent fixed points, *Ergodic Theory Dynam. Systems*, 20 (2000), 1519–1549