



Hot Topics in General Relativity and Gravitation

EQUATIONS OF MOTION OF COMPACT BINARIES at THE FOURTH POST-NEWTONIAN ORDER

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Summary of known PN orders

| Method | Equations of motion | Energy flux | Waveform |
|--|---------------------|-----------------------------|----------------|
| Multipolar-post-Minkowskian & post-Newtonian | 4PN non-spin | 3.5PN non-spin ¹ | 3.5PN non-spin |
| (MPM-PN) | 3.5PN (NNL) SO | 4PN (NNL) SO | 1.5PN (L) SO |
| | 3PN (NL) SS | 3PN (NL) SS | 2PN (L) SS |
| | 3.5PN (NL) SSS | 3.5PN (NL) SSS | |
| Canonical ADM Hamiltonian | 4PN non-spin | | |
| | 3.5PN (NNL) SO | | |
| | 4PN (NNL) SS | | |
| | 3.5PN (NL) SSS | | |
| Effective Field Theory (EFT) | 3PN non-spin | 2PN non-spin | |
| | 2.5PN (NL) SO | | |
| | 4PN (NNL) SS | 3PN (NL) SS | |
| Direct Integration of Relaxed Equations (DIRE) | 2.5PN non-spin | 2PN non-spin | 2PN non-spin |
| | 1.5PN (L) SO | 1.5PN (L) SO | 1.5PN (L) SO |
| | 2PN (L) SS | 2PN (L) SS | 2PN (L) SS |
| Surface Integral | 3PN non-spin | | |

Many works devoted to spins:

- Spin effects (SO, SS, SSS) are known in EOM up to 4PN order
- SO effects are known in radiation field up to 4PN
- SS in radiation field known to 3PN

¹The 4.5PN coefficient is also known

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THE 4PN EQUATIONS OF MOTION

Based on collaborations with

Laura Bernard, Alejandro Bohé, Guillaume Faye & Sylvain Marsat

[PRD 93, 084037 (2016); PRD 95, 044026 (2017); PRD submitted (2017)]

Tanguy Marchand, Laura Bernard & Guillaume Faye

[PRL submitted (2017)]

The 4PN equations of motion

The 1PN equations of motion

[Lorentz & Droste 1917; Einstein, Infeld & Hoffmann 1938]



$$\begin{aligned} \frac{\mathrm{d}^{2} \boldsymbol{r}_{A}}{\mathrm{d}t^{2}} &= -\sum_{B \neq A} \frac{Gm_{B}}{r_{AB}^{2}} \boldsymbol{n}_{AB} \left[1 - 4\sum_{C \neq A} \frac{Gm_{C}}{c^{2}r_{AC}} - \sum_{D \neq B} \frac{Gm_{D}}{c^{2}r_{BD}} \left(1 - \frac{\boldsymbol{r}_{AB} \cdot \boldsymbol{r}_{BD}}{r_{BD}^{2}} \right) \right. \\ &+ \frac{1}{c^{2}} \left(\boldsymbol{v}_{A}^{2} + 2\boldsymbol{v}_{B}^{2} - 4\boldsymbol{v}_{A} \cdot \boldsymbol{v}_{B} - \frac{3}{2} (\boldsymbol{v}_{B} \cdot \boldsymbol{n}_{AB})^{2} \right) \right] \\ &+ \sum_{B \neq A} \frac{Gm_{B}}{c^{2}r_{AB}^{2}} \boldsymbol{v}_{AB} [\boldsymbol{n}_{AB} \cdot (3\boldsymbol{v}_{B} - 4\boldsymbol{v}_{A})] - \frac{7}{2} \sum_{B \neq A} \sum_{D \neq B} \frac{G^{2}m_{B}m_{D}}{c^{2}r_{AB}r_{BD}^{3}} \boldsymbol{n}_{BD} \end{aligned}$$

4PN: state-of-the-art on equations of motion



[Otha, Okamura, Kimura & Hiida 1973, 1974; Damour & Schäfer 1985]ADM[Damour & Deruelle 1981; Damour 1983]Harm[Kopeikin 1985; Grishchuk & Kopeikin 1986]Exter[Blanchet, Faye & Ponsot 1998]Direct[Itoh, Futamase & Asada 2001]Surfation

ADM Hamiltonian Harmonic coordinates Extended fluid balls Direct PN iteration Surface integral method

 $2\mathsf{PN}$

4PN: state-of-the-art on equations of motion



[Jaranowski & Schäfer 2013; Damour, Jaranowski & Schäfer 2014]
[Bernard, Blanchet, Bohé, Faye, Marchand & Marsat 2015, 2016, 2017ab]
[Foffa & Sturani 2012, 2013] (partial results)

Harmonic EOM Surface integral method Effective field theory ADM Hamiltonian Fokker Lagrangian Effective field theory

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4PN equations of motion

Fokker action of N particles [Fokker 1929]

 $\textcircled{\ } \textbf{Gauge-fixed Einstein-Hilbert action for } N \text{ point particles}$

$$\begin{split} S_{\rm g.f.} &= \frac{c^3}{16\pi G} \int \mathrm{d}^4 x \, \sqrt{-g} \Big[R \underbrace{-\frac{1}{2} g_{\mu\nu} \Gamma^{\mu} \Gamma^{\nu}}_{\text{Gauge-fixing term}} \Big] \\ &- \sum_A \underbrace{m_A c^2 \int \mathrm{d} t \, \sqrt{-(g_{\mu\nu})_A \, v_A^{\mu} v_A^{\nu}/c^2}}_{N \text{ point particles}} \end{split}$$



Fokker action is obtained by inserting an explicit PN solution of the Einstein field equations

$$g_{\mu\nu}(\mathbf{x},t) \longrightarrow \overline{g}_{\mu\nu}(\mathbf{x}; \boldsymbol{y}_B(t), \boldsymbol{v}_B(t), \cdots)$$

③ The PN equations of motion of the N particles (self-gravitating system) are

$$\frac{\delta S_{\mathsf{F}}}{\delta \boldsymbol{y}_{A}} \equiv \frac{\partial L_{\mathsf{F}}}{\partial \boldsymbol{y}_{A}} - \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\partial L_{\mathsf{F}}}{\partial \boldsymbol{v}_{A}}\right) + \dots = 0$$

The 4PN equations of motion

Problem of point particles and UV divergences



- For extended bodies the self-acceleration of the body cancels out by Newton's action-reaction law
- For point particles one needs a self-field regularization to remove the infinite self-field of the particle

Dimensional regularization for UV divergences

[t'Hooft & Veltman 1972; Bollini & Giambiagi 1972; Breitenlohner & Maison 1977]

• Einstein's field equations are solved in d spatial dimensions (with $d \in \mathbb{C}$) with distributional sources. In Newtonian approximation

$$\Delta U = -4\pi \frac{2(d-2)}{d-1} G\rho$$

② For two point-particles $\rho = m_1 \delta_{(d)}(\mathbf{x} - \mathbf{y}_1) + m_2 \delta_{(d)}(\mathbf{x} - \mathbf{y}_2)$ we get

$$U(\mathbf{x},t) = \frac{2(d-2)k}{d-1} \left(\frac{Gm_1}{|\mathbf{x} - \mathbf{y}_1|^{d-2}} + \frac{Gm_2}{|\mathbf{x} - \mathbf{y}_2|^{d-2}} \right) \quad \text{with} \quad k = \frac{\Gamma\left(\frac{d-2}{2}\right)}{\pi^{\frac{d-2}{2}}}$$

- Omputations are performed when ℜ(d) is a large negative number, and the result is analytically continued for any d ∈ C except for isolated poles
- Dimensional regularization is then followed by a renormalization of the worldline of the particles so as to absorb the poles $\propto (d-3)^{-1}$

Fokker action in the PN approximation

We face the problem of the near-zone limitation of the PN expansion

• Lemma 1: The Fokker action can be split into a PN (near-zone) term plus a contribution involving the multipole (far-zone) expansion

$$S_{\mathsf{F}}^{g} = \underset{B=0}{\operatorname{FP}} \int \mathrm{d}^{4}x \left(\frac{r}{r_{0}}\right)^{B} \overline{\mathcal{L}}_{g} + \underset{B=0}{\operatorname{FP}} \int \mathrm{d}^{4}x \left(\frac{r}{r_{0}}\right)^{B} \mathcal{M}(\mathcal{L}_{g})$$

• Lemma 2: The multipole contribution is zero for any "instantaneous" term thus only "hereditary" terms contribute to this term and they appear at least at 5.5PN order

$$S_{\mathsf{F}}^g = \mathop{\mathrm{FP}}_{B=0} \int \mathrm{d}^4 x \left(\frac{r}{r_0}\right)^B \overline{\mathcal{L}}_g$$

- The constant r_0 will play the role of an IR cut-off scale
- IR divergences appear at the 4PN order

Gravitational wave tail effect at the 4PN order

[Blanchet & Damour 1988; Blanchet 1993, 1996]

- At the 4PN order there is an imprint of gravitational wave tails in the local (near-zone) dynamics of the source
- This leads to a non-local-in-time contribution in the Fokker action
- This corresponds to a 1.5PN modification of the radiation field beyond the quadrupole approximation (already tested by LIGO)



matter source

$$S_{\rm F}^{\rm tail} = \frac{G^2 M}{5c^8} \underset{s_0}{\Pr} \iint \frac{{\rm d}t {\rm d}t'}{|t-t'|} \, I_{ij}^{(3)}(t) \, I_{ij}^{(3)}(t')$$

where the Hadamard partie finie (Pf) is parametrized by an arbitrary constant s_0

Problem of the IR ambiguity parameter

- Using dimensional regularization one can properly regularize the UV divergences and renormalize the UV poles
- Interval the second terms of terms
 - r_0 the IR cut-off scale in the Einstein-Hilbert part of the action
 - s_0 the Hadamard regularization scale coming from the tail effect
- Modulo unphysical shifts these combine into a single parameter

$$\alpha = \ln\left(\frac{r_0}{s_0}\right)$$

which is left undetermined at this stage

- This parameter is equivalent to the constant C in the 4PN ADM Hamiltonian formalism [Damour, Jaranowski & Schäfer 2014]
- It is fixed by computing the conserved energy of circular orbits and comparing with gravitational self-force (GSF) results

Conserved energy for a non-local Hamiltonian

Because of the tail effect at 4PN order the Lagrangian or Hamiltonian becomes non-local in time

$$H\left[\mathbf{x},\mathbf{p}\right] = H_0\left(\mathbf{x},\mathbf{p}\right) + \underbrace{H_{\mathsf{tail}}\left[\mathbf{x},\mathbf{p}\right]}_{\mathsf{non-local piece at 4PN}}$$

Hamilton's equations involve functional derivatives

$$\frac{\mathrm{d}x^{i}}{\mathrm{d}t} = \frac{\delta H}{\delta p_{i}} \qquad \frac{\mathrm{d}p_{i}}{\mathrm{d}t} = -\frac{\delta H}{\delta x^{i}}$$

• The conserved energy is not given by the Hamiltonian on-shell but $E = H + \Delta H^{AC} + \Delta H^{DC}$ where the AC term averages to zero and

$$\boxed{\Delta H^{\rm DC} = -\frac{2GM}{c^3} \mathcal{F}^{\rm GW} = -\frac{2G^2M}{5c^5} \langle \left(I^{(3)}_{ij}\right)^2 \rangle}$$

On the other hand [DJS] perform a non-local shift to transform the Hamiltonian into a local one, and both procedure are equivalent

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Conserved energy for circular orbits at 4PN order

- The 4PN energy for circular orbits in the small mass ratio limit is known from GSF of the redshift variable [Le Tiec, Blanchet & Whiting 2012; Bini & Damour 2013]
- This permits to fix the ambiguity parameter α and to complete the 4PN equations of motion

$$\begin{split} E^{4\text{PN}} &= -\frac{\mu c^2 x}{2} \bigg\{ 1 + \left(-\frac{3}{4} - \frac{\nu}{12} \right) x + \left(-\frac{27}{8} + \frac{19}{8}\nu - \frac{\nu^2}{24} \right) x^2 \\ &+ \left(-\frac{675}{64} + \left[\frac{34445}{576} - \frac{205}{96}\pi^2 \right] \nu - \frac{155}{96}\nu^2 - \frac{35}{5184}\nu^3 \right) x^3 \\ &+ \left(-\frac{3969}{128} + \left[-\frac{123671}{5760} + \frac{9037}{1536}\pi^2 + \frac{896}{15}\gamma_{\text{E}} + \frac{448}{15}\ln(16x) \right] \nu \\ &+ \left[-\frac{498449}{3456} + \frac{3157}{576}\pi^2 \right] \nu^2 + \frac{301}{1728}\nu^3 + \frac{77}{31104}\nu^4 \right) x^4 \bigg\} \end{split}$$

Periastron advance for circular orbits at 4PN order

The periastron advanced (or relativistic precession) constitutes a second invariant which is also known in the limit of circular orbits from GSF calculations

$$\begin{split} K^{4\mathsf{PN}} &= 1 + 3x + \left(\frac{27}{2} - 7\nu\right)x^2 \\ &+ \left(\frac{135}{2} + \left[-\frac{649}{4} + \frac{123}{32}\pi^2\right]\nu + 7\nu^2\right)x^3 \\ &+ \left(\frac{2835}{8} + \left[-\frac{275941}{360} + \frac{48007}{3072}\pi^2 - \frac{1256}{15}\ln x\right. \\ &- \frac{592}{15}\ln 2 - \frac{1458}{5}\ln 3 - \frac{2512}{15}\gamma_{\mathsf{E}}\right]\nu \\ &+ \left[\frac{5861}{12} - \frac{451}{32}\pi^2\right]\nu^2 - \frac{98}{27}\nu^3\right)x^4 \end{split}$$

Problem of the second ambiguity parameter

- The initial calculation of the Fokker action was based on the Hadamard regularization (HR) to treat the IR divergences (FP procedure when $B \rightarrow 0$)
- Computing the periastron advance for circular orbits it did not agree with GSF calculations (offending coefficient $-\frac{275941}{360}$)
- We found that the problem was due to the HR and conjectured that a different IR regularization would give (modulo shifts)

$$L = L^{\text{HR}} + \underbrace{\frac{G^4 m \, m_1^2 m_2^2}{c^8 r_{12}^4} \left(\delta_1 (n_{12} v_{12})^2 + \delta_2 v_{12}^2 \right)}_{\text{two ambiguity parameters } \delta_1 \text{ and } \delta_2}$$

- One combination of the two parameters δ_1 and δ_2 is equivalent to the previous ambiguity parameter α
- Matching with GSF results for the energy and periastron we have

$$\delta_1 = -\frac{2179}{315} \qquad \delta_2 = \frac{192}{35}$$

Dimensional regularization of the IR divergences

• The Hadamard regularization of IR divergences reads

$$I_{\mathcal{R}}^{\mathsf{HR}} = \mathop{\mathrm{FP}}_{B=0} \int_{r > \mathcal{R}} \mathrm{d}^{3} \mathbf{x} \left(\frac{r}{r_{0}}\right)^{B} F(\mathbf{x})$$

• The corresponding dimensional regularization reads

$$I_{\mathcal{R}}^{\mathsf{DR}} = \int_{r > \mathcal{R}} \frac{\mathrm{d}^{d} \mathbf{x}}{\ell_{0}^{d-3}} F^{(d)}(\mathbf{x})$$

• The difference between the two regularization is of the type $(\varepsilon = d - 3)$

$$\mathcal{D}I = \sum_{q} \left[\underbrace{\frac{1}{(q-1)\varepsilon}}_{\text{IR pole}} - \ln\left(\frac{r_0}{\ell_0}\right) \right] \int d\Omega_{2+\varepsilon} \, \varphi_{3,q}^{(\varepsilon)}(\mathbf{n}) + \mathcal{O}\left(\varepsilon\right)$$

Computing the tail effect in d dimensions

• The 4PN tail terms arises from the solution of the matching equation

$$\overline{\mathcal{M}(h^{\mu\nu})} = \mathcal{M}(\overline{h}^{\mu\nu})$$

The PN-expanded field in the near zone reads [PB 2002, BFN 2005]

$$\overline{h}^{\mu\nu} = \frac{16\pi G}{c^4} \overline{\Box}_{\mathsf{ret}}^{-1} \left[r^{\eta} \, \overline{\tau}^{\mu\nu} \right] + \mathcal{H}^{\mu\nu}$$

In the first term is a particular retarded solution of the PN expanded EFE

$$\overline{\Box_{\mathsf{ret}}^{-1}} \left[\boldsymbol{r}^{\boldsymbol{\eta}} \, \overline{\tau}^{\mu\nu} \right] = -\frac{\tilde{k}}{4\pi} \int \mathrm{d}^{d} \mathbf{x}' \, |\mathbf{x}'|^{\boldsymbol{\eta}} \overline{\int_{1}^{+\infty} \mathrm{d}z \, \gamma_{\frac{1-d}{2}}(z)} \, \frac{\overline{\tau}^{\mu\nu}(\mathbf{x}', t-z|\mathbf{x}-\mathbf{x}'|/c)}{|\mathbf{x}-\mathbf{x}'|^{d-2}}$$

with $\gamma_{\frac{1-d}{2}}(z)$ associated to the Green's function of the wave equation

• We employ a specific generalization of dimensional regularization where a regulator r^{η} is inserted in all formulas and called it the " $\varepsilon \eta$ " regularization

Computing the tail effect in d dimensions

• The tail effect comes from the second term of the PN solution which is a specific homogeneous solution of the wave equation regular when $r \to 0$

$$\mathcal{H}^{\mu\nu}(\mathbf{x},t) = \sum_{\ell=0}^{+\infty} \sum_{j=0}^{+\infty} \frac{1}{c^{2j}} \, \Delta^{-j} \hat{x}_L \, f_L^{(2j)\mu\nu}(t)$$

where

$$f_L^{\mu\nu}(t) = \frac{(-)^{\ell+1}\tilde{k}}{4\pi\ell!} \int_1^{+\infty} \mathrm{d}z \,\gamma_{\frac{1-d}{2}}(z) \int \mathrm{d}^d \mathbf{x}' \,|\mathbf{x}'|^\eta \,\hat{\partial}'_L \bigg[\frac{\mathcal{M}(\Lambda^{\mu\nu})(\mathbf{y}, t - zr'/c)}{r'^{d-2}} \bigg]_{\mathbf{y}=\mathbf{x}'}$$

In practice the multipole expansion is computed by the MPM algorithm hence

$$\mathcal{M}(h^{\mu\nu}) = h^{\mu\nu}_{\mathsf{MPM}} = \sum_{n=0}^{+\infty} G^n h^{\mu\nu}_n$$

and for the tail effect we must look at the interaction between the static mass monopole M and the varying mass quadrupole $I_{ij}(t)$

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Computing the tail effect in d dimensions

In a particular gauge the 4PN tail effect is entirely described by a single scalar potential in the 00 component of the metric

$$g_{00}^{\text{tail}} = -\frac{8G^2M}{5c^8} x^{ij} \int_0^{+\infty} \mathrm{d}\tau \left[\ln\left(\frac{c\sqrt{\bar{q}}\,\tau}{2\ell_0}\right) \underbrace{-\frac{1}{2\varepsilon}}_{\text{UV pole}} + \frac{41}{60} \right] I_{ij}^{(7)}(t-\tau) + \mathcal{O}\left(\frac{1}{c^{10}}\right)$$

In the conservative part of the 4PN tail effect corresponds in the action

$$S_g^{\text{tail}} = \frac{G^2 M}{5c^8} \Pr_{s_0^{\text{DR}}} \iint \frac{\mathrm{d}t \mathrm{d}t'}{|t-t'|} I_{ij}^{(3)}(t) I_{ij}^{(3)}(t')$$

with
$$\ln s_0^{\mathsf{DR}} = \ln \left(\frac{2\ell_0}{c\sqrt{\bar{q}}} \right) + \frac{1}{2\varepsilon} - \frac{41}{60}$$

The result is in full agreement with [Galley, Leibovich, Porto & Ross 2016] how computed the tail effects as a Feynman diagram within the EFT

Ambiguity-free completion of the 4PN EOM

- The tail effect contains a UV pole which cancels the IR pole coming from the instantaneous part of the action (the cancellation is also expected to occur in the EFT [Porto & Rothstein 2017])
- ⁽²⁾ Adding up all contributions the constants r_0 , s_0 and ℓ_0 cancel out as well and we obtain the conjectured form of the ambiguity terms with the correct values

$$\delta_1 = -\frac{2179}{315} \qquad \delta_2 = \frac{192}{35}$$

- This constitutes the first complete (i.e., ambiguity-free) derivation of the equations of motion at the 4PN order
- It is likely that the EFT formalism will also succeed in deriving the full EOM without ambiguities
- It seems that the lack of a consistent matching in the ADM Hamiltonian formalism [DJS] forces this formalism to be still plagued by one ambiguity parameter